

Semiparametric Estimation of the Proportion of True Null Hypotheses

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Problem:

- One has a large collection of p-values, p_1, \dots, p_n
- Need to know the proportion that came from a true H_0
 - useful, e.g., to estimate the false discovery rate

Recent paper:

Langaas, Ferkingstad, and Lindqvist (2005, JRSS-B)

- Surveys earlier work on this topic
 - Estimator of Schweder and Spjøtvoll

$$\hat{\pi}(\lambda) = \frac{\#\{p_j > \lambda\}}{n(1 - \lambda)}$$

- * λ estimated by a bootstrapping (Storey, 2002) or spline-smoothing (Storey and Tibshirani, 2003)
- Proposes new estimators
 - Estimate the marginal density of the p-values at 0 by
 - * Grenander decreasing density estimator
 - * longest-constant interval estimator
 - * convex-decreasing estimator

Topic of this talk – semiparametric estimator:

- $\{(p_i, \mu_i)\}_{i=1}^n$ are iid

- let

$$\pi_0 = P(\mu_i \in \text{null region})$$

- $g(\mu) = \text{density of } \mu_i \text{ under } H_1$

- marginal cdf of p_i is

$$F_p(p; \pi_0) = \pi_0 p + (1 - \pi_0) \int_0^\infty F_{p|\mu}(p; \mu) g(\mu) d\mu \quad (1)$$

- denote marginal pdf by $f_p(p; \pi_0)$.

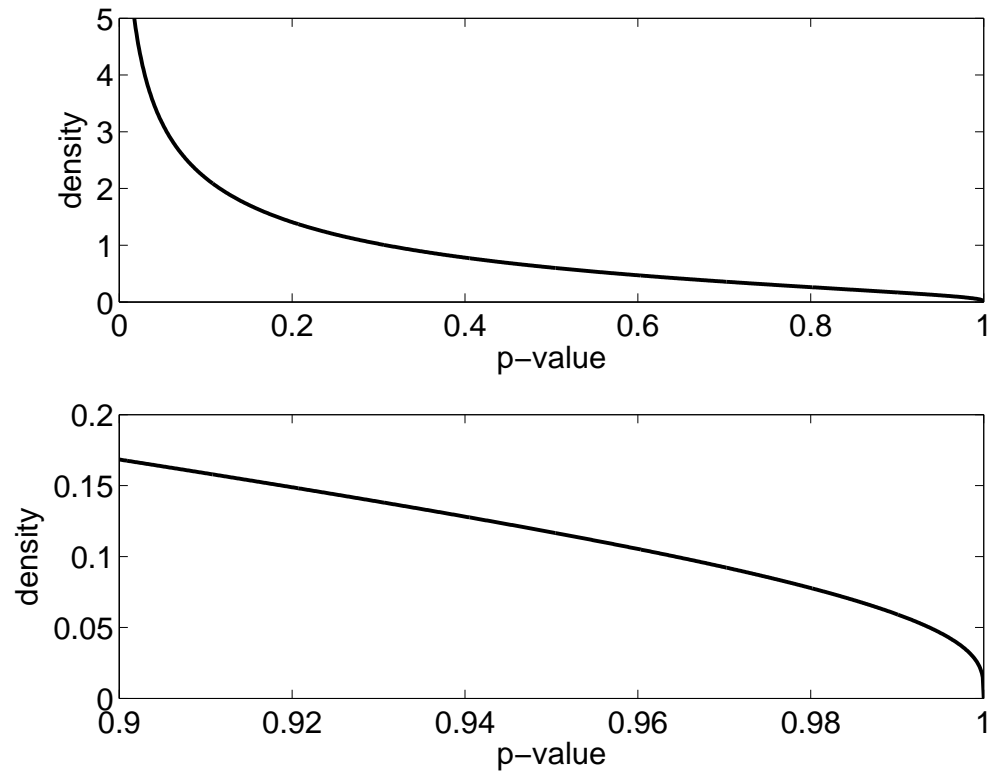


Figure 1: Density of the p -value from a z -test of $H_0 : \mu = 0$ versus $H_1 : \mu > 0$ when $\mu = 1$. The lower plot zooms in on the region where the density is concave.

- model g as $g(\mu; \boldsymbol{\beta})$
 - $g(\cdot; \cdot)$ is a known function
 - $\boldsymbol{\beta}$ is a vector of parameters
 - will use linear splines
- let $F_p(\cdot; \pi_0, \boldsymbol{\beta})$ be given by (1) with $g(\mu)$ replaced by $g(\mu; \boldsymbol{\beta})$.

Weighted penalized least-squares

- let l_i, c_i, r_i , and $w_i = r_i - l_i$ be the left edge, center, right edge, and width of the i th bin, $i = 1, \dots, N_{\text{bin}}$
- let $M_1, \dots, M_{N_{\text{bin}}}$ be the bin counts
-

$$y_i = \frac{M_i}{nw_i}$$

is an unbiased estimate of

$$m_i(\pi_0, \boldsymbol{\beta}) = \frac{F_p(l_i; \pi_0, \boldsymbol{\beta}) - F_p(r_i; \pi_0, \boldsymbol{\beta})}{w_i} \approx f_p(c_i; \pi_0)$$

- estimate $(\pi_0, \boldsymbol{\beta})$ by minimizing the penalized sum of squares is

$$SS(\pi_0, \boldsymbol{\beta}; \lambda) = \sum_{i=1}^{N_{\text{bin}}} \{y_i - m_i(\pi_0, \boldsymbol{\beta})\}^2 + \lambda Q(\boldsymbol{\beta}) \quad (2)$$

- $\lambda \geq 0$
- $Q(\boldsymbol{\beta})$ is a roughness penalty

Spline model for g

- g will be modeled as a linear spline and estimated using the B-spline basis
- g is assumed to have support contained in $[0, \mu^*]$
- spline will have K knots, $0 = \kappa_1, \dots, \kappa_K = \mu^*$, equally spaced between 0 and μ^*

- B-splines are normalized to be densities
 - not essential, but helpful
 - any convex combination is a density
- let

$$g(\mu, \boldsymbol{\beta}) = \sum_{k=1}^{K-1} \beta_k B_k(\mu), \quad (3)$$

where $\beta_k \geq 0$ for all k and $\sum_{k=1}^{K-1} \beta_k = 1$.

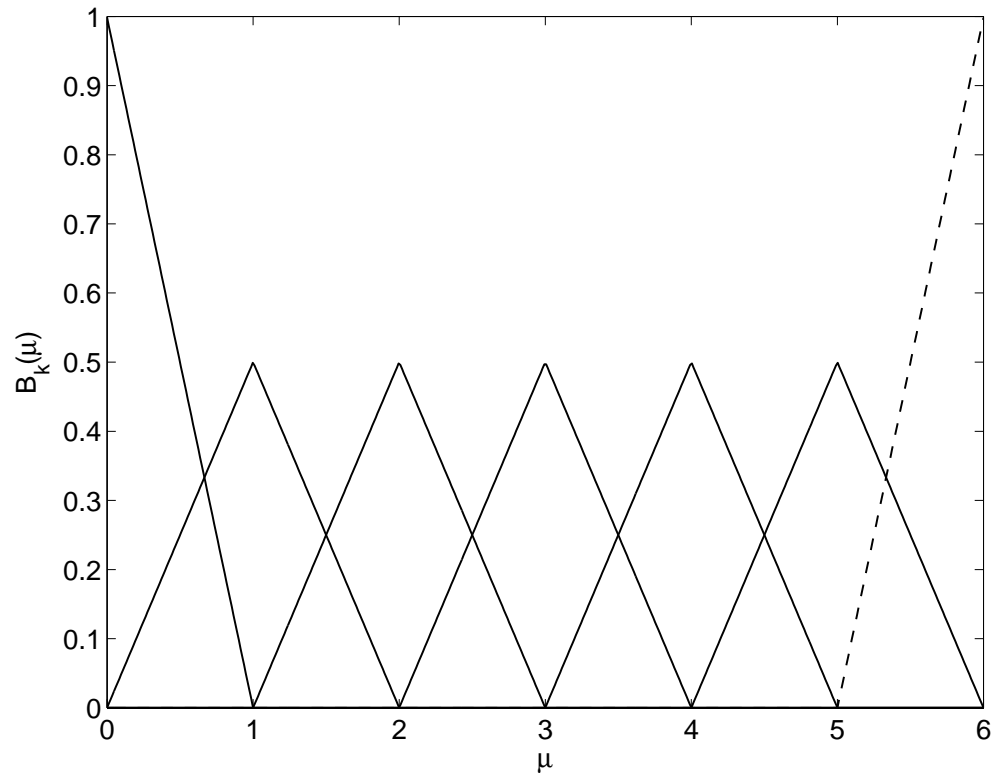


Figure 2: B-splines with 7 knots and $\mu^* = 6$ used to model g . Each B-spline is normalized to be a density. The B-spline with support $[5, 6]$ is shown as a dashed line and is not used in the model for g because it is discontinuous at 6.

- define $\theta_1 = \pi_0$ and $\theta_{k+1} = (1 - \pi_0)\beta_k$ for $k = 1, \dots, K - 1$
- define $\boldsymbol{\theta} = (\theta_1, \dots, \theta_K)^\top$
- let $Z_1(p) = p$ be the (uniform) cdf of the p -values under H_0
- for $k = 1, \dots, K - 1$, let $Z_{k+1}(p) = \int F_{p|\mu}(p; \mu) B_k(\mu) d\mu$ be the marginal cdf of a p -value if the density of μ is B_k
- the marginal cdf of a p -value is modeled as

$$F_p(p; \boldsymbol{\theta}) = \sum_{k=1}^K \theta_k Z_k(p), \quad (4)$$

where

$$\theta_k \geq 0, \quad \forall k, \quad \text{and} \quad \sum_{k=1}^K \theta_k = 1 \quad (5)$$

- The roughness penalty is

$$\begin{aligned} Q(\boldsymbol{\theta}) &= (2\theta_1 - \theta_2)^2 + \sum_{k=2}^{K-1} (\theta_k - \theta_{k+1})^2 \\ &= \{d(1 - \pi_0)\}^2 \sum_{k=1}^{K-1} \{g(\kappa_k) - g(\kappa_{k+1})\}^2 \end{aligned}$$

- the sum of squares is

$$\begin{aligned}
 SS(\boldsymbol{\theta}; \lambda) &= \sum_{i=1}^{N_{\text{bin}}} \left\{ y_i - \sum_{k=0}^{K-1} \theta_k Z_{i,k+1} \right\}^2 \\
 &+ \lambda \left\{ (2\theta_2 - \theta_3)^2 + \sum_{k=3}^{K-1} (\theta_k - \theta_{k+1})^2 \right\} \\
 &= \|\mathbf{y} - \mathbf{Z}\boldsymbol{\theta}\|^2 + \lambda \boldsymbol{\theta}^\top \{(\mathbf{D}\mathbf{A})^\top \mathbf{D}\mathbf{A}\} \boldsymbol{\theta},
 \end{aligned}$$

where

- $\mathbf{y} = (y_1, \dots, y_{N_{\text{bin}}})^\top$
- \mathbf{Z} is the $N_{\text{bin}} \times K$ matrix whose i, j th element is $Z_{i,j} = \{Z_j(r_i) - Z_j(l_i)\}/w_i$
- $\mathbf{A} = \text{diag}(0, 2, 1, \dots, 1)$
- \mathbf{D} is a $(K - 2) \times K$ “differencing matrix” whose i th row has +1 in column $i + 1$, -1 in column $i + 2$, 0 elsewhere

- minimizing $SS(\boldsymbol{\theta}; \lambda)$ is equivalent to minimizing

$$\boldsymbol{f}^\top \boldsymbol{\theta} + 0.5 \boldsymbol{\theta}^\top \mathbf{H} \boldsymbol{\theta} \quad (6)$$

where

- $\boldsymbol{f} = -\mathbf{y}^\top \mathbf{Z}$
- $\mathbf{H} = \mathbf{Z}^\top \mathbf{Z} + \lambda \mathbf{A}^\top \mathbf{D}^\top \mathbf{D} \mathbf{A}$,

- the constraints are

$$\boldsymbol{\theta} \geq 0 \text{ and } \mathbf{1}^\top \boldsymbol{\theta} = 1, \quad (7)$$

- $\mathbf{1}$ is a K -dimensional vector of ones

- **approximate GCV** — use GCV for the **unconstrained** estimator

Two semiparametric estimators of θ :

- $\widehat{\pi}_{0\text{sem},1} = \widehat{\theta}_1$
- $\widehat{\pi}_{0\text{sem},2} =$ estimated density at 1 Recall:

$$F_p(p; \boldsymbol{\theta}) = \sum_{k=1}^K \theta_k Z_k(p)$$

Therefore,

$$\widehat{\pi}_{0\text{sem},2} = \sum_{k=1}^K \widehat{\theta}_k Z'_k(p) \Big|_{p=1}$$

Recall:

- $Z_1(p) = p$ is the (uniform) cdf of the p -values under H_0
- for $k = 1, \dots, K - 1$, let $Z_{k+1}(p) = \int F_{p|\mu}(p; \mu) B_k(\mu) d\mu$ is the marginal cdf of a p -value if the density of μ is B_k
- therefore

$$\widehat{\pi}_{0\text{sem},2} = \widehat{\theta}_1 + \sum_{k=2}^K \widehat{\theta}_k \int f_{p|\mu}(p; \mu) B_k(\mu) d\mu \Big|_{p=1} \geq \widehat{\pi}_{0\text{sem},1}$$

Simulation study

- one-side z -test
 - $\mu = 0$ versus $\mu > 0$ based on $Z \sim N(\mu, 1)$
- g is beta(b_1, b_2) on $[\mu_{\min}, \mu_{\max}]$
- Gr- M and LCI- M are the Grenander and longest constant interval estimator estimators using M equally-spaced order statistics
 - $M = n$ gives standard Grenander and LCI estimators

Gr-50	Gr-500	Gr-5000	LCI-50	LCI-500	LCI-5000
3.0231	23.3634	95.7562	1.9185	4.2623	12.6780

Table 1: $1000 \times \text{MSE}$ for six estimators with $n = 5000$, $\pi_0 = 0.8000$, $\mu_{\min} = 0$, $\mu_{\max} = 4$, $b_1 = 2$, and $b_2 = 2$. Each MSE is based on 25 Monte Carlo simulations. The standard errors of the MSE values are roughly $1/2$ the MSE values themselves or smaller.

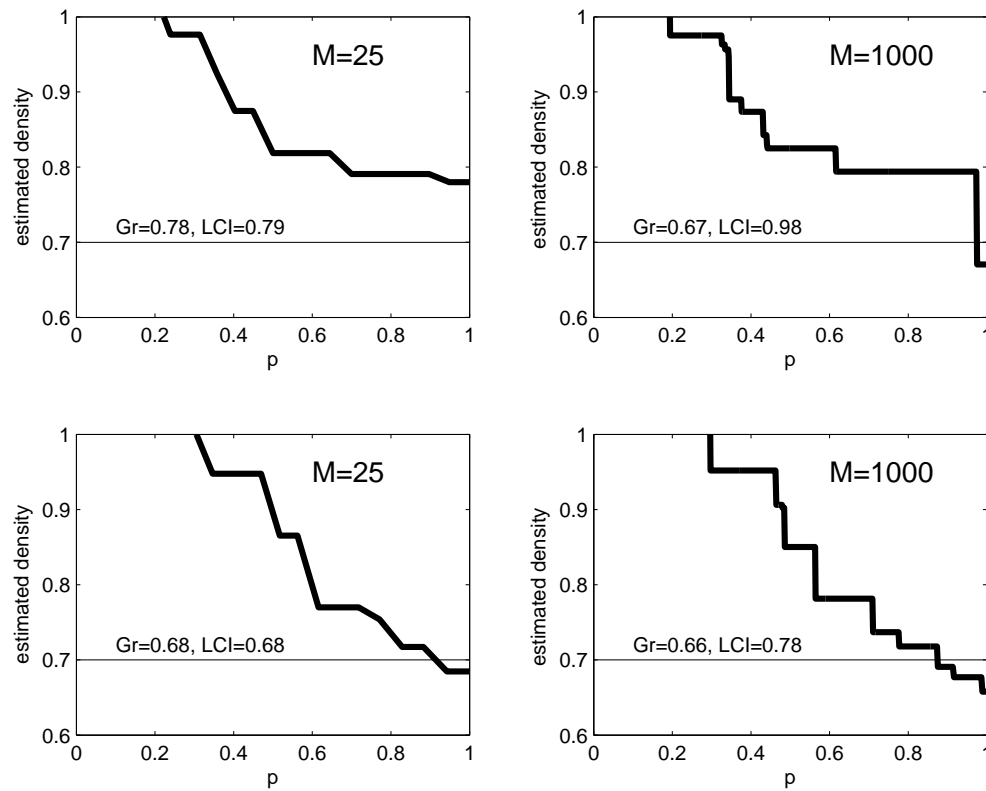


Figure 3: Comparison of Gr-25, Gr-1000, LCI-25, LCI-1000 estimators. The top and bottom rows are different data sets, both from Case #3.

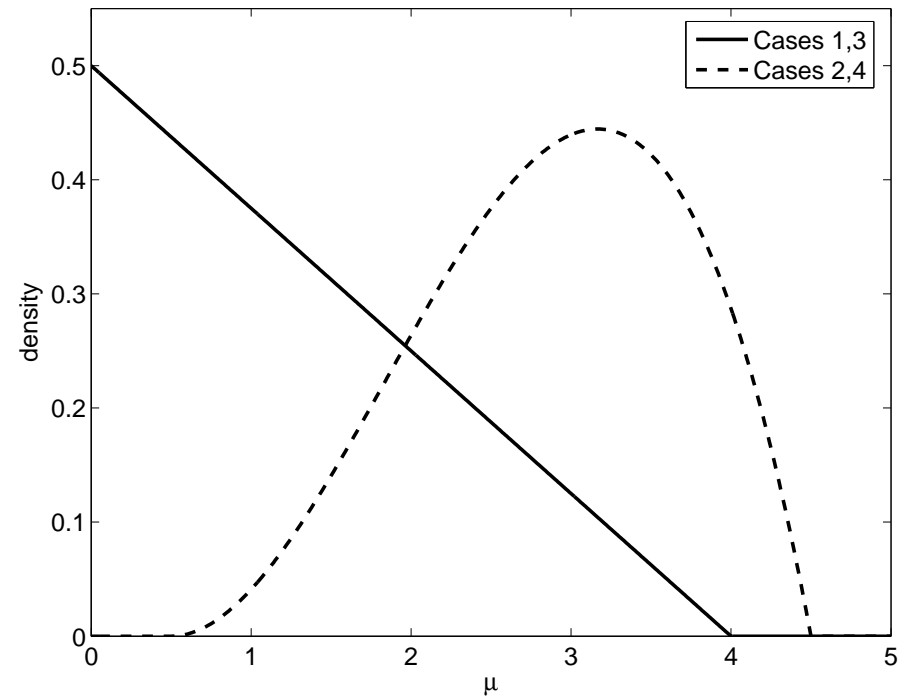


Figure 4: The two non-null densities of μ used in the simulations. Their values of $(\mu_{\min}, \mu_{\max}, b_1, b_2)$ are $(0, 4, 1, 2)$ for Cases 1 and 3, and $(0.5, 4.5, 3, 2)$ for Cases 2 and 4.

	Case #1	Case #2	Case #3	Case #4
π_0	0.95	0.95	0.7	0.7
$\mu_{\min}, \mu_{\max}, b_1, b_2$	0, 4, 1, 2	0.5, 4.5, 3, 2	0, 4, 1, 2	0.5, 4.5, 3, 2
$\widehat{\pi}_{0\text{sem},1}, K = 8, \text{wt}$	0.3759	0.3555	1.6042	0.8240
$\widehat{\pi}_{0\text{sem},2}, K = 8, \text{wt}$	0.3014	0.1878	2.3984	0.3466
$\widehat{\pi}_{0\text{sem},1}, K = 16, \text{wt}$	0.4694	0.2974	1.8562	1.0424
$\widehat{\pi}_{0\text{sem},2}, K = 16, \text{wt}$	0.2961	0.1635	2.5801	0.4004
Gr-10	0.6609	0.8513	4.4478	0.4323
Gr-50	4.0509	4.4439	2.5229	2.3228
Gr-250	16.8678	17.7898	6.5489	9.6928
LCI-10	0.7541	0.7012	4.6142	0.4575
LCI-50	2.2739	1.6569	5.4461	1.4849
LCI-250	3.1757	2.3155	10.2505	2.1253

Table 2: $1000 \times \text{MSE}$. 1500 Monte Carlo samples per case.

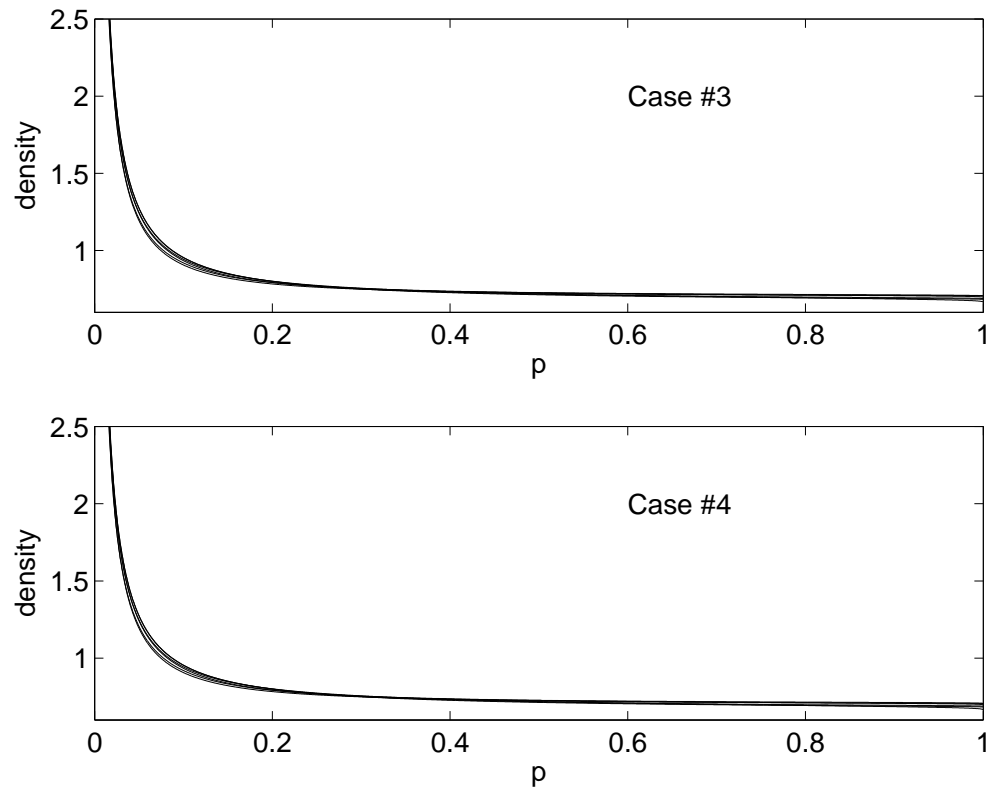


Figure 5: Semiparametric estimates of f_p , the density of the p -values, from six independent data sets from Cases #3 and #4.

Features of semiparametric estimators:

- accurate (small MSE and bias)
- shape-preserving
- fully automatic
- can be computed very rapidly