## **ORIE 6300** Mathematical Programming I

October 27, 2016

Problem Set 7

Due Date: November 3, 2016

1. Let  $\gamma$  and  $\tau$  be positive real numbers **that satisfy**  $\gamma \tau < \frac{1}{\|A\|^2}$ . Consider the Chambolle-Pock operator

$$T_{\rm CP} : \mathbb{R}^m \times \mathbb{R}^n \to \mathbb{R}^m \times \mathbb{R}^n$$
$$T_{\rm CP} \begin{bmatrix} y \\ x \end{bmatrix} := \begin{bmatrix} y - \gamma \left(Ax - b\right) \\ \max\{x + \tau \left(A^T \left(y - 2\gamma (Ax - b)\right) - c\right), 0\} \end{bmatrix},$$

In this exercise, we're going to prove that  $T_{CP}$  is firmly-nonexpansive in a Mahalanobis norm  $||x||_Q$ , i.e.,

$$(\forall z_1 \in \mathbb{R}^{m+n}), (\forall z_2 \in \mathbb{R}^{m+n}) \|T_{CP}z_1 - T_{CP}z_2\|_Q^2 \le \|z_1 - z_2\|_Q^2 - \|(z_1 - T_{CP}z_1) - (z_2 - T_{CP}z_2)\|_Q^2,$$
(1)

where

$$Q = \begin{bmatrix} \frac{1}{\gamma}I & -A\\ -A^T & \frac{1}{\tau}I \end{bmatrix}$$

Define the *set-valued* mapping  $M : \mathbb{R}^{m+n} \to 2^{\mathbb{R}^{m+n}}$ : for all  $z = (y, x) \in \mathbb{R}^{m+n}$ ,

$$Mz := \{-b\} \times (c + N_{\mathbb{R}^m_{\geq 0}}(x)) + \begin{bmatrix} 0 & A \\ -A^T & 0 \end{bmatrix} \begin{bmatrix} y \\ x \end{bmatrix}$$

(a) Let  $z = (y, x) \in \mathbb{R}^{m+n}$ . Show that

$$Q(z - T_{\rm CP}z) \in MT_{\rm CP}z$$

(**Hint:** use the projection inclusion formula  $x - P_C(x) \in N_C(P_C(x))$ ).

(b) Let  $z_1 = (y_1, x_1) \in \mathbb{R}^{m+n}$  and  $z_2 = (y_2, x_2) \in \mathbb{R}^{m+n}$ . Show that

$$(\forall u_1 \in Mz_1), (\forall u_2 \in Mz_2) \qquad \langle z_1 - z_2, u_1 - u_2 \rangle \ge 0$$

(this condition states that M is a monotone operator). Using Part 1a, conclude that

$$\langle (z_1 - T_{\rm CP} z_1) - (z_2 - T_{\rm CP} z_2), T_{\rm CP} z_1 - T_{\rm CP} z_2 \rangle_Q \ge 0$$

where for all  $z, z' \in \mathbb{R}^{m+n}$ , we have  $\langle z, z' \rangle_Q = \langle Qz, z' \rangle$ . (c) Prove (1). 2. This exercise shows that solving a system of linear inequalities is essentially as hard as solving an LP.

Let  $P(A, b) = \{x \mid Ax = b, x \ge 0\}$ . Suppose that  $x^*$  is a minimizer of  $\min_{x \in P(A,b)} c^T x$ . Let  $x_0 \in \mathbb{R}^n$  and for all  $\gamma > 0$ , define

$$x_{\gamma} = P_{P(A,b)}(x_0 - \gamma c).$$

Prove that

$$\langle c, x_{\gamma} \rangle \leq \langle c, x^* \rangle + \frac{1}{2\gamma} \|x_0 - x^*\|^2.$$

For which  $\gamma > 0$  is  $x_{\gamma}$  an  $\varepsilon$ -accuracy solution of the LP? (Recall that x is an  $\varepsilon$ -accuracy solution if it is feasible and  $\langle c, x \rangle < \langle c, x^* \rangle + \varepsilon$ .)

3. In this exercise, we learn how to parallelize the Douglas-Rachford Splitting (DRS) algorithm and the Method of Alternating Projections (MAP) through the *product-space trick*.

Consider l closed convex sets  $C_1, \ldots, C_l \subseteq \mathbb{R}^r$ . Assume that  $C_1 \cap \ldots \cap C_l \neq \emptyset$ . Define  $C = C_1 \times \cdots \times C_l$ . Define the *diagonal* vector subspace  $V \subseteq \mathbb{R}^{rl}$ :

$$V := \{ (x_1, \dots, x_l) \in \mathbb{R}^{rl} \mid (\forall i) \ x_i \in \mathbb{R}^r, x_1 = x_2 = \dots = x_l \}.$$

- (a) Given  $z \in \mathbb{R}^{rl}$ , compute  $P_V z$  and determine  $\operatorname{Fix}(P_V)$ .
- (b) Given  $z \in \mathbb{R}^{rl}$ , compute  $P_C z$  and determine  $\operatorname{Fix}(P_C)$ .
- (c) Determine  $\operatorname{Fix}(P_V P_C)$  and  $\operatorname{Fix}\left(\frac{1}{2}(2P_V I) \circ (2P_C I) + \frac{1}{2}I\right)$

(d) Consider the primal-dual pair of linear programs

 $\min\{c^T x \mid Ax = b, x \ge 0\} \qquad \text{and} \qquad \max\{b^T y \mid A^T y \le c\},$ 

and assume that there exists a primal-dual optimal solution, e.g.,  $(x^*, y^*) \in \mathbb{R}^{n+m}$ . Define

$$D := \begin{bmatrix} A & 0 & 0 \\ 0 & A^T & I \\ c^T & -b^T & 0 \end{bmatrix} \quad \text{and} \quad d := \begin{bmatrix} b \\ c \\ 0 \end{bmatrix}.$$

Note that Dz = d has at least one solution because the LPs are solvable. Let l = n+m+2and define

$$C_l := \left\{ \begin{bmatrix} x \\ y \\ s \end{bmatrix} \mid x \ge 0, s \ge 0 \right\}.$$

Provide l-1 sets  $C_1, \ldots, C_{l-1} \subseteq \mathbb{R}^{m+2n}$  such that (1)  $\{z \mid Dz = d\} = C_1 \cap \ldots \cap C_{l-1}$ and (2) for each  $i = 1, \ldots, l-1$ , the set  $C_i$  is defined purely in terms of the *i*th rows of D and d.

As before, define  $V \subseteq \mathbb{R}^{l(m+2n)}$  and  $C := C_1 \times \ldots \times C_l$ . Given  $z \in \mathbb{R}^{l(m+2n)}$  compute  $P_V P_C(z)$ . What is the biggest computational drawback of this approach? Are there other ways to split  $\{z \mid Dz = d\}$  into fewer sets? (There is no single correct answer.)