

Superresolution in the Markov Moment Problem

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Suppose that \bar{x} is a characteristic function and a_1, a_2, \dots, a_n are weight functions on a finite measure space. Recent work of Gamboa and Gassiat observed conditions guaranteeing that $\|x - \bar{x}\|_1$ is small whenever $0 \leq x \leq 1$ a.e. and the moment errors $\int(x - \bar{x})a_i$ are small ($i = 1, 2, \dots, n$). Using concise and elementary techniques we obtain similar results, under very mild assumptions. We also provide precise error bounds. © 1996 Academic Press, Inc.

1. INTRODUCTION

The Markov moment problem studies the relationship between a density \bar{x} on a finite measure space S with $0 \leq \bar{x} \leq 1$ a.e. and its moments $\int a_i \bar{x}$ with respect to given integrable weight functions a_1, a_2, \dots, a_n (see [12]). In physical applications we seek to estimate \bar{x} on the basis of this moment information, sometimes using a maximum entropy technique (see for example [6, 8]). A mathematical survey of such techniques may be found in [3].

Heuristically it has been observed that for some densities \bar{x} , any estimate $0 \leq x \leq 1$ a.e. with moments $\int a_i x$ close to the given moments $\int a_i \bar{x}$ must necessarily be close to \bar{x} (in L_1 norm). This phenomenon is called “superresolution” (see [11] and [7]). An interesting explanation was presented in [9] and [10], based on some sophisticated probabilistic maximum entropy techniques introduced in [5]. The aim of this note is to give a concise, elementary, measure-theoretic approach to this problem. In this straightforward framework we derive results analogous to some of those in [9] and [10] under very simple assumptions and with an explicit error bound.

Let $[0, 1]_\infty = \{x \in L_\infty(S) \mid 0 \leq x \leq 1 \text{ a.e.}\}$, and define a continuous linear map $A: L_\infty(S) \rightarrow \mathbb{R}^n$ by $Ax = \int ax$ (where a has components a_1, a_2, \dots, a_n). Since superresolution requires that $\|\bar{x} - x\|_1$ is small whenever $0 \leq x \leq 1$

a.e. and $f(x - \bar{x})a$ is small, an obvious prerequisite is that $x = \bar{x}$ is the unique solution in $[0, 1]_\infty$ of $fax = f\bar{x}$. For this to be the case, except in trivial, finite-dimensional cases where the null space $N(A) = \{0\}$, it follows that $A\bar{x}$ cannot be in the relative interior of $A[0, 1]_\infty$, $\text{ri}(A[0, 1]_\infty)$, since an easy standard argument shows that $A(\text{int}[0, 1]_\infty) = \text{ri}(A[0, 1]_\infty)$ (see for example Proposition 2.10 in [1]). Hence there exists a supporting hyperplane for $A[0, 1]_\infty$ at $A\bar{x}$: for some nonzero λ in \mathbb{R}^n , $f(x - \bar{x})\lambda^T a \leq 0$ whenever $0 \leq x \leq 1$ a.e. Thus providing that $\lambda^T a$ is nonzero a.e. we have that $\bar{x} = \chi_{S_{\lambda^T a}}$, the characteristic function of the set $S_{\lambda^T a} = \{s \in S \mid \lambda^T a(s) > 0\}$.

The above argument shows that we may often restrict our study of superresolution to cases where $\bar{x} = \chi_{S_{\lambda^T a}}$ for some nonzero λ in \mathbb{R}^n . This is our assumption for the main result, Theorem 2.2, which gives conditions guaranteeing that, for $0 \leq x \leq 1$ a.e.,

$$\|\bar{x} - x\|_1 = O\left(\left\|\int(\bar{x} - x)a\right\|^{1/2}\right).$$

The following example shows that the order of growth is best possible.

EXAMPLE. Let $S = [0, 1]$ with Lebesgue measure, $\bar{x} = \chi_{[0, 1/2]}$, and $x_\varepsilon = \chi_{[0, 1/2 - \varepsilon] \cup [1/2, 1/2 + \varepsilon]}$ for $0 \leq \varepsilon \leq \frac{1}{2}$. Then with $a(s) = (1, s)^T$ we obtain $f(\bar{x} - x_\varepsilon)a = (0, -\varepsilon^2)^T$ and $\|\bar{x} - x_\varepsilon\|_1 = 2\varepsilon$.

We have seen that the superresolution phenomenon is confined to cases where the underlying density \bar{x} is the characteristic function of a set of the form $S_{\lambda^T a}$. It is therefore natural to ask how one recognizes such sets. In one case, familiar from approximation theory, this is extremely easy.

Continuous functions a_1, a_2, \dots, a_n on a real interval I are said to satisfy the *Haar condition* if $\lambda^T a$ has at most $n - 1$ zeroes for any nonzero λ in \mathbb{R}^n (see for example [4]). The standard example is $a_i(s) = s^{i-1}$, for $i = 1, 2, \dots, n$. Suppose that $S = [\mu, \nu]$ is contained in the interior of I (endowed with Lebesgue measure). Then any set $S_{\lambda^T a}$ clearly has the form (up to measure zero)

$$[s_0, s_1] \cup [s_2, s_3] \cup \dots \quad \text{or} \quad [s_1, s_2] \cup [s_3, s_4] \cup \dots,$$

where $\mu = s_0 < s_1 < \dots < s_k < s_{k+1} = \nu$ and $k < n$.

In fact, the converse is also true: any set of this form can be written $S_{\lambda^T a}$ for some λ in \mathbb{R}^n . To see this, we simply choose λ so that $\lambda^T a$ has zeroes s_1, s_2, \dots, s_k in the interior of S and any remaining zeroes outside S (and if necessary replace λ by $-\lambda$). Clearly a similar technique applies to the case where $S = [-\pi, \pi]$ and $a(s) = (1, \cos s, \sin s, \cos 2s, \sin 2s, \dots)^T$.

2. THE MAIN RESULT

We suppose that (S, ρ) is a fixed finite measure space. Our quantification of the superresolution phenomenon revolves around the following idea. We define, for any nonnegative function f in $L_1(S)$, the constant

$$\beta_f = \limsup_{\delta \downarrow 0} \delta^{-1} \rho\{s \in S | f(s) \leq \delta\}. \quad (2.1)$$

The constant β_f is finite exactly when the measure of the set $\{s | f(s) \leq \delta\}$ does not grow faster than linearly for small positive δ . For example, if the set S is a compact, nonsingleton, real interval with Lebesgue measure, then $\beta_{|g|}$ will be finite for any continuously differentiable function g on S with only a finite number of zeroes, all simple.

Our aim in this section is to prove the following result.

THEOREM 2.2. *Suppose that the functions a_1, a_2, \dots, a_n lie in $L_1(S)$, and that $\bar{x} = \chi_{S, \lambda^T a}$ for some λ in \mathbb{R}^n with $\lambda^T a \neq 0$ a.e. Then for any sequence of measurable functions $x_r: S \rightarrow [0, 1]$, if $\int a x_r \rightarrow \int a \bar{x}$ it follows that $\|x_r - \bar{x}\|_1 \rightarrow 0$.*

Suppose further that the constant $\beta_{|\lambda^T a|}$ defined by (2.1) is finite. Then for any norm $\|\cdot\|$ on \mathbb{R}^n the following error estimate holds:

$$\|\bar{x} - x_r\|_1 \leq K(r) \left\| \int (\bar{x} - x_r) a \right\|^{1/2}, \quad (2.3)$$

where the function K satisfies

$$K(r) \sim (2\beta_{|\lambda^T a|} \|\lambda\|_*)^{1/2} \quad \text{as } r \rightarrow \infty$$

(and $\|\cdot\|_*$ is the dual norm).

The proof will depend on a sequence of lemmas. For any function f in $L_1(S)$ we define a function $\Lambda_f: \mathbb{R} \rightarrow (-\infty, +\infty]$ by

$$\Lambda_f(\varepsilon) = \inf \left\{ \int f y \mid 0 \leq y \leq 1 \text{ a.e., } \int y \geq \varepsilon \right\}. \quad (2.4)$$

For u in \mathbb{R} we write $u^+ = \max\{u, 0\}$.

LEMMA 2.5. *The function Λ_f is convex, nondecreasing, and continuous on its domain, $(-\infty, \rho(S)]$. The infimum in (2.4) is attained for any ε in $(-\infty, \rho(S)]$. For any ε in \mathbb{R} ,*

$$\Lambda_f(\varepsilon) \geq \sup \left\{ \gamma \varepsilon - \int (\gamma - f)^+ \mid 0 \leq \gamma \in \mathbb{R} \right\}. \quad (2.6)$$

Proof. The function Λ_f is just the value function of the convex program on the right-hand side of (2.4). Convexity is easy and standard to check, while attainment and lower semicontinuity are consequences of the weak-star compactness of $\{y \in L_\infty | 0 \leq y \leq 1 \text{ a.e.}\}$. The inequality (2.6) is simply the weak duality inequality for problem (2.4), and is easily checked directly. ■

In fact, a standard Fenchel duality result applied to the right-hand side of (2.6) shows that (2.6) holds with equality for all ε in \mathbb{R} (see for example [13]). Furthermore, the supremum in (2.6) is attained, at least for $\varepsilon < \rho(S)$, by the results in [2]. We shall not need these stronger duality results.

The next result is the key tool in our general convergence analysis.

LEMMA 2.7. *Suppose that $f > 0$ a.e. Then $\Lambda_f(\varepsilon) > 0$ for all $\varepsilon > 0$, and if $\Lambda_f(\varepsilon_r) \rightarrow 0$ for some sequence $\varepsilon_r > 0$ then $\varepsilon_r \rightarrow 0$.*

Proof. The first statement is a consequence of the attainment in (2.4). Now since $\varepsilon_r \in [0, \rho(S)]$ for all large r , if $\varepsilon_r \rightarrow 0$ then some subsequence $\varepsilon_{r'}$ has limit $\varepsilon > 0$, whence by continuity $\Lambda_f(\varepsilon_{r'}) \rightarrow \Lambda_f(\varepsilon) > 0$. This is a contradiction. ■

This result can sometimes be quantified.

LEMMA 2.8. *If $f > 0$ a.e. then*

$$\limsup_{\delta \downarrow 0} \delta^{-2} \int (\delta - f)^+ \leq \beta_f / 2.$$

Proof. By Fubini's theorem,

$$\begin{aligned} \int (\delta - f)^+ &= \int_{s \in S} \int_{t \in \mathbb{R}} \chi_{\{0 < f(s) \leq \delta, 0 \leq t \leq \delta - f(s)\}} dt d\rho \\ &= \int_{t=0}^{\delta} \rho\{s \in S | f(s) \leq \delta - t\} dt \\ &= \int_0^{\delta} \rho\{s \in S | f(s) \leq r\} dr. \end{aligned}$$

For any $\varepsilon > 0$,

$$r^{-1} \rho\{s \in S | f(s) \leq r\} \leq \beta_f + \varepsilon, \quad \text{for all small } r > 0,$$

so for small $\delta > 0$,

$$\delta^{-2} \int (\delta - f)^+ \leq \delta^{-2} \int_0^{\delta} (\beta_f + \varepsilon)r dr = (\beta_f + \varepsilon) / 2.$$

The result follows. ■

LEMMA 2.9. *Suppose that the function f lies in $L_1(S)$ with $f > 0$ a.e., and β_f defined by (2.1) finite. Then*

$$\liminf_{\varepsilon \downarrow 0} \varepsilon^{-2} \Lambda_f(\varepsilon) \geq (2\beta_f)^{-1}.$$

Proof. For any $k > 0$, setting $\gamma = k\varepsilon$ in (2.6) shows that

$$\begin{aligned} \liminf_{\varepsilon \downarrow 0} \varepsilon^{-2} \Lambda_f(\varepsilon) &\geq \liminf_{\varepsilon \downarrow 0} \varepsilon^{-2} \left\{ k\varepsilon^2 - \int (k\varepsilon - f)^+ \right\} \\ &= k - k^2 \limsup_{\delta \downarrow 0} \delta^{-2} \int (\delta - f)^+ \\ &\geq k - \beta_f k^2 / 2, \end{aligned}$$

by the previous lemma. Setting $k = \beta_f^{-1}$ gives the result. ■

For any function g in $L_1(S)$, define $S_g = \{s \in S | g(s) > 0\}$.

LEMMA 2.10. *For any measurable functions g in $L_1(S)$ and $x: S \rightarrow [0, 1]$,*

$$\int (\chi_{S_g} - x)g \geq \Lambda_{|g|}(\|\chi_{S_g} - x\|_1).$$

Proof. Choose $y = |\chi_{S_g} - x|$ in (2.4). Then $0 \leq y \leq 1$ a.e. and $\int y = \|\chi_{S_g} - x\|_1$. Furthermore,

$$\begin{aligned} \int |g|y &= \int |g| |\chi_{S_g} - x| \\ &= \int_{g>0} |g| |1 - x| + \int_{g<0} |g| |-x| \\ &= \int_{g>0} (1 - x)g + \int_{g<0} x(-g) \\ &= \int (\chi_{S_g} - x)g. \end{aligned}$$

The result follows. ■

We can now prove the main result.

Proof of Theorem 2.2. By the previous lemma,

$$0 \leq \Lambda_{|\lambda^T a|}(\|\bar{x} - x_r\|_1) \leq \int (\bar{x} - x_r) \lambda^T a \rightarrow 0, \tag{2.11}$$

so $\|x - x_r\|_1 \rightarrow 0$ by Lemma 2.4. To see the second part, observe that

$$\|\lambda\|_* \left\| \int (\bar{x} - x_r) a \right\| \geq \int (\bar{x} - x_r) \lambda^T a \geq \Lambda_{|\lambda^T a|}(\|\bar{x} - x_r\|_1).$$

Without loss of generality, for all $r, x_r \neq \bar{x}$, and hence $\int (\bar{x} - x_r) a \neq 0$, by Lemma 2.4. Then by Lemma 2.9,

$$\liminf_{r \rightarrow \infty} \|\bar{x} - x_r\|_1^{-2} \|\lambda\|_* \left\| \int (\bar{x} - x_r) a \right\| \geq (2\beta_{|\lambda^T a|})^{-1},$$

and the result follows. ■

Note that the proof of the first part of the theorem in fact only needs the assumption that $\int \lambda^T a x_r \rightarrow \int \lambda^T a \bar{x}$. An equivalent way to state this part of the result is then the following: for any function g in $L^1(S)$ with $g \neq 0$ a.e., and any sequence of measurable functions $x_r: S \rightarrow [0, 1]$, if $\int g x_r \rightarrow \int g_+$ then it follows that $\|x_r - \chi_{S_g}\|_1 \rightarrow 0$. This can also be seen by a more direct argument.

EXAMPLE. Suppose in Theorem 2.2 that S is a compact interval of \mathbb{R} (not a singleton) with Lebesgue measure, and that $\lambda^T a$ is continuously differentiable on S with zeroes s_1, s_2, \dots, s_m ($m > 0$), all simple. A straightforward calculation shows that

$$\beta_{|\lambda^T a|} = \sum_{i=1}^m \alpha_i |(\lambda^T a)'(s_i)|^{-1},$$

where $\alpha_i = 2$ if s_i lies in the interior of S and $\alpha_i = 1$ otherwise. Hence we obtain the error estimate

$$\limsup_{r \rightarrow \infty} \|\bar{x} - x_r\|_1 \left\| \int (\bar{x} - x_r) a \right\|^{-1/2} \leq \left(2\|\lambda\|_* \sum_{i=1}^m \alpha_i |(\lambda^T a)'(s_i)|^{-1} \right)^{1/2}.$$

We can compare this inequality with the example at the end of Section 1, by setting $\lambda = (1, -2)^T$, so $s_1 = \frac{1}{2}$ and

$$\|\bar{x} - x_\varepsilon\|_1 \left\| \int (\bar{x} - x_\varepsilon) a \right\|_1^{-1/2} = 2 = \left(2\|\lambda\|_\infty \alpha_1 |(\lambda^T a)'(s_1)|^{-1} \right)^{1/2},$$

whence the error bound is tight.

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