

Generalized Low Rank Models

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Data table

age	gender	state	diabetes	education	...
22	F	CT	?	college	...
57	?	NY	severe	high school	...
?	M	CA	moderate	masters	...
41	F	NV	none	?	...
⋮	⋮	⋮	⋮	⋮	

- ▶ detect demographic groups?
- ▶ find typical responses?
- ▶ identify related features?
- ▶ impute missing entries?

Low rank model

given: A , $k \ll m, n$

find: $X \in \mathbf{R}^{m \times k}$, $Y \in \mathbf{R}^{k \times n}$ for which

$$\begin{bmatrix} X \\ \end{bmatrix} \begin{bmatrix} Y \\ \end{bmatrix} \approx \begin{bmatrix} A \\ \end{bmatrix}$$

i.e., $x_i y_j \approx A_{ij}$, where

$$\begin{bmatrix} X \\ \end{bmatrix} = \begin{bmatrix} -x_1- \\ \vdots \\ -x_m- \\ \end{bmatrix} \quad \begin{bmatrix} Y \\ \end{bmatrix} = \begin{bmatrix} | & & | \\ y_1 & \cdots & y_n \\ | & & | \\ \end{bmatrix}$$

interpretation:

- ▶ X and Y are (compressed) representation of A
- ▶ $x_i^T \in \mathbf{R}^k$ is a point associated with example i
- ▶ $y_j \in \mathbf{R}^k$ is a point associated with feature j
- ▶ inner product $x_i y_j$ approximates A_{ij}

Why use a low rank model?

- ▶ reduce storage; speed transmission
- ▶ understand (visualize, cluster)
- ▶ remove noise
- ▶ infer missing data
- ▶ simplify data processing

Principal components analysis

PCA:

$$\text{minimize } \|A - XY\|_F^2 = \sum_{i=1}^m \sum_{j=1}^n (A_{ij} - x_i y_j)^2$$

with variables $X \in \mathbf{R}^{m \times k}$, $Y \in \mathbf{R}^{k \times n}$

- ▶ old roots [Pearson 1901, Hotelling 1933]
- ▶ least squares low rank fitting
- ▶ (analytical) solution via SVD of $A = U\Sigma V^T$:

$$X = U_k \Sigma_k^{1/2} \quad Y = \Sigma_k^{1/2} V_k^T$$

- ▶ (numerical) solution via alternating minimization

Generalized low rank model

$$\text{minimize } \sum_{(i,j) \in \Omega} L_j(x_i y_j, A_{ij}) + \sum_{i=1}^m r_i(x_i) + \sum_{j=1}^n \tilde{r}_j(y_j)$$

- ▶ loss functions L_j for each column
 - ▶ e.g., different losses for reals, booleans, categoricals, ordinals, ...
- ▶ regularizers $r : \mathbf{R}^{1 \times k} \rightarrow \mathbf{R}$, $\tilde{r} : \mathbf{R}^k \rightarrow \mathbf{R}$
- ▶ observe only $(i, j) \in \Omega$ (other entries are missing)

Losses

$$\text{minimize } \sum_{(i,j) \in \Omega} L_j(x_i y_j, A_{ij}) + \sum_{i=1}^m r_i(x_i) + \sum_{j=1}^n \tilde{r}_j(y_j)$$

choose loss $L(u, a)$ adapted to data type:

data type	loss	$L(u, a)$
real	quadratic	$(u - a)^2$
real	absolute value	$ u - a $
real	huber	huber $(u - a)$
boolean	hinge	$(1 - ua)_+$
boolean	logistic	$\log(1 + \exp(-au))$
integer	poisson	$\exp(u) - au + a \log a - a$
ordinal	ordinal hinge	$\sum_{a'=1}^{a-1} (1 - u + a')_+ +$ $\sum_{a'=a+1}^d (1 + u - a')_+$
categorical	one-vs-all	$(1 - u_a)_+ + \sum_{a' \neq a} (1 + u_{a'})_+$
categorical	multinomial logit	$\frac{\exp(u_a)}{(\sum_{a'=1}^d \exp(u_{a'}))}$

Regularizers

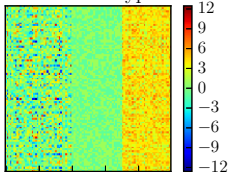
$$\text{minimize } \sum_{(i,j) \in \Omega} L_j(x_i y_j, A_{ij}) + \sum_{i=1}^m r_i(x_i) + \sum_{j=1}^n \tilde{r}_j(y_j)$$

choose regularizers r, \tilde{r} to impose structure:

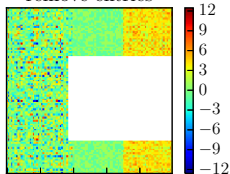
structure	$r(x)$	$\tilde{r}(y)$
small	$\ x\ _2^2$	$\ y\ _2^2$
sparse	$\ x\ _1$	$\ y\ _1$
nonnegative	$\mathbf{1}(x \geq 0)$	$\mathbf{1}(y \geq 0)$
clustered	$\mathbf{1}(\text{card}(x) = 1)$	0

Impute heterogeneous data

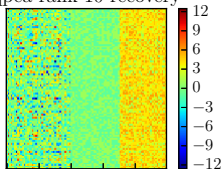
mixed data types



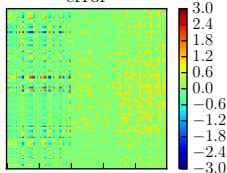
remove entries



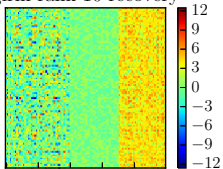
qpca rank 10 recovery



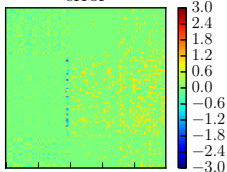
error



glm rank 10 recovery



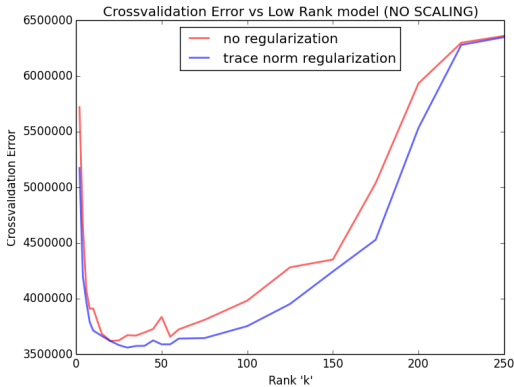
error



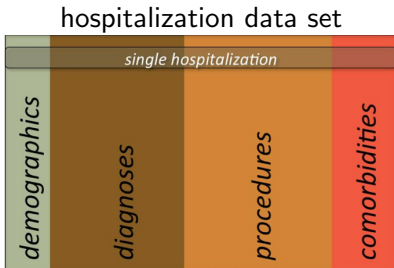
US politics are low rank [Sengupta U Evans, in prep]

General Social Survey (GSS):

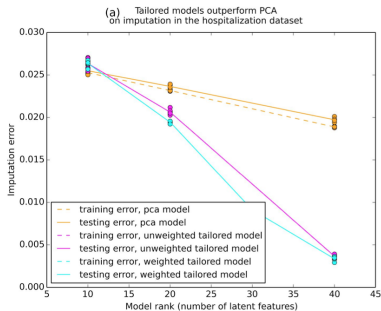
- ▶ survey adults in randomly selected US households about attitudes and demographics
- ▶ > 33% missing data



Hospitalizations are low rank [Schuler et al., 2016]



GLRM outperforms PCA



Fitting GLRMs with alternating minimization

$$\text{minimize } \sum_{(i,j) \in \Omega} L_j(x_i y_j, A_{ij}) + \sum_{i=1}^m r_i(x_i) + \sum_{j=1}^n \tilde{r}_j(y_j)$$

repeat:

1. minimize objective over x_i (in parallel)
2. minimize objective over y_j (in parallel)

properties:

- ▶ subproblems easy to solve
- ▶ objective decreases at every step, so converges if losses and regularizers are bounded below
- ▶ (not guaranteed to find global solution, but) usually finds good model in practice
- ▶ naturally parallel, so scales to *huge* problems

Alternating updates

```
given  $X^0, Y^0$ 
for  $t = 1, 2, \dots$  do
  for  $i = 1, \dots, m$  do
     $x_i^t = \text{update}_{L,r}(x_i^{t-1}, Y^{t-1}, A)$ 
  end for
  for  $j = 1, \dots, n$  do
     $y_j^t = \text{update}_{L,\tilde{r}}(y_j^{(t-1)T}, X^{(t)T}, A^T)$ 
  end for
end for
```

- ▶ no need to exactly minimize
- ▶ choose fast, simple update rules

Proximal operator

define the *proximal operator*

$$\mathbf{prox}_f(z) = \underset{x}{\operatorname{argmin}}(f(x) + \frac{1}{2}\|x - z\|_2^2)$$

- ▶ **generalized projection:** if $\mathbf{1}_C$ is the indicator function of a set C , then

$$\mathbf{prox}_{\mathbf{1}_C}(z) = \Pi_C(z)$$

- ▶ **implicit gradient step:** if $x = \mathbf{prox}_f(z)$, then

$$\nabla f(x) + x - z = 0$$

$$x = z - \nabla f(x)$$

- ▶ **simple to evaluate:** closed form solutions for

- ▶ $f = \|\cdot\|_2^2$

- ▶ $f = \|\cdot\|_1$

- ▶ $f = \mathbf{1}_+$

- ▶ ...

A simple, fast update rule

proximal gradient method: let

$$g = \sum_{j:(i,j) \in \Omega} \nabla L_j(x_i y_j, A_{ij}) y_j$$

and update

$$x_i^{t+1} = \mathbf{prox}_{\alpha_t r}(x_i^t - \alpha_t g)$$

- ▶ **simple:** only requires ability to evaluate ∇L and \mathbf{prox}_r
- ▶ **time per iteration:** $O\left(\frac{(n+m+|\Omega|)k}{p}\right)$ on p processors

Implementations

Implementations in Python (serial), Julia (shared memory parallel), Spark (parallel distributed), and H2O (parallel distributed).

example: (Julia) forms and fits a k -means model with $k = 5$

```
losses = QuadLoss()           # minimize squared error
rx = UnitOneSparseConstraint() # one cluster per row
ry = ZeroReg()                # free cluster centroids
glrm = GLRM(A,losses,rx,ry,k) # form model
fit!(glrm)                   # fit model
```

When is a low rank model an SDP?

Theorem

(X, Y) is a solution to

$$\text{minimize } \sum_{(i,j) \in \Omega} L_j(x_i y_j, A_{ij}) + \sum_{i=1}^m \|x_i\|^2 + \sum_{j=1}^n \|y_j\|^2 \quad (\mathcal{F})$$

if and only if $Z = XY$ is a solution to

$$\begin{aligned} &\text{minimize } L(Z) + \gamma \|Z\|_* \\ &\text{subject to } \mathbf{Rank}(Z) \leq k \end{aligned} \quad (\mathcal{R})$$

where $\|Z\|_*$ is the sum of the singular values of Z .

- ▶ if F is convex, then \mathcal{R} is a rank-constrained semidefinite program
- ▶ local minima of \mathcal{F} correspond to local minima of \mathcal{R}

Dynamic low rank models (with Nathan Kallus)

for $t = 1, \dots, T$,

- ▶ customer $i_t \in \{1, \dots, m\}$ arrives
- ▶ store presents item j_t
- ▶ customer takes action (and store observes) $x_{i_t} y_{j_t} + \epsilon_t$
(buys/rates item j)
- ▶ store receives utility $r_t = x_{i_t} y_{j_t} + \epsilon_t$

choose j_t to maximize utility $\sum_{t=1}^T r_t$?

There's more to do!

theory

- ▶ fast algorithms for large-scale low-rank SDPs
- ▶ dynamics for fast learning (and profit) (Nathan Kallus)
- ▶ asynchronous parallel algorithms for GLRMs (Damek Davis)
- ▶ statistical inference and consistency

applications

- ▶ medical diagnostics
- ▶ social science
- ▶ low energy sensing and data processing
- ▶ photovoltaic array design

extensions

- ▶ using timeseries and graph structure
- ▶ learning across data sets