ORIE 633 Network Flows

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Lecture 12

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1 Minimum-cost circulations

Recall the minimum-cost circulation problem, introduced in the previous lecture:

Minimum-cost circulation problem

- Input:
 - A directed graph G = (V, A).
 - Integer costs $c_{ij} \in \mathbb{Z}, \forall (i,j) \in A$.
 - Integer capacities $u_{ij} \geq 0, \forall (i,j) \in A$.
 - Integer demands $0 \le l_{ij} \le u_{ij}, \forall (i,j) \in A$.
- Goal: Find a minimum-cost circulation.

The goal is to find a flow $f: A \to \mathbb{R}^{\geq 0}$ that minimizes $\sum_{(i,j)\in A} c_{ij} f_{ij}$ such that

$$l_{ij} \le f_{ij} \le u_{ij}, \qquad \forall (i,j) \in A$$
$$\sum_{k:(i,k)\in A} f_{ik} - \sum_{k:(k,i)\in A} f_{ki} = 0, \quad \forall i \in V$$

In the previous lecture, we defined a notation change for circulations similar to the one we defined for s-t flows.

Definition 1 A circulation f satisfies the following:

- 1. $f_{ij} \leq u_{ij} \ \forall \ (i,j) \in A$
- 2. $f_{ij} = -f_{ji}, \forall (i,j) \in A$
- 3. $\sum_{k:(k,i)\in A} f_{ki} = 0$

In the new definition, flow in the original arc f_{ij} satisfies the constraints $f_{ij} \leq u_{ij}$, and each unit of flow incurs cost c_{ij} . Flow on the reverse arc f_{ji} satisfies $f_{ji} \leq u_{ji} = -l_{ij}$ and incurs cost $c_{ji} = -c_{ij}$ per unit of flow. The total cost for the two edges with flow f is $c_{ji}f_{ji} + c_{ij}f_{ij} = 2c_{ij}f_{ij}$. Hence optimizing the total cost for this new graph is the same as optimizing the total cost for the original graph.

Given a flow f on G, last time we defined the residual graph to be $G_f = (V, A_f)$ where the new arc set

$$A_f := \{(i, j) \in A : f_{ij} < u_{ij}\}.$$

Note that we are using the new notation here. Impose the upper bound $u_{ij}^f = u_{ij} - f_{ij}$ for arc $(i,j) \in A_f$. Then clearly $u_{ij}^f > 0$ for all $(i,j) \in A_f$.

We also defined node potentials

Definition 2 A potential is a function $p: V \to \mathbb{R}$.

Definition 3 Given a potential p, define the reduced cost $c_{ij}^p := c_{ij} + p_i - p_j$. Then $c_{ji}^p = c_{ji} + p_j - p_i = -(c_{ij} + p_i - p_j) = -c_{ij}^p$.

The node potentials play the role of dual variables.

Definition 4 The cost of a cycle Γ is $c(\Gamma) = \sum_{(i,j) \in \Gamma} c_{ij}$.

We proved the following theorem (optimality conditions) in the last lecture:

Theorem 1 The following are equivalent:

- 1. f is a minimal cost circulation,
- 2. There are no negative cost cycles in G_f , and,
- 3. There exists a potential p such that $c_{ij}^p \geq 0$ for all $(i,j) \in A_f$.

2 A cycle-cancelling algorithm

The theorem above leads to a natural algorithm for computing a min-cost circulation:

Cycle-Cancelling Algorithm (Klein '67)

Let f be a feasible circulation.

While A_f contains a negative cycle Γ

Cancel Γ , update f.

The correctness of the algorithm follows immediately from the above theorem. If costs and capacities are both integral, then there exists an optimal flow f such that f_{ij} integer for all $(i,j) \in A$. Suppose

$$U = \max_{(i,j)\in A} u_{ij} \qquad C = \max_{(i,j)\in A} |c_{ij}|.$$

Then any feasible circulation costs at most mCU and at least -mCU. Since a cycle cancellation improves the cost of a circulation by at least 1, at most O(mCU) cancellations are needed in order to find an optimal circulation.

We need two more things to conclude that the above algorithm is pseudo-polynomial:

- 1. We need to be able to find an initial circulation: For this, recall from Problem Set 1 that this can be done in one max flow calculation.
- 2. We need to be able to check the existence of a negative-cost cycle: For this, recall from Problem Set 2 that the this can be done via the Bellman-Ford algorithm in O(mn) time. So we have a pseudo-polynomial time algorithm that runs in $O(m^2nCU)$ time.

3 Minimum mean-cost cycle cancelling

As with the augmenting path algorithm for the maximum flow problem, we can obtain a polynomial-time algorithm by a better choice of which cycle to cancel at each iteration. Consider the following.

Definition 5 Let the mean cost of a cycle Γ be $\frac{c(\Gamma)}{|\Gamma|}$ where $c(\Gamma)$ is the cost of the cycle and $|\Gamma|$ is the number of arcs in Γ .

Definition 6 Given a circulation f, let $\mu(f)$ be the cost of the minimum mean-cost cycle in G_f :

$$\mu(f) = \min_{cycles \ \Gamma \subseteq A_f} \frac{c(\Gamma)}{|\Gamma|}$$

It turns out we can get a polynomial-time algorithm by cancelling the *minimum mean-cost cycle*. We can now give the following algorithm:

Minimum mean-cost cycle cancelling algorithm (Goldberg-Tarjan '89)

Let f be any circulation

While $\mu(f) < 0$

Cancel min-mean cycle Γ , update f

Observe that the condition $\mu(f) < 0$ is equivalent to having a negative-cost cycle in A_f . To have a polynomial-time algorithm, we need to be able to find the minimum mean-cost cycle in polynomial-time. In Problem Set 3, we will show that one can compute $\mu(f)$ and find the corresponding cycle in O(mn) time.

To begin our analysis, we need to introduce a few terms.

Definition 7 A circulation f is ϵ -optimal if there exist potentials p s.t. $c_{ij}^p \geq -\epsilon$ for all $(i,j) \in A_f$.

Clearly f is 0-optimal if and only if f is a min-cost circulation by the third equivalence in Theorem 1. For any circulation, f is C-optimal, since if we assign $p_i = 0$ for all $i \in V$, $c_{ij}^p \geq -C$ for all $(i,j) \in A_f$.

Definition 8 Define $\epsilon(f)$ to be the minimum ϵ such that f is ϵ -optimal.

Interestingly, the two values of $\epsilon(f)$ and $\mu(f)$ are closely related.

Theorem 2 For a circulation f, $\mu(f) = -\epsilon(f)$.

Proof: We first show that $\mu(f) \geq -\epsilon(f)$. Since $\exists p \text{ s.t. } c_{ij}^p \geq -\epsilon(f)$ for all $(i,j) \in A_f$, by summing over all arcs in any cycle Γ we obtain that $c^p(\Gamma) \geq -\epsilon(f)|\Gamma|$. Thus

$$\mu(f) = \frac{c(\Gamma)}{|\Gamma|} = \frac{c^p(\Gamma)}{|\Gamma|} \ge -\epsilon(f).$$

for a minimum mean-cost cycle Γ .

We now show that $\mu(f) \leq -\epsilon(f)$. Set $\overline{c}_{ij} = c_{ij} - \mu(f)$. Then for any cycle Γ in A_f :

$$\overline{c}(\Gamma) = c(\Gamma) - |\Gamma|\mu(f) \ge c(\Gamma) - |\Gamma|\frac{c(\Gamma)}{|\Gamma|} = 0.$$

We introduce a source vertex s, connected to all vertices i with arcs of cost $\bar{c}_{si} = 0$, and define the potential p_i of node i to be the length of shortest path from s to i using costs \bar{c}_{ij} . Note that this notion is well-defined, since by the previous argument, there are no negative-cost cycles with respect to costs \bar{c}_{ij} . By the definition of shortest path, for all $(i,j) \in A_f$, $p_j \leq p_i + \bar{c}_{ij} = p_i + c_{ij} - \mu(f)$ which implies $c_{ij}^p = c_{ij} + p_i - p_j \geq \mu(f)$ for all $(i,j) \in A_f$. This means f is $-\mu(f)$ -optimal which implies that $\epsilon(f) \leq -\mu(f)$.

Given circulation f, let $f^{(k)}$ denote the circulation we get after k iterations of cancelling minimum mean-cost cycles in f. The following theorems, which we will prove later, will show that the Goldberg-Tarjan algorithm runs in polynomial time.

Theorem 3 $\epsilon(f^{(1)}) \leq \epsilon(f)$.

Theorem 4 $\epsilon(f^{(m)}) \le (1 - 1/n)\epsilon(f)$.

where m, n are the number of arcs and nodes in the graph, respectively.

We will also need the following.

Theorem 5 When $\epsilon(f) < 1/n$ then circulation f is optimal.

Proof: The fact that $\epsilon(f) < 1/n$ implies that there exist a potential p such that $c_{ij}^p > -1/n$ for all $(i,j) \in A_f$. Thus for all cycles $\Gamma \in A_f$, $c(\Gamma) = c^p(\Gamma) > -1$. By the integrality of costs, this gives $c(\Gamma) \geq 0$.

We shall now prove using the previous three results that the Goldberg-Tarjan algorithm terminates in time bounded by a polynomial in the input size.

Theorem 6 (Goldberg-Tarjan '89) The Goldberg-Tarjan minimum mean-cost cycle cancelling algorithm requires at most $O(mn \log(nC))$ iterations.

Proof: Any initial circulation is C-optimal. After $k = mn \log(nC)$ iterations, we have that

$$\epsilon(f^{(k)}) \le (1 - 1/n)^{n \log(nC)} C < e^{-\log(nC)} C = 1/n,$$

using the fact that $(1-1/n)^n < e^{-1}$. This proves the optimality of $f^{(k)}$ by Theorem 5.

The running of the Goldberg-Tarjan algorithm is $O(m^2n^2\log(nC))$ time as min-mean cycle computations take O(mn) time (See Problem Set 3 regarding the latter fact). Note that this algorithm is not strongly polynomial. A strongly polynomial algorithm will be presented in the next lecture. For now, we return and prove Theorem 3 and Theorem 4.

Proof of Theorem 3: We know there exist potentials p such that

$$c_{ij}^p \ge -\epsilon(f)$$
 for all $(i,j) \in A_f$.

Also, $\mu(f) = -\epsilon(f)$. For the minimum-mean cost cycle Γ , since $\mu(f) = c^p(\Gamma)/|\Gamma|$, it follows that for all $(i,j) \in \Gamma$, $c^p_{ij} = -\epsilon(f)$. We now claim that $c^p_{ij} \ge -\epsilon(f)$ for all $(i,j) \in A_{f^{(1)}}$. We have $(i,j) \in A_{f^{(1)}}$ if either (i,j) was in A_f , or if $(j,i) \in \Gamma$. In the first case, $c^p_{ij} \ge -\epsilon(f)$. In

the latter case, $c_{ij}^p = -c_{ji}^p = \epsilon(f) \ge 0$. In both cases, it follows that $f^{(1)}$ is $\epsilon(f)$ -optimal, so the theorem statement follows.

Proof of Theorem 4: We know there exists a potential p such that $c_{ij}^p \geq -\epsilon(f)$ for all $(i,j) \in A_f$. Suppose that in some iteration k we cancel cycle Γ such that $\exists (i,j) \in \Gamma$ with $c_{ij}^p \geq 0$. Then:

$$-\epsilon(f^{(k)}) = \mu(f^{(k)}) = \frac{c^p(\Gamma)}{|\Gamma|}$$

$$\geq \frac{|\Gamma| - 1}{|\Gamma|} (-\epsilon(f))$$

$$\geq \left(1 - \frac{1}{n}\right) (-\epsilon(f)).$$

Thus

$$\epsilon(f^{(k)}) \le \left(1 - \frac{1}{n}\right)\epsilon(f).$$

How many consecutive iterations can there be such that $c^p_{ij} < 0$ for all (i,j) in the cancelled cycle Γ ? Cancelling the cycle removes one edge with $c^p_{ij} < 0$ from the residual graph and creates only edges with $c^p_{ij} \geq 0$. So we need no more than m iterations before we cancel such a cycle Γ .