LINEAR ALGEBRA
AND ITS
APPLICATIONS

# Quadratic expansions of spectral functions ${ }^{\text {N }}$ 

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#### Abstract

A function, $F$, on the space of $n \times n$ real symmetric matrices is called spectral if it depends only on the eigenvalues of its argument, that is $F(A)=F\left(U A U^{\mathrm{T}}\right)$ for every orthogonal $U$ and symmetric $A$ in its domain. Spectral functions are in one-to-one correspondence with the symmetric functions on $\mathbb{R}^{n}$ : those that are invariant under arbitrary swapping of their arguments. In this paper, we show that a spectral function has a quadratic expansion around a point $A$ if and only if its corresponding symmetric function has quadratic expansion around $\lambda(A)$ (the vector of eigenvalues). We also give a concise and easy to use formula for the 'Hessian' of the spectral function. In the case of convex functions we show that a positive definite 'Hessian' of $f$ implies positive definiteness of the 'Hessian' of $F$. © 2002 Elsevier Science Inc. All rights reserved.


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## 1. Introduction

In this work, we investigate a property of functions $F$ on the real vector space of symmetric matrices that are orthogonally invariant:
$F\left(U^{\mathrm{T}} A U\right)=F(A) \quad$ for all $A$ symmetric and $U$ orthogonal.
Every such function can be decomposed as

[^0]$$
F(A)=(f \circ \lambda)(A),
$$
where $\lambda$ is the map that gives the eigenvalues of the matrix $A$ and $f$ is a permutation invariant function. (See Section 2 for more details.) We call such functions $F$ spectral functions (or just functions of eigenvalues) because de facto they depend only on the spectrum of the operator $A$. (All the results we present in this paper have parallel versions for unitarily invariant functions on the space of Hermitian matrices, with essentially identical proofs.)

In the past, such functions have been of interest for example to people working in the field of quantum mechanics [8,15]. With developments in semidefinite programming, functions of eigenvalues became an inseparable part of mathematical programming. Optimization problems now often involve spectral functions like $\log \operatorname{det}(A)$, the largest eigenvalue of the matrix argument $A$, or the constraint that $A$ must be positive definite and so on. Remarkably, many properties of the function $f$ are inherited by the spectral function $F$. For example, this holds for differentiability and convexity [9], various types of generalized differentiability [10], analyticity [20], various second-order properties [17-19], and so on. Second-order properties of matrix functions are of great interest for optimization because the application of Newton's method and recent interior point methods [12] requires that we know the second-order behaviour of the functions involved in the mathematical model.

The standard reference for the behaviour of the eigenvalues of a matrix subject to perturbations in a particular direction is Ref. [7]. Second-order properties of eigenvalue value functions in a particular direction are derived in [19]. What interests us in this paper is a second-order property of spectral functions subject to perturbation by an arbitrary matrix. Analytical properties subject to matrix perturbations are discussed in [20]. In some sense our result about spectral functions having quadratic expansions lies between the results in [9] and the results in [20]. In a parallel paper [11], we show that $F$ is twice differentiable if and only if $f$ is, and also that $F \in \mathscr{C} \mathscr{C}^{2}$ if and only if $f \in \mathscr{C}^{2}$.

Many functions have quadratic expansions. For example a theorem of Alexandrov [1] states that every finite, convex function on an open subset of $\mathbb{R}^{n}$ has quadratic expansion at almost every point. Notice that it is not necessary for a function to be twice differentiable in order to have quadratic expansion. For example, the function

$$
f(x)= \begin{cases}x^{3} \sin (1 / x) & \text { if } x \neq 0 \\ 0 & \text { if } x=0\end{cases}
$$

has quadratic expansion around $x=0$ but is not twice differentiable there. On the other hand being twice differentiable at $x$ implies having quadratic expansion at $x$.

## 2. Notation and definitions

Let $S^{n}$ be the Euclidean space of all $n \times n$ symmetric matrices with inner product $\langle A, B\rangle=\operatorname{tr}(A B)$, and for $A \in S^{n}$ denote by $\lambda(A)^{\mathrm{T}}=\left(\lambda_{1}(A), \ldots, \lambda_{n}(A)\right)$ the vector of its eigenvalues ordered in nonincreasing order. (All vectors in this paper
are assumed to be column vectors unless stated otherwise and $A^{i j}$ will denote the $(i, j)$ th entry of the matrix $A$.) For any vector $x$ in $\mathbb{R}^{n}$, $\operatorname{Diag} x$ will denote the diagonal matrix with the vector $x$ on the main diagonal, and $\bar{x}$ will denote the vector with the same entries as $x$ ordered in nonincreasing order, that is $\bar{x}_{1} \geqslant \bar{x}_{2} \geqslant \cdots \geqslant \bar{x}_{n}$. Let $\mathbb{R}_{\downarrow}^{n}$ denote the convex cone of all vectors $x$ in $\mathbb{R}^{n}$ such that $x_{1} \geqslant x_{2} \geqslant \cdots \geqslant x_{n}$. The following definition explains the property that interests us in this paper.

Definition 2.1. We say that a function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ has a weak quadratic expansion at the point $x$ if there exist a vector $\nabla f(x)$ and a symmetric matrix $\nabla^{2} f(x)$ such that for small $h \in \mathbb{R}^{n}$

$$
f(x+h)=f(x)+\langle\nabla f(x), h\rangle+\frac{1}{2}\left\langle h, \nabla^{2} f(x) h\right\rangle+\mathrm{o}\left(\|h\|^{2}\right),
$$

and a strong quadratic expansion at the point $x$ if

$$
f(x+h)=f(x)+\langle\nabla f(x), h\rangle+\frac{1}{2}\left\langle h, \nabla^{2} f(x) h\right\rangle+\mathrm{O}\left(\|h\|^{3}\right) .
$$

The vector $h$ is called a perturbation vector.

A few comments on this definition are necessary. Clearly having a strong quadratic expansion implies a weak quadratic expansion. We want to alert the reader that a function may not be twice differentiable at the point $x$ but still possesses a strong quadratic expansion at this point. (See the example at the end of Section 1.) It is clear that if the function has quadratic expansion at the point $x$, then it is differentiable at $x$ and its gradient is the vector $\nabla f(x)$ from the above definition. If the function has a weak quadratic expansion, then there is a unique vector $\nabla f(x)$ and a unique symmetric matrix $\nabla^{2} f(x)$ (the Hessian) for which the expansion holds. There is a slight abuse of notation when we call $\nabla^{2} f(x)$ the Hessian of $f$, but no danger of confusion exists, at least when $f$ is twice continuously differentiable around $x$, because then consideration of the Taylor expansion shows that the symmetric matrix $\nabla^{2} f(x)$ is exactly the Hessian. Finally, another way to write the quadratic expansion of a function $f$, consistent with [12], is

$$
\begin{equation*}
f(x+h)=f(x)+\nabla f(x)[h]+\frac{1}{2} \nabla^{2} f(x)[h, h]+\mathrm{O}\left(\|h\|^{3}\right) . \tag{1}
\end{equation*}
$$

We give some less common notation which will be used throughout the paper. These are taken directly from [19]. We are interested in quadratic expansions of matrix functions $f \circ \lambda$ around a matrix $A$. (In all of our preliminary results the matrix $A$ will be a diagonal matrix, Diag $\mu$.) Let $H \in S^{n}$ be the perturbation matrix. Fix a number $m \in \mathbb{N}, 1 \leqslant m \leqslant n$ and let the "block structure" of the vector $\lambda(A)$ be given by

$$
\begin{aligned}
\lambda_{1}(A) & =\cdots=\lambda_{k_{1}}(A)>\cdots>\lambda_{k_{l-1}+1}(A)=\cdots=\lambda_{m}(A) \\
& =\cdots=\lambda_{k_{l}}(A)>\cdots \lambda_{k_{r}}(A) \quad\left(k_{0}=0, \quad k_{r}=n\right) .
\end{aligned}
$$

That is, the eigenvalue $\lambda_{m}(A)$ lies in the $l$ th block of equal eigenvalues. Let $X=$ $\left[x^{1}, \ldots, x^{n}\right]$ be an orthogonal matrix such that $X^{\mathrm{T}} A X=\operatorname{Diag} \lambda(A)$ (so $x^{i}$ is a unit eigenvector corresponding to $\left.\lambda_{i}(A)\right)$ and let

$$
X_{l}=\left[x^{k_{l-1}+1}, \ldots, x^{k_{l}}\right] .
$$

Let $U_{l}=\left[v^{1}, \ldots, v^{k_{l}-k_{l-1}}\right]$ be a $\left(k_{l}-k_{l-1}\right) \times\left(k_{l}-k_{l-1}\right)$ orthogonal matrix such that

$$
U_{l}^{\mathrm{T}}\left(X_{l}^{\mathrm{T}} H X_{l}\right) U_{l}=\operatorname{Diag} \lambda\left(X_{l}^{\mathrm{T}} H X_{l}\right)
$$

Set $H_{l}:=X_{l}^{\mathrm{T}} H X_{l}, \quad 1 \leqslant l \leqslant r$, and suppose

$$
\begin{aligned}
\lambda_{1}\left(H_{l}\right) & =\cdots=\lambda_{t_{l, 1}}\left(H_{l}\right)>\cdots>\lambda_{t_{l, j-1}+1}\left(H_{l}\right)=\cdots \lambda_{m-k_{l-1}}\left(H_{l}\right) \cdots \\
& =\lambda_{t_{l, j}}\left(H_{l}\right)>\cdots \lambda_{t_{l, s_{l}}}\left(H_{l}\right) \quad\left(t_{l, 0}=0, t_{l, s_{l}}=k_{l}-k_{l-1}\right) .
\end{aligned}
$$

Finally let

$$
U_{l, j}=\left[v^{t_{l, j-1}+1}, \ldots, v^{t_{l, j}}\right] .
$$

We should point out that $X_{l}=X_{l}(A, m)$, and $U_{l, j}=U_{l, j}(A, H, X, m)$ but from now on we will write only $X_{l}$ and $U_{l, j}$ to simplify the notation.

By $A^{\dagger}$ we denote the Moore-Penrose generalized inverse of the matrix $A$. For more information on the topic, see [16, p. 102]. But for our needs, because we will be working only on symmetric matrices, the concept can be quickly explained. First, ( $\operatorname{Diag} x)_{i, j}^{\dagger}$ is equal to $1 / x_{i}$ if $i=j$ and $x_{i} \neq 0$, and is 0 otherwise. Second, for any orthogonal matrix $U$ that diagonalizes $A$, we have $A^{\dagger}=\left(U \operatorname{Diag} \lambda(A) U^{\mathrm{T}}\right)^{\dagger}:=$ $U(\operatorname{Diag} \lambda(A))^{\dagger} U^{\mathrm{T}}$.

## 3. Supporting results

Let $A$ be in $S^{n}$ and its eigenvalues have the following block structure

$$
\lambda_{1}(A)=\cdots=\lambda_{k_{1}}(A)>\lambda_{k_{1}+1}(A)=\cdots=\lambda_{k_{2}}(A)>\lambda_{k_{2}+1}(A) \cdots \lambda_{k_{r}}(A),
$$

where $k_{r}=n$. All our results rest on the fact that for every block $l=1, \ldots, r$, the following two functions have quadratic expansion at $A$ :

$$
\begin{aligned}
\sigma_{k_{l}}(\cdot) & =\sum_{i=1}^{k_{l}} \lambda_{i}(\cdot), \\
S_{l}(\cdot) & =\sum_{i=k_{l-1}+1}^{k_{l}} \lambda_{i}^{2}(\cdot) .
\end{aligned}
$$

We are going to give three independent justifications of this fact and two of them will show that these functions are even analytic at $A$. We call a function of several real variables analytic at a point if it is given locally by the sum of a power series expansion: the term holomorphic is the corresponding complex variable notion. For every index $m=1, \ldots, n$ and every block $l=1, \ldots, r$ define the functions

$$
\begin{aligned}
& f_{m}(x)=\sum_{i=1}^{m} \bar{x}_{i}, \\
& s_{l}(x)=\sum_{i=k_{l-1}+1}^{k_{l}} \bar{x}_{i}^{2} .
\end{aligned}
$$

The function $f_{m}$ is the sum of the $m$ largest entries in $x$. The functions $f_{m}$ and $s_{l}(x)$ are symmetric. (A function $f$ is symmetric if $f(x)=f(P x)$ for any permutation matrix $P$. We denote the set of all $n \times n$ permutation matrices by $P(n)$.) It is clear that if the point $x$ is such that $\bar{x}_{m}>\bar{x}_{m+1}$, then $f_{m}$ is linear near $x$ (by which we mean that it agrees with some linear function on a neighbourhood of $x$ ). In particular, for points $x$ near $\lambda(A)$ the functions $f_{k_{l}}(x)$ and $s_{l}(x)$ are both polynomials in the entries of $x$. Notice also that

$$
\begin{aligned}
& \sigma_{k_{l}}(\cdot)=\left(f_{k_{l}} \circ \lambda\right)(\cdot), \\
& S_{l}(\cdot)=\left(s_{l} \circ \lambda\right)(\cdot) .
\end{aligned}
$$

The first justification comes from the following result in [11, Theorem 3.3].
Theorem 3.1. The symmetric function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is twice continuously differentiable around the point $\lambda(A)$ if and only if $f \circ \lambda$ is twice continuously differentiable around the point $A$.

Since $f_{k_{l}}$ is a symmetric function that is twice continuously differentiable around $\lambda(A)$ (being locally linear), the theorem above shows that $\sigma_{k_{l}}$ is twice continuously differentiable around $A$. A similar argument applies to $S_{l}$.

The second justification is from [20, Theorem 2.1].
Theorem 3.2. Suppose $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a function analytic at the point $\lambda(A)$ for some $A$ in $S^{n}$. Suppose also $f(P x)=f(x)$ for every permutation matrix $P$ for which $P \lambda(A)=\lambda(A)$. Then the function $f \circ \lambda$ is analytic at $A$.

As before, we know that the function $f_{k_{l}}$ is symmetric, and analytic, being locally linear, so the theorem above shows that $\sigma_{k_{l}}$ is analytic at $A$. The argument for $S_{l}$ is similar.

For the third justification, we use the standard algebraic fact that every symmetric polynomial in several variables can be written as a polynomial in the elementary symmetric functions. We also use the following result [2]. Until the end of this section only, $\lambda_{i}(X)$ will denote an arbitrary eigenvalue of a matrix $X$, not necessarily the $i$ th largest one.

Theorem 3.3 (Arnold [2]). Suppose that $A \in \mathbb{C}^{n \times n}$ has $q$ eigenvalues $\lambda_{1}(A), \ldots$, $\lambda_{q}(A)$ (counting multiplicities) in an open set $\Omega \subset \mathbb{C}$, and the remaining $n-q$
eigenvalues not in the closure of $\Omega$. Then there is a neighbourhood $\Delta$ of $A$ and holomorphic mappings $S: \Delta \rightarrow \mathbb{C}^{q \times q}$ and $T: \Delta \rightarrow \mathbb{C}^{(n-q) \times(n-q)}$ such that for all matrices $X \in \Delta$,

$$
X \text { is similar to }\left(\begin{array}{cc}
S(X) & 0 \\
0 & T(X)
\end{array}\right) \text {, }
$$

and $S(A)$ has eigenvalues $\lambda_{1}(A), \ldots, \lambda_{q}(A)$.
Using Arnold's theorem we can prove that in fact the functions $\sigma_{k_{l}}$ and $S_{l}$ are holomorphic around $A$.

Theorem 3.4. With the assumptions of Arnold's Theorem, for every symmetric polynomial $p: \mathbb{C}^{q} \rightarrow \mathbb{C}$, the function $(p \circ \lambda)(S(X))$ is holomorphic around $A$.

Proof. It suffices to prove the theorem in the case of an elementary symmetric polynomial, since any symmetric polynomial is a polynomial in the elementary symmetric functions (see for example [6, Proposition V.2.20.(ii)]). By continuity of the eigenvalues, any matrix $X$ close to $A$ has $q$ eigenvalues in $\Omega$ and the remainder outside its closure. Thus for every $i=1, \ldots, n$ we can define a function $\lambda_{i}: \mathbb{C}^{n \times n} \rightarrow \mathbb{C}$ such that for matrices $X$ near $A,\left\{\lambda_{i}(X)\right\}_{i=1}^{n}$ are the eigenvalues of $X$, and $\left\{\lambda_{i}(X)\right\}_{i=1}^{q}$ are the eigenvalues of $S(X)$. So the elementary symmetric functions of $\lambda_{1}(X), \ldots$, $\lambda_{q}(X)$ are the coefficients of the characteristic polynomial $\operatorname{det}(\lambda I-S(X))$ (as can be seen by writing the characteristic polynomial as a product of linear factors). Since $S(\cdot)$ is holomorphic, so, for any fixed $\lambda$, is the characteristic polynomial $\operatorname{det}(\lambda I-$ $S(\cdot))$, and hence so is each of its coefficients, as required.

To deduce the results we need by this approach, we could for example apply it with the set

$$
\Omega=\left\{z: \operatorname{Re} z>\frac{1}{2}\left(\lambda_{k_{l}}(A)+\lambda_{k_{l}+1}(A)\right)\right\} .
$$

Then the eigenvalues in $\Omega$ are exactly the largest $k_{l}$, so $\sigma_{k_{l}}(X)=\operatorname{trace}(S(X))$ for all matrices $X$ close to $A$. Thus $\sigma_{k_{l}}$ is holomorphic near $A$. A similar argument applies to $S_{l}$.

## 4. Quadratic expansion of spectral functions

Our goal in this section is to prove the main result of the paper.
Theorem 4.1 (quadratic expansion). The symmetric function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ has a strong quadratic expansion at the point $x=\lambda(Y)\left(Y \in S^{n}\right)$ if and only if $f \circ \lambda$ has a strong quadratic expansion at $Y$, and in this case

$$
\nabla(f \circ \lambda)(Y)[H]=\operatorname{tr}(\tilde{H} \operatorname{Diag} \nabla f(\mu)),
$$

$$
\begin{aligned}
\nabla^{2}(f \circ \lambda)(Y)[H, H]= & \sum_{p, q=1}^{n} \tilde{h}_{p p} f_{p q}^{\prime \prime}(\mu) \tilde{h}_{q q}+\sum_{\substack{p \neq q \\
\mu_{p}=\mu_{q}}} b_{p} \tilde{h}_{p q}^{2} \\
& +\sum_{p, q: \mu_{p} \neq \mu_{q}} \frac{f_{p}^{\prime}(\mu)-f_{q}^{\prime}(\mu)}{\mu_{p}-\mu_{q}} \tilde{h}_{p q}^{2}
\end{aligned}
$$

where $\mu=\lambda(Y), \tilde{H}=U^{T} \mathrm{HU}, Y=U(\operatorname{Diag} \mu) U^{\mathrm{T}}, U$ orthogonal, and the vector $b$ is defined in Lemma 4.8. The analogous result holds for the weak quadratic expansion.

We will only discuss about the strong quadratic expansions in this paper: the development for the weak version is analogous. We need the following result from [19, Remark 6].

Lemma 4.2. Every eigenvalue, $\lambda_{m}(Y)$, of a symmetric matrix, $Y$, has the following expansion in the direction of the symmetric matrix $H$ :

$$
\begin{align*}
\lambda_{m}(Y+t H)= & \lambda_{m}(Y)+t \lambda_{m-k_{l-1}}\left(X_{l}^{\mathrm{T}} H X_{l}\right) \\
& +\frac{1}{2} t^{2} \lambda_{m-k_{l-1}-t_{l, j-1}}\left(2 U_{l, j}^{\mathrm{T}} X_{l}^{\mathrm{T}} H\left(\lambda_{m}(Y) I-Y\right)^{\dagger} H X_{l} U_{l, j}\right) \\
& +\mathrm{O}\left(t^{3}\right), \tag{2}
\end{align*}
$$

where the meaning of $X_{l}$ and $U_{l, j}$ is explained in the previous section.
Definition 4.3 [10]. We say that the vector $\mu \in \mathbb{R}^{n}$ block refines the vector $b \in \mathbb{R}^{n}$ if $\mu_{i}=\mu_{j}$ implies $b_{i}=b_{j}$ for all $i, j \in\{1, \ldots, n\}$. Equivalently

$$
P \mu=\mu \Rightarrow P b=b \text { for all } P \in P(n) .
$$

Next we give a technical lemma that will allow us to cut down on the notation.
Lemma 4.4. Let $\mu \in \mathbb{R}^{n}$ be such that

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{0}=0, k_{r}=n\right),
$$

and let the vector $b \in \mathbb{R}^{n}$ be block refined by $\mu$. Let $H \in S^{n}$ be an arbitrary matrix and $X_{i}=\left[e^{k_{i-1}+1}, \ldots, e^{k_{i}}\right]$ for every $i=1, \ldots, r$. Then we have the identities

$$
\begin{aligned}
& \left\langle H, b_{k_{l}}\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} X_{l}^{\mathrm{T}}\right\rangle=\sum_{p=k_{l-1}+1}^{k_{l}} \sum_{\substack{q=1 \\
\mu_{q} \neq \mu_{p}}}^{n} \frac{b_{p}}{\mu_{p}-\mu_{q}} h_{p q}^{2}, \\
& \left\langle H, \sum_{i=1}^{r} b_{k_{i}}\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} X_{i}^{\mathrm{T}}\right\rangle=\sum_{p, q: \mu_{p}>\mu_{q}} \frac{b_{p}-b_{q}}{\mu_{p}-\mu_{q}} h_{p q}^{2} .
\end{aligned}
$$

Proof. The product $X_{i} X_{i}^{\mathrm{T}}$ is an $n \times n$ matrix with zero entries, except $\left(X_{l} X_{l}^{\mathrm{T}}\right)^{p, p}=$ 1 for $p=k_{i-1}+1, \ldots, k_{i}$. Thus the columns of $H X_{i} X_{i}^{\mathrm{T}}$ are zero vectors, except the columns with indices $p=k_{i-1}+1, \ldots, k_{i}$ which are equal to the corresponding columns of $H$. The matrix $b_{k_{i}}\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger}$ is equal to

$$
\operatorname{Diag}\left(\frac{b_{k_{i}}}{\mu_{k_{i}}-\mu_{1}}, \ldots, \frac{b_{k_{i}}}{\mu_{k_{i}}-\mu_{k_{i-1}}}, 0, \ldots, 0, \frac{b_{k_{i}}}{\mu_{k_{i}}-\mu_{k_{i}+1}}, \ldots, \frac{b_{k_{i}}}{\mu_{k_{i}}-\mu_{k_{r}}}\right)
$$

Consequently we have

$$
\begin{aligned}
& \left\langle H, b_{k_{i}}\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} X_{i}^{\mathrm{T}}\right\rangle \\
& \quad=\sum_{p=k_{i-1}+1}^{k_{i}} \sum_{\substack{q=1 \\
\mu_{q} \neq \mu_{p}}}^{n} \frac{b_{k_{i}}}{\mu_{k_{i}}-\mu_{q}} h_{p q}^{2} \\
& \quad=\sum_{p=k_{i-1}+1}^{k_{i}}\left(\sum_{q=1}^{k_{i-1}} \frac{-b_{p}}{\mu_{q}-\mu_{p}} h_{p q}^{2}+\sum_{q=k_{i}+1}^{n} \frac{b_{p}}{\mu_{p}-\mu_{q}} h_{p q}^{2}\right) r .
\end{aligned}
$$

and the first identity follows. The second identity follows by summing over $i$.
Our first goal is to find a formula for the Hessian of $\sigma_{k_{l}}, 1 \leqslant l \leqslant r$. We denote the standard basis in $\mathbb{R}^{n}$ by $e^{1}, e^{2}, \ldots, e^{n}$. As a byproduct in the following lemma we derive a formula for the derivative of the function $\sigma_{k_{l}}$ at the point $\operatorname{Diag} \mu$. This formula had appeared many times in the literature: see for example Corollary 3.10 in [5], or the proof of Corollary 3.3 in [9]. The expression for the Hessian is also known, see Formula (3.28) in [13]. Here we present yet another way of deriving it.

Lemma 4.5. For a real vector $\mu \in \mathbb{R}^{n}$, such that

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{0}=0, k_{r}=n\right)
$$

the function

$$
\sigma_{k_{l}}(\cdot)=\sum_{i=1}^{k_{l}} \lambda_{i}(\cdot)
$$

is analytic at the matrix $\operatorname{Diag} \mu$ with first and second derivatives satisfying

$$
\begin{aligned}
& \nabla \sigma_{k_{l}}(\operatorname{Diag} \mu)[H]=\operatorname{tr}\left(H \operatorname{Diag} \sum_{i=1}^{k_{l}} e^{i}\right) \\
& \nabla^{2} \sigma_{k_{l}}(\operatorname{Diag} \mu)[H, H]=2 \sum_{p=1}^{k_{l}} \sum_{q=k_{l}+1}^{n} \frac{h_{q p}^{2}}{\mu_{p}-\mu_{q}}
\end{aligned}
$$

$$
=\operatorname{tr}\left(2 H \sum_{i=1}^{l}\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} X_{i}^{\mathrm{T}}\right)
$$

where $X_{i}=\left[e^{k_{i-1}+1}, \ldots, e^{k_{i}}\right]$.
Proof. The fact that $\sigma_{k_{l}}$ is analytic at the point $\operatorname{Diag} \mu$ follows from Section 3. Next, summing Eqs. (2) with $Y=\operatorname{Diag} \mu$, for $m=1, \ldots, k_{l}$ and using the fact that $X=I$ (so $X_{i}=\left[e^{k_{i-1}+1}, \ldots, e^{k_{i}}\right]$ ), we get

$$
\begin{aligned}
& \sigma_{k_{l}}(\operatorname{Diag} \mu+t H) \\
& =\sum_{i=1}^{k_{l}} \lambda_{i}(\operatorname{Diag} \mu+t H) \\
& =\sigma_{k_{l}}(\operatorname{Diag} \mu)+t \sum_{i=1}^{l} \operatorname{tr}\left(X_{i}^{\mathrm{T}} H X_{i}\right) \\
& \quad+\frac{1}{2} t^{2} \sum_{i=1}^{l} \sum_{j=1}^{s_{i}} \sum_{v=1}^{t_{i, j}-t_{i, j-1}} \lambda_{v}\left(2 U_{i, j}^{\mathrm{T}} X_{i}^{\mathrm{T}} H\left(\mu_{k} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} U_{i, j}\right)+\mathrm{O}\left(t^{3}\right) \\
& = \\
& \quad \sigma_{k_{l}}(\operatorname{Diag} \mu)+t\left\langle\operatorname{Diag} \sum_{i=1}^{k_{l}} e^{i}, H\right\rangle \\
& \quad+\frac{1}{2} t^{2} \sum_{i=1}^{l} \sum_{j=1}^{s_{i}} \operatorname{tr}\left(2 U_{i, j}^{\mathrm{T}} X_{i}^{\mathrm{T}} H\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} U_{i, j}\right)+\mathrm{O}\left(t^{3}\right)
\end{aligned}
$$

We concentrate on the double sum above.

$$
\begin{aligned}
& \sum_{i=1}^{l} \sum_{j=1}^{s_{i}} \operatorname{tr}\left(2 U_{i, j}^{\mathrm{T}} X_{i}^{\mathrm{T}} H\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} U_{i, j}\right) \\
& \quad=\sum_{i=1}^{l} \sum_{j=1}^{s_{i}} \operatorname{tr}\left(2 X_{i}^{\mathrm{T}} H\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} U_{i, j} U_{i, j}^{\mathrm{T}}\right) \\
& \quad=\sum_{i=1}^{l} \operatorname{tr}\left(2 X_{i}^{\mathrm{T}} H\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} \sum_{j=1}^{s_{i}} U_{i, j} U_{i, j}^{\mathrm{T}}\right)
\end{aligned}
$$

$$
\begin{aligned}
& =\sum_{i=1}^{l} \operatorname{tr}\left(2 X_{i}^{\mathrm{T}} H\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i}\right) \\
& =\operatorname{tr}\left(2 H \sum_{i=1}^{l}\left(\mu_{k_{i}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{i} X_{i}^{\mathrm{T}}\right) \\
& =\sum_{p=1}^{k_{l}} \sum_{\substack{q=1 \\
\mu_{q} \neq \mu_{p}}}^{n} \frac{2}{\mu_{p}-\mu_{q}} h_{q p}^{2} \\
& =2 \sum_{p=1}^{k_{l}} \sum_{q=k_{l}+1}^{n} \frac{h_{q p}^{2}}{\mu_{p}-\mu_{q}} .
\end{aligned}
$$

The next to last equality follows from Lemma 4.4 , with $b=(2, \ldots, 2)$, and the last equality after cancelling all terms with opposite signs. By the uniqueness of the Hessian in the quadratic expansion of a function, we conclude that the last expression above must be indeed the Hessian.

Note 4.6. Notice that the Hessian above is a positive semidefinite quadratic form. This is not a surprise since a well-known result of Fan [4] says that $\sigma_{m}$ is a convex function for all $m=1, \ldots, n$.

Lemma 4.7. For a real vector $\mu \in \mathbb{R}^{n}$, such that

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{0}=0, k_{r}=n\right),
$$

the function

$$
S_{l}(\cdot)=\sum_{m=k_{l-1}+1}^{k_{l}} \lambda_{m}^{2}(\cdot)
$$

is analytic at the matrix $\operatorname{Diag} \mu$, with first and second derivatives satisfying

$$
\begin{aligned}
& \nabla S_{l}(\operatorname{Diag} \mu)[H]=2 \mu_{k_{l}} \operatorname{tr}\left(H \operatorname{Diag} \sum_{i=k_{l-1}+1}^{k_{l}} e^{i}\right) \\
& \begin{aligned}
\nabla^{2} S_{l}(\operatorname{Diag} \mu)[H, H] & =2 \sum_{p, q=k_{l-1}+1}^{k_{l}} h_{q p}^{2}+4 \sum_{p=k_{l-1}+1}^{k_{l}} \sum_{\substack{q=1 \\
\mu_{p} \neq \mu_{q}}}^{n} \frac{\mu_{p}}{\mu_{p}-\mu_{q}} h_{q p}^{2} \\
& =\left\langle H, 2 X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}+4 \mu_{k_{l}}\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} X_{l}^{\mathrm{T}}\right\rangle
\end{aligned}
\end{aligned}
$$

where $X_{l}=\left[e^{k_{l-1}+1}, \ldots, e^{k_{l}}\right]$.

Proof. The analyticity of $S(\cdot)$ at the point $\operatorname{Diag} \mu$ follows from Section 3. Next, summing the squares of Eqs. (2) with $A=\operatorname{Diag} \mu$, for $m=1, \ldots, k_{l}$ and using the fact that $X=I$ (so $X_{i}=\left[e^{k_{i-1}+1}, \ldots, e^{k_{i}}\right]$ ), we get

$$
\begin{aligned}
& \sum_{m=k_{l-1}+1}^{k_{l}} \lambda_{m}^{2}(\operatorname{Diag} \mu+t H) \\
& =\sum_{m=k_{l-1}+1}^{k_{l}}\left(\mu_{k_{l}}+t \lambda_{m-k_{l-1}}\left(X_{l}^{\mathrm{T}} H X_{l}\right)\right. \\
& \left.\quad+\frac{1}{2} t^{2} \lambda_{m-k_{l-1}-t_{l, j-1}}\left(2 U_{l, j}^{\mathrm{T}} X_{l}^{\mathrm{T}} H\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} U_{l, j}\right)+\mathrm{O}\left(t^{3}\right)\right)^{2} \\
& =\left(k_{l}-k_{l-1}\right) \mu_{k_{l}}^{2}+t^{2} \sum_{m=k_{l-1}+1}^{k_{l}} \lambda_{m-k_{l-1}}^{2}\left(X_{l}^{\mathrm{T}} H X_{l}\right) \\
& \quad+2 t \mu_{k_{l}} \sum_{m=k_{l-1}+1}^{k_{l}} \lambda_{m-k_{l-1}}\left(X_{l}^{\mathrm{T}} H X_{l}\right) \\
& \quad+t^{2} \mu_{k_{l}} \sum_{j=1}^{s_{l}} \sum_{v=1}^{t_{l, j}-t_{l, j-1}} \lambda_{v}\left(2 U_{l, j}^{\mathrm{T}} X_{l}^{\mathrm{T}} H\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} U_{l, j}\right)+\mathrm{O}\left(t^{3}\right) .
\end{aligned}
$$

We recall the fact that for every symmetric $n \times n$ matrix $Q$ we have

$$
\sum_{i=1}^{n} \lambda_{i}^{2}(Q)=\langle Q, Q\rangle
$$

We use this fact to evaluate the second summand in the formula above.

$$
\sum_{m=k_{l-1}+1}^{k_{l}} \lambda_{m-k_{l-1}}^{2}\left(X_{l}^{\mathrm{T}} H X_{l}\right)=\left\langle X_{l}^{\mathrm{T}} H X_{l}, X_{l}^{\mathrm{T}} H X_{l}\right\rangle=\left\langle H, X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}\right\rangle
$$

Observe as in Lemma 4.5 that for the fourth summand in the formula above, we have

$$
\begin{aligned}
& \sum_{j=1}^{s_{l}} \sum_{v=1}^{t_{l, j}-t_{l, j-1}} \lambda_{v}\left(2 U_{l, j}^{\mathrm{T}} X_{l}^{\mathrm{T}} H\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} U_{l, j}\right) \\
& \quad=\sum_{j=1}^{s_{l}} \operatorname{tr}\left(2 U_{l, j}^{\mathrm{T}} X_{l}^{\mathrm{T}} H\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} U_{l, j}\right) \\
& \quad=\operatorname{tr}\left(2 X_{l}^{\mathrm{T}} H\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l}\right) .
\end{aligned}
$$

Substituting everything in the original formula we get

$$
\begin{aligned}
& \sum_{m=k_{l-1}+1}^{k_{l}} \lambda_{m}^{2}(\operatorname{Diag} \mu+t H) \\
& =\left(k_{l}-k_{l-1}\right) \mu_{k_{l}}^{2}+t^{2}\left\langle H, X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}\right\rangle \\
& \quad+2 t \mu_{k_{l}}\left\langle\operatorname{Diag} \sum_{i=k_{l-1}+1}^{k_{l}} e^{i}, H\right\rangle \\
& \quad+t^{2} \mu_{k_{l}}\left\langle H, 2\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} X_{l}^{\mathrm{T}}\right\rangle+\mathrm{O}\left(t^{3}\right) \\
& = \\
& \quad\left(k_{l}-k_{l-1}\right) \mu_{k_{l}}^{2}+2 t \mu_{k_{l}}\left\langle\operatorname{Diag} \sum_{i=k_{l-1}+1}^{k_{l}} e^{i}, H\right\rangle \\
& \quad+\frac{1}{2} t^{2}\left\langle H, 2 X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}+4 \mu_{k_{l}}\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} X_{l}^{\mathrm{T}}\right\rangle+\mathrm{O}\left(t^{3}\right)
\end{aligned}
$$

Using Lemma 4.4, with $b=4 \mu$, we conclude that

$$
\nabla^{2} S_{l}(\operatorname{Diag} \mu)[H, H]=2 \sum_{p, q=k_{l-1}+1}^{k_{l}} h_{q p}^{2}+4 \sum_{p=k_{l-1}+1}^{k_{l}} \sum_{\substack{q=1 \\ \mu_{p} \neq \mu_{q}}}^{n} \frac{\mu_{p}}{\mu_{p}-\mu_{q}} h_{q p}^{2}
$$

By the uniqueness of the Hessian in the quadratic expansion of a function, we conclude that the last expression above must be indeed the Hessian.

Lemma 4.8. Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a symmetric function having quadratic expansion at the point $\mu \in \mathbb{R}_{\downarrow}^{n}$, where

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{0}=0, k_{r}=n\right)
$$

and let $P$ be a permutation matrix such that $P \mu=P$. Then:
(i) $\nabla f(\mu)=P^{\mathrm{T}} \nabla f(\mu)$, and
(ii) $\nabla^{2} f(\mu)=P^{\mathrm{T}} \nabla^{2} f(\mu) P$.

In particular we can write

$$
\nabla^{2} f(\mu)=\left(\begin{array}{cccc}
a_{11} E_{11}+b_{k_{1}} I_{1} & a_{12} E_{12} & \cdots & a_{1 r} E_{1 r} \\
a_{21} E_{21} & a_{22} E_{22}+b_{k_{2}} I_{2} & \cdots & a_{2 r} E_{2 r} \\
\vdots & \vdots & \ddots & \vdots \\
a_{r 1} E_{r 1} & a_{r 2} E_{r 2} & \cdots & a_{r r} R_{r r}+b_{k_{r}} I_{r}
\end{array}\right)
$$

where each $E_{u v}$ is a $\left(k_{u}-k_{u-1}\right) \times\left(k_{v}-k_{v-1}\right)$ matrix of all ones, $\left(a_{i j}\right)_{i, j=1}^{r, r}$ is a real symmetric matrix, $b:=\left(b_{1}, \ldots, b_{n}\right)$ is a real vector which is block refined by $\mu$, and $I_{u}$ is a square identity matrix of the same dimensions as $E_{u u}$. We also define the following matrix:

$$
A:=\nabla^{2} f(\mu)-\operatorname{Diag} b=\left(a_{i j} E_{i j}\right)_{i, j=1}^{r}
$$

Before we give the proof, some comments about the above representation are necessary:
(i) We make the convention that if the $i$ th diagonal block in the above representation has dimensions $1 \times 1$, then we set $a_{i i}=0$ and $b_{k_{i}}=f_{k_{i} k_{i}}{ }^{\prime \prime}(\mu)$. Otherwise, the value of $b_{k_{i}}$ is uniquely determined as the difference between a diagonal and an off-diagonal element of this block.
(ii) Note that the matrix $A$ as well as the vector $b$ depends on the point around which we form the quadratic expansion (in this case $\mu$ ) and on the function $f$.

Proof. We have

$$
f(\mu+h)=f(\mu)+\langle\nabla f(\mu), h\rangle+\frac{1}{2}\left\langle h, \nabla^{2} f(\mu) h\right\rangle+\mathrm{O}\left(\|h\|^{3}\right) .
$$

Let $P$ be a permutation matrix such that $P \mu=\mu$. Then

$$
\begin{aligned}
f(P(\mu+h)) & =f(\mu)+\langle\nabla f(\mu), P h\rangle+\frac{1}{2}\left\langle P h, \nabla^{2} f(\mu) P h\right\rangle+\mathrm{O}\left(\|P h\|^{3}\right) \\
& =f(\mu)+\left\langle P^{\mathrm{T}} \nabla f(\mu), h\right\rangle+\frac{1}{2}\left\langle h,\left(P^{\mathrm{T}} \nabla^{2} f(\mu) P\right) h\right\rangle+\mathrm{O}\left(\|h\|^{3}\right) .
\end{aligned}
$$

Using the fact that $f$ is symmetric gives us that $f(P(\mu+h))=f(\mu+h)$ so $\nabla f(\mu)$ $=P^{\mathrm{T}} \nabla f(\mu)$. Subtracting the above two equalities we obtain

$$
\begin{equation*}
\nabla^{2} f(\mu)=P^{\mathrm{T}} \nabla^{2} f(\mu) P \quad \forall P \in P(n) \text { s.t. } P \mu=\mu . \tag{3}
\end{equation*}
$$

The claimed block structure of $\nabla^{2} f(\mu)$ is now easy to check.
Note 4.9. Observe that Eq. (3) holds for arbitrary $\mu \in \mathbb{R}^{n}$.
Lemma 4.10. The vector $\mu$ block refines $\nabla^{2} f(\mu) \mu$.
Proof. Suppose $P \mu=\mu$. Then using twice Eq. (3) and the above note, we get

$$
P \nabla^{2} f(\mu) \mu=P\left(P^{\mathrm{T}} \nabla^{2} f(\mu) P\right) \mu=\nabla^{2} f(\mu) P \mu=\nabla^{2} f(\mu) \mu .
$$

Lemma 4.11. Let $\mu \in \mathbb{R}_{\downarrow}^{n}$ be such that

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{0}=0, k_{r}=n\right) .
$$

Suppose $\mu$ block refines a vector $b \in \mathbb{R}^{n}$. Then $b^{\mathrm{T}} \lambda$ is analytic at the matrix $\operatorname{Diag} \mu$ with quadratic expansion

$$
b^{\mathrm{T}} \lambda(\operatorname{Diag} \mu+H)=b^{\mathrm{T}} \mu+\langle\operatorname{Diag} b, H\rangle+\sum_{p, q: \mu_{p}>\mu_{q}} \frac{b_{p}-b_{q}}{\mu_{p}-\mu_{q}} h_{q p}^{2}+\mathrm{O}\left(\|H\|^{3}\right)
$$

Proof. Because the vector $\mu$ block refines the vector $b$ there exist reals $b_{1}^{\prime}, b_{2}^{\prime}, \ldots, b_{r}^{\prime}$ with

$$
b_{j}=b_{i}^{\prime} \quad \text { whenever } k_{i-1}+1 \leqslant j \leqslant k_{i}, \quad i=1,2, \ldots, r .
$$

We obtain

$$
b^{\mathrm{T}} \lambda(\cdot)=\sum_{i=1}^{r} b_{i}^{\prime} \sum_{j=k_{i-1}+1}^{k_{i}} \lambda_{j}(\cdot)=\sum_{i=1}^{r} b_{i}^{\prime}\left(\sigma_{k_{i}}(\cdot)-\sigma_{k_{i-1}}(\cdot)\right) .
$$

Now applying Lemmas 4.5 and 4.4 gives the result.
Lemma 4.12. Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a symmetric function having quadratic expansion at the point $\mu \in \mathbb{R}_{\downarrow}^{n}$, where

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{0}=0, k_{r}=n\right) .
$$

Then the following matrix functions on $S^{n}$ :
(i) $F(\cdot):=\nabla f(\mu)^{\mathrm{T}} \lambda(\cdot)$,
(ii) $K(\cdot):=\mu^{\mathrm{T}} \nabla^{2} f(\mu) \lambda(\cdot)$,
(iii) $G(\cdot):=\lambda(\cdot)^{T} \nabla^{2} f(\mu) \lambda(\cdot)$,
have quadratic expansions at the matrix $\operatorname{Diag} \mu$.
Proof. Later we will need the formulae, giving the quadratic expansions of these functions, derived in the following proof. Notice that the first two parts follow immediately from the previous two lemmas. So we can write, up to $\mathrm{O}\left(\|H\|^{3}\right)$,

$$
\begin{aligned}
F(\operatorname{Diag} \mu+H) \approx & \nabla f(\mu)^{\mathrm{T}} \mu+\langle\operatorname{Diag} \nabla f(\mu), H\rangle \\
& +\sum_{p, q: \mu_{p}>\mu_{q}} \frac{f_{p}^{\prime}(\mu)-f_{q}^{\prime}(\mu)}{\mu_{p}-\mu_{q}} h_{q p}^{2} \\
K(\operatorname{Diag} \mu+H) \approx & \mu^{\mathrm{T}} \nabla^{2} f(\mu) \mu+\left\langle\operatorname{Diag} \nabla^{2} f(\mu) \mu, H\right\rangle \\
& +\sum_{p, q: \mu_{p}>\mu_{q}} \frac{\left(\mu^{\mathrm{T}} \nabla^{2} f(\mu)\right)_{p}-\left(\mu^{\mathrm{T}} \nabla^{2} f(\mu)\right)_{q}}{\mu_{p}-\mu_{q}} h_{q p}^{2}
\end{aligned}
$$

(iii) Because of the block structure of $\nabla^{2} f(\mu)$ described in Lemma 4.8, we have

$$
\lambda(\cdot)^{\mathrm{T}} \nabla^{2} f(\mu) \lambda(\cdot)=\sum_{i, j=1}^{r} a_{i j}\left(\sigma_{k_{i}}(\cdot)-\sigma_{k_{i-1}}(\cdot)\right)\left(\sigma_{k_{j}}(\cdot)-\sigma_{k_{j-1}}(\cdot)\right)+\sum_{l=1}^{r} b_{k_{l}} S_{l}(\cdot),
$$

where the matrix $\left(a_{i j}\right)_{i, j=1}^{r}$, vector $b$, and $S_{l}(\cdot)$ are defined in Lemmas 4.8 and 4.7. Now by Lemma 4.5

$$
\begin{aligned}
\sigma_{k_{l}} & (\operatorname{Diag} \mu+H)-\sigma_{k_{l-1}}(\operatorname{Diag} \mu+H) \\
= & \sum_{i=k_{l-1}+1}^{k_{l}} \mu_{i}+\left\langle\operatorname{Diag} \sum_{i=k_{l-1}+1}^{k_{l}} e^{i}, H\right\rangle \\
& +\frac{1}{2}\left\langle H, 2\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} X_{l}^{\mathrm{T}}\right\rangle+\mathrm{O}\left(\|H\|^{3}\right) \\
= & \sum_{i=k_{l-1}+1}^{k_{l}} \mu_{i}+\sum_{i=k_{l-1}+1}^{k_{l}} h_{i i}+\sum_{i=k_{l-1}+1}^{k_{l}}\left\langle H,\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H e^{i}\left(e^{i}\right)^{\mathrm{T}}\right\rangle
\end{aligned}
$$

$$
+\mathrm{O}\left(\|H\|^{3}\right) .
$$

We can evaluate the first summand in the above representation of the function $G(\cdot)$.

$$
\begin{aligned}
& \sum_{i, j=1}^{r} a_{i j}\left(\sigma_{k_{i}}(\operatorname{Diag} \mu+H)-\sigma_{k_{i-1}}(\operatorname{Diag} \mu+H)\right) \\
& \times\left(\sigma_{k_{j}}(\operatorname{Diag} \mu+H)-\sigma_{k_{j-1}}(\operatorname{Diag} \mu+H)\right) \\
& =\mu^{\mathrm{T}} A \mu+(\operatorname{diag} H)^{\mathrm{T}} A(\operatorname{diag} H)+2 \mu^{\mathrm{T}} A(\operatorname{diag} H) \\
& \quad+2\left\langle H, \sum_{i, j=1}^{n} \mu_{i} A^{i j}\left(\mu_{j} I-\operatorname{Diag} \mu\right)^{\dagger} H e^{j}\left(e^{j}\right)^{\mathrm{T}}\right\rangle+\mathrm{O}\left(\|H\|^{3}\right) \\
& \quad=\mu^{\mathrm{T}} A \mu+2\langle\operatorname{Diag} A \mu, H\rangle+\langle H, \operatorname{Diag} A(\operatorname{diag} H)\rangle \\
& \quad+2\left\langle H, \sum_{i, j=1}^{n} \mu_{i} A^{i j}\left(\mu_{j} I-\operatorname{Diag} \mu\right)^{\dagger} H e^{j}\left(e^{j}\right)^{\mathrm{T}}\right\rangle+\mathrm{O}\left(\|H\|^{3}\right),
\end{aligned}
$$

where diag: $S^{n} \rightarrow \mathbb{R}^{n}$ defined by diag $(H)=\left(h_{11}, \ldots, h_{n n}\right)$ is the conjugate operator of Diag: $\mathbb{R}^{n} \rightarrow S^{n}$. On the other hand Lemma 4.7 gives us

$$
\begin{aligned}
& \sum_{l=1}^{r} b_{k_{l}} S_{l}(\operatorname{Diag} \mu+H) \\
& =\sum_{l=1}^{r} b_{k_{l}}\left(\left(k_{l}-k_{l-1}\right) \mu_{k_{l}}^{2}+2 \mu_{k_{l}}\left\langle\operatorname{Diag} \sum_{i=k_{l-1}+1}^{k_{l}} e^{i}, H\right\rangle\right. \\
& \left.\quad+\left\langle H, X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}+2 \mu_{k_{l}}\left(\mu_{k_{l}} I-\operatorname{Diag} \mu\right)^{\dagger} H X_{l} X_{l}^{\mathrm{T}}\right\rangle\right) \\
& \quad+\mathrm{O}\left(\|H\|^{3}\right) \\
& = \\
& \quad \mu^{\mathrm{T}}(\operatorname{Diag} b) \mu+2\langle\operatorname{Diag}(\operatorname{Diag} b) \mu, H\rangle+\left\langle H, \sum_{l=1}^{r} b_{k_{l}} X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}\right\rangle \\
& \quad+\left\langle H, 2 \sum_{i, j=1}^{n} \mu_{i}(\operatorname{Diag} b)^{i j}\left(\mu_{j} I-\operatorname{Diag} \mu\right)^{\dagger} H e^{j}\left(e^{j}\right)^{\mathrm{T}}\right\rangle+\mathrm{O}\left(\|H\|^{3}\right)
\end{aligned}
$$

Adding these two formulae together we finally get

$$
\begin{aligned}
& \lambda(\operatorname{Diag} \mu+H)^{\mathrm{T}} \nabla^{2} f(\mu) \lambda(\operatorname{Diag} \mu+H) \\
& \quad=\mu^{\mathrm{T}} \nabla^{2} f(\mu) \mu+2\left\langle\operatorname{Diag} \nabla^{2} f(\mu) \mu, H\right\rangle \\
& \quad+\langle H, \operatorname{Diag} A(\operatorname{diag} H)\rangle+\left\langle H, \sum_{l=1}^{r} b_{k_{l}} X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}\right\rangle
\end{aligned}
$$

$$
\begin{aligned}
& +\left\langle H, 2 \sum_{j=1}^{n}\left(\mu^{\mathrm{T}} \nabla^{2} f(\mu)\right)_{j}\left(\mu_{j} I-\operatorname{Diag} \mu\right)^{\dagger} H e^{j}\left(e^{j}\right)^{\mathrm{T}}\right\rangle+\mathrm{O}\left(\|H\|^{3}\right) \\
= & \mu^{\mathrm{T}} \nabla^{2} f(\mu) \mu+2\left\langle\operatorname{Diag} \nabla^{2} f(\mu) \mu, H\right\rangle+\langle H, \operatorname{Diag} A(\operatorname{diag} H)\rangle \\
& +\sum_{p, q: \mu_{p}=\mu_{q}} b_{p} h_{p q}^{2}+2 \sum_{p, q: \mu_{p}>\mu_{q}} \frac{\left(\mu^{\mathrm{T}} \nabla^{2} f(\mu)\right)_{p}-\left(\mu^{\mathrm{T}} \nabla^{2} f(\mu)\right)_{q}}{\mu_{p}-\mu_{q}} h_{q p}^{2} \\
& +\mathrm{O}\left(\|H\|^{3}\right) .
\end{aligned}
$$

In the last equality we used Lemmas 4.10 and 4.4.
Now we are ready to prove a preliminary case of Theorem 4.1, namely, that it holds at $X=\operatorname{diag} \mu,\left(\mu \in \mathbb{R}_{\downarrow}\right)$ and to give a formula for the Hessian of $f \circ \lambda$ at this point. The results for the gradient of $f \circ \lambda$ that we will obtain along the way were first obtained in [10].

Theorem 4.13. Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a symmetric function having quadratic expansion at the point $\mu \in \mathbb{R}_{\downarrow}^{n}$, where

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{0}=0, k_{r}=n\right)
$$

Then $f \circ \lambda$ has quadratic expansion at the point $\operatorname{Diag} \mu$, with

$$
\begin{aligned}
\nabla(f \circ \lambda)(\operatorname{Diag} \mu)[H]=\operatorname{tr}( & H \operatorname{Diag} \nabla f(\mu)) \\
\nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)[H, H]= & \sum_{p, q=1}^{n} h_{p p} f^{\prime \prime}{ }_{p q}(\mu) h_{q q}+\sum_{\substack{p \neq q \\
\mu_{p}=\mu_{q}}} b_{p} h_{p q}^{2} \\
& +\sum_{p, q: \mu_{p} \neq \mu_{q}} \frac{f_{p}^{\prime}(\mu)-f_{q}^{\prime}(\mu)}{\mu_{p}-\mu_{q}} h_{p q}^{2}
\end{aligned}
$$

(with $b$ defined by Lemma 4.8).
Note 4.14. Corollary 4.15 will show that the requirement that $\mu \in \mathbb{R}_{\downarrow}^{n}$ can be omitted. For a matrix representation of the above formula combine Eq. (4) below, and the first identity in Lemma 4.4.

Proof. We are given that

$$
\begin{aligned}
f(x)= & f(\mu)+\nabla f(\mu)^{\mathrm{T}}(x-\mu)+\frac{1}{2}(x-\mu)^{\mathrm{T}} \nabla^{2} f(\mu)(x-\mu) \\
& +\mathrm{O}\left(\|x-\mu\|^{3}\right),
\end{aligned}
$$

so after letting $x=\lambda(\operatorname{Diag} \mu+H)$ and using the fact that

$$
\lambda(\operatorname{Diag} \mu+H)=\lambda(\operatorname{Diag} \mu)+\mathrm{O}(\|H\|)
$$

we get

$$
\begin{aligned}
(f \circ \lambda)(\operatorname{Diag} \mu+H)= & f(\mu)+\nabla f(\mu)^{\mathrm{T}} \lambda(\operatorname{Diag} \mu+H)-\nabla f(\mu)^{\mathrm{T}} \mu \\
& +\frac{1}{2} \lambda(\operatorname{Diag} \mu+H)^{\mathrm{T}} \nabla^{2} f(\mu) \lambda(\operatorname{Diag} \mu+H) \\
& -\mu^{\mathrm{T}} \nabla^{2} f(\mu) \lambda(\operatorname{Diag} \mu+H) \\
& +\frac{1}{2} \mu^{\mathrm{T}} \nabla^{2} f(\mu) \mu+\mathrm{O}\left(\|H\|^{3}\right) .
\end{aligned}
$$

Substituting the three expressions in the proof of Lemma 4.12 we obtain

$$
\begin{align*}
(f \circ \lambda)(\operatorname{Diag} \mu+H)= & (f \circ \lambda)(\operatorname{Diag} \mu)+\langle\operatorname{Diag} \nabla f(\mu), H\rangle \\
& +\frac{1}{2}\left\langle H, \operatorname{Diag} A(\operatorname{diag} H)+\sum_{l=1}^{r} b_{k_{l}} X_{l} X_{l}^{\mathrm{T}} H X_{l} X_{l}^{\mathrm{T}}\right\rangle \\
& +\sum_{p, q: \mu_{p}>\mu_{q}} \frac{f_{p}^{\prime}(\mu)-f_{q}^{\prime}(\mu)}{\mu_{p}-\mu_{q}} h_{q p}^{2}+\mathrm{O}\left(\|H\|^{3}\right) . \tag{4}
\end{align*}
$$

Recall that $X_{l}=\left[e^{k_{l-1}+1}, \ldots, e^{k_{l}}\right]$. In order to obtain the representation given in the theorem one has to use the definition of $A$ and $b=\left(b_{1}, \ldots, b_{n}\right)$ given in Lemma 4.8 and the note that follows it.

Proof of Theorem 4.1. Suppose $f$ has quadratic expansion at the point $\lambda(Y)$, and choose any orthogonal matrix $U=\left[u^{1} \cdots u^{n}\right]$ that gives the ordered spectral decomposition of $Y, Y=U(\operatorname{Diag} \lambda(Y)) U^{\mathrm{T}}$. Here we actually have $A=A(\lambda(Y))$ and $b_{i}=b_{i}(\lambda(Y))$. While in formula (4) we had $A=A(\mu)$ and $b_{i}=b_{i}(\mu)$, to make the formulae here easier to read we will write again simply $A$ and $b_{i}$. Then we have, using formula (4) and some easy manipulations,

$$
\begin{aligned}
&(f \circ \lambda)(Y+H)=(f \circ \lambda)\left(\operatorname{Diag} \lambda(Y)+U^{\mathrm{T}} H U\right) \\
&=(f \circ \lambda)(Y)+\left\langle\operatorname{Diag} \nabla f(\lambda(Y)), U^{\mathrm{T}} H U\right\rangle \\
&+\frac{1}{2}\left\langle U^{\mathrm{T}} H U, \operatorname{Diag} A\left(\operatorname{diag} U^{\mathrm{T}} H U\right)+\sum_{l=1}^{r} b_{k_{l}} X_{l} X_{l}^{\mathrm{T}} U^{\mathrm{T}} H U X_{l} X_{l}^{\mathrm{T}}\right\rangle \\
& \quad+\sum_{\substack{p, q \\
\lambda_{p}(Y)>\lambda_{q}(Y)}} \frac{f_{p}^{\prime}(\lambda(Y))-f_{q}^{\prime}(\lambda(Y))}{\lambda_{p}(Y)-\lambda_{q}(Y)}\left(\left(U^{\mathrm{T}} H U\right)^{q p}\right)^{2}+\mathrm{O}\left(\|H\|^{3}\right),
\end{aligned}
$$

where $X_{l}=\left[e^{k_{l-1}+1}, \ldots, e^{k_{l}}\right]$.
Corollary 4.15. Theorem 4.13 holds for arbitrary $\mu \in \mathbb{R}^{n}$, where

$$
\begin{equation*}
b(\mu):=P b(\bar{\mu}), \tag{5}
\end{equation*}
$$

and $P$ is a permutation matrix, such that $P^{\mathrm{T}} \mu=\bar{\mu}$.

Proof. Pick a permutation matrix $P$ such that $P^{\mathrm{T}} \mu=\bar{\mu}$ and let $\pi$ be the permutation associated with it, that is $\bar{\mu}=\left(\mu_{\pi(1)}, \ldots, \mu_{\pi(n)}\right)$, or in other words $P e^{i}=e^{\pi(i)}$. We have that $f$ has quadratic expansion at the point $\mu$, that is

$$
f(\mu+h)=f(\mu)+\langle\nabla f(\mu), h\rangle+\frac{1}{2}\left\langle h, \nabla^{2} f(\mu) h\right\rangle+\mathrm{O}\left(\|h\|^{3}\right)
$$

Using the fact that $f$ is symmetric we obtain

$$
\begin{aligned}
f\left(\bar{\mu}+P^{T} h\right)= & f\left(P^{\mathrm{T}}(\mu+h)\right) \\
= & f(\mu+h) \\
= & f(\mu)+\langle\nabla f(\mu), h\rangle+\frac{1}{2}\left\langle h, \nabla^{2} f(\mu) h\right\rangle+\mathrm{O}\left(\|h\|^{3}\right) \\
= & f(\bar{\mu})+\left\langle P^{\mathrm{T}} \nabla f(\mu), P^{\mathrm{T}} h\right\rangle+\frac{1}{2}\left\langle P^{\mathrm{T}} h, P^{\mathrm{T}} \nabla^{2} f(\mu) P P^{\mathrm{T}} h\right\rangle \\
& +\mathrm{O}\left(\left\|P^{\mathrm{T}} h\right\|^{3}\right) .
\end{aligned}
$$

So $f$ has quadratic expansion at the point $\bar{\mu}$ as well, and we have the relationships

$$
\begin{align*}
& \nabla f(\bar{\mu})=P^{\mathrm{T}} \nabla f(\mu), \\
& \nabla^{2} f(\bar{\mu})=P^{\mathrm{T}} \nabla^{2} f(\mu) P \tag{6}
\end{align*}
$$

We have $\operatorname{Diag} \mu=P(\operatorname{Diag} \bar{\mu}) P^{T}$. Applying Theorem 4.1 with $Y=\operatorname{Diag} \mu$ and $U=$ $P$, and using Eqs. (6) and (5) we get

$$
\begin{aligned}
& \nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)[H, H] \\
& \quad=\sum_{p, q=1}^{n} h_{\pi(p) \pi(p)} f_{p q}^{\prime \prime}(\bar{\mu}) h_{\pi(q) \pi(q)}+\sum_{\substack{p \neq q \\
\bar{\mu}_{p}=\bar{\mu}_{q}}} b_{p}(\bar{\mu}) h_{\pi(p) \pi(q)}^{2} \\
& \quad+\sum_{\bar{\mu}_{p} \neq \bar{\mu}_{q}} \frac{f_{p}^{\prime}(\bar{\mu})-f_{q}^{\prime}(\bar{\mu})}{\bar{\mu}_{p}-\bar{\mu}_{q}} h_{\pi(p) \pi(q)}^{2} \\
& =\sum_{p, q=1}^{n} h_{p p} f_{p q}^{\prime \prime}(\mu) h_{q q}+\sum_{\substack{p \neq q \\
\mu_{p}=\mu_{q}}} b_{p}(\mu) h_{p q}^{2}+\sum_{\mu_{p} \neq \mu_{q}} \frac{f_{p}^{\prime}(\mu)-f_{q}^{\prime}(\mu)}{\mu_{p}-\mu_{q}} h_{p q}^{2}
\end{aligned}
$$

The invariance of the formula for the gradient is shown in a similar manner. See also [10].

## 5. Strongly convex functions

As we mentioned in Section 1, a symmetric function $f$ is convex if and only if $f \circ \lambda$ is convex. The analogous result also holds for essential strict convexity [9, Corollary 3.5]. Here we study yet a stronger property.

In this section, we show that if a symmetric, convex function $f$ has a quadratic expansion at the point $x=\lambda(Y)$, then the symmetric matrix $\nabla^{2} f(x)$ is positive definite, if and only if the same is true for the bilinear operator $\nabla^{2}(f \circ \lambda)(Y)$.

Lemma 5.1. If a function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is symmetric, strictly convex, and differentiable at the point $\mu$

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{r}=n\right)
$$

then its gradient satisfies

$$
\frac{f_{p}^{\prime}(\mu)-f_{q}^{\prime}(\mu)}{\mu_{p}-\mu_{q}}>0 \quad \text { for all } p, q \text { such that } \mu_{p} \neq \mu_{q}
$$

Proof. Because $f$ is strictly convex and differentiable at $\mu$, for every $x \in \mathbb{R}^{n}(\mu \neq x)$ we have that (see for example [14, Theorem 2.3.5])

$$
\langle\nabla f(\mu), x-\mu\rangle<f(x)-f(\mu) .
$$

Suppose $\mu_{p} \neq \mu_{q}$. Let $P$ be the permutation matrix that transposes $p$ and $q$ only. Then we have

$$
\left(f_{q}^{\prime}(\mu)-f_{p}^{\prime}(\mu)\right)\left(\mu_{p}-\mu_{q}\right)=\langle\nabla f(\mu), P \mu-\mu\rangle<f(P \mu)-f(\mu)=0
$$

Lemma 5.2. Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a symmetric function having quadratic expansion at $\mu$, where

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{r}=n\right)
$$

If the Hessian $\nabla^{2} f(\mu)$ is positive definite, then the vector $b=\left(b_{1}, \ldots, b_{n}\right)$, defined in Lemma 4.8, has strictly positive entries.

Proof. It is well known that every principal minor in a positive definite matrix is positive definite. Fix an index $1 \leqslant i \leqslant n$. If $\mu_{i-1}>\mu_{i}>\mu_{i+1}$, then from the representation of the matrix $\nabla^{2} f(\mu)$ in Lemma 4.8 and the note after it, it is clear that $b_{i}>0$. Suppose now that $i$ is in a block of length at least 2 . Then some principal minor of $\nabla^{2} f(\mu)$ of the form

$$
\left(\begin{array}{cc}
a+b_{i} & a \\
a & a+b_{i}
\end{array}\right)
$$

is positive definite, and the result follows.
Theorem 5.3. Let $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a symmetric, strictly convex function having quadratic expansion at $\mu$

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{r}=n\right) .
$$

Then the symmetric matrix $\nabla^{2} f(\mu)$ is positive definite if and only if the bilinear operator $\nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)$ is positive definite.

Note 5.4. In fact by Alexandrov's Theorem, if a function is convex it has quadratic expansion at almost every point of its domain [1].

Proof. Suppose first that the symmetric matrix $\nabla^{2} f(\mu)$ is positive definite. Take a symmetric matrix $H \neq 0$. Then we have

$$
\sum_{p, q=1}^{n} h_{p p} f_{p q}^{\prime \prime}(\mu) h_{q q} \geqslant 0
$$

because $\nabla^{2} f(\mu)$ is positive definite,

$$
2 \sum_{l=1}^{r} b_{k_{l}} \sum_{k_{i-1}<p<q \leqslant k_{i}} h_{p q}^{2} \geqslant 0,
$$

follows from Lemma 5.2, and

$$
2 \sum_{p, q: \mu_{p}>\mu_{q}} \frac{f_{p}^{\prime}(\mu)-f_{q}^{\prime}(\mu)}{\mu_{p}-\mu_{q}} h_{p q}^{2} \geqslant 0
$$

which follows from Lemma 5.1. Now because $H \neq 0$ at least one of the above inequalities will be strict.

In the other direction the argument is easy: take $H=\operatorname{Diag} x$, for $0 \neq x \in \mathbb{R}^{n}$ in the formula for $\nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)$ given in Theorem 4.13 to get immediately $x^{\mathrm{T}} \nabla^{2} f(\mu) x>0$.

Theorem 5.5. If $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a symmetric, strictly convex function having quadratic expansion at the point $Y$, then $\nabla^{2} f(\lambda(Y))$ is positive definite if and only if $\nabla^{2}(f \circ \lambda)(Y)$ is.

Proof. The proof of this theorem is now clear since $\nabla^{2}(f \circ \lambda)(Y)$ is positive definite if and only if $\nabla^{2}(f \circ \lambda)(\operatorname{Diag} \lambda(Y))$ is.

## 6. Examples

Example 6.1. Let $g$ be a function on a scalar argument. Consider the following separable symmetric function with its corresponding spectral function

$$
\begin{aligned}
& f\left(x_{1}, \ldots, x_{n}\right)=\sum_{i=1}^{n} g\left(x_{i}\right), \\
& (f \circ \lambda)(Y)=\sum_{i=1}^{n} g\left(\lambda_{i}(Y)\right) .
\end{aligned}
$$

Then if $g$ has quadratic expansion at the points $x_{1}, \ldots, x_{n}$ so does $f$ at $x=\left(x_{1}, \ldots, x_{n}\right)$ and we have

$$
\begin{aligned}
& \nabla f(x)=\left(g^{\prime}\left(x_{1}\right), \ldots, g^{\prime}\left(x_{n}\right)\right)^{\mathrm{T}} \\
& \nabla^{2} f(x)=\operatorname{Diag}\left(g^{\prime \prime}\left(x_{1}\right), \ldots, g^{\prime \prime}\left(x_{n}\right)\right), \\
& b(x)=\left(g^{\prime \prime}\left(x_{1}\right), \ldots, g^{\prime \prime}\left(x_{n}\right)\right)^{\mathrm{T}}
\end{aligned}
$$

Suppose $g$ has quadratic expansion at each entry of the vector $\mu \in \mathbb{R}_{\downarrow}^{n}$, which satisfies

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{r}=n\right) .
$$

Then Theorem 4.13 says that

$$
\begin{aligned}
& \nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)[H, H] \\
& \quad=\sum_{p=1}^{n} g^{\prime \prime}\left(\mu_{p}\right) h_{p p}^{2}+\sum_{\substack{p \neq q \\
\mu_{p}=\mu_{q}}} g^{\prime \prime}\left(\mu_{p}\right) h_{p q}^{2}+\sum_{p, q: \mu_{p} \neq \mu_{q}} \frac{g^{\prime}\left(\mu_{p}\right)-g^{\prime}\left(\mu_{q}\right)}{\mu_{p}-\mu_{q}} h_{p q}^{2} \\
& \quad=\sum_{p, q: \mu_{p}=\mu_{q}} g^{\prime \prime}\left(\mu_{p}\right) h_{p q}^{2}+\sum_{p, q: \mu_{p} \neq \mu_{q}} \frac{g^{\prime}\left(\mu_{p}\right)-g^{\prime}\left(\mu_{q}\right)}{\mu_{p}-\mu_{q}} h_{p q}^{2} .
\end{aligned}
$$

Let us define the following notation consistent with [3, Section V.3]. For any function $h$ defined on a subset of $\mathbb{R}$ define

$$
h^{[1]}(\alpha, \beta)= \begin{cases}\frac{h(\alpha)-h(\beta)}{\alpha-\beta} & \text { if } \alpha \neq \beta \\ h^{\prime}(\alpha) & \text { if } \alpha=\beta\end{cases}
$$

If $\Lambda$ is a diagonal matrix with diagonal entries $\alpha_{1}, \ldots, \alpha_{n}$, we denote by $h^{[1]}(\Lambda)$ the $n \times n$ symmetric matrix matrix whose $(i, j)$-entry is $h^{[1]}\left(\alpha_{i}, \alpha_{j}\right)$.

Using this notation, for the function $h=g^{\prime}$, we clearly have

$$
\begin{align*}
& \nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)[H, H]=\left\langle H, h^{[1]}(\operatorname{Diag} \mu) \circ H\right\rangle, \\
& \nabla^{2}(f \circ \lambda)(Y)[H, H]=\left\langle U^{\mathrm{T}} H U, h^{[1]}(\operatorname{Diag} \lambda(Y)) \circ\left(U^{\mathrm{T}} H U\right)\right\rangle, \tag{7}
\end{align*}
$$

where $Y=U(\operatorname{Diag} \lambda(Y)) U^{\mathrm{T}}, U$ orthogonal, and $X \circ Y=\left(x_{i j} y_{i j}\right)_{i, j=1}^{n}$ is the Hadamard product of matrices $X$ and $Y$.

Let us extend the domain of the function $h$ to include a subset of the symmetric matrices in the following way. If $\Lambda=\operatorname{Diag}\left(\alpha_{1}, \ldots, \alpha_{n}\right)$ is a diagonal matrix whose entries are in the domain of $h$, we define $h(\Lambda)=\operatorname{Diag}\left(h\left(\alpha_{1}\right), \ldots, h\left(\alpha_{n}\right)\right)$. If $Y$ is a symmetric matrix with eigenvalues $\alpha_{1}, \ldots, \alpha_{n}$ in the domain of $h$, we choose an orthogonal matrix $U$ such that $Y=U \Lambda U^{\mathrm{T}}$ and define $h(Y)=U h(\Lambda) U^{\mathrm{T}}$. (Notice that the definition of $h(Y)$ does not depend on the choice of the orthogonal matrix $U$.) In this way we can define $h(Y)$ for all symmetric matrices with eigenvalues in the domain of $h$. Then the formula for the gradient in Theorem 4.1 says that for $h=g^{\prime}$ we have

$$
\nabla(f \circ \lambda)(Y)=h(Y)
$$

Thus Eqs. (7) are just the formulae for the derivative $\nabla h$ given in Theorem V.3.3 in [3].

Example 6.2. Now we specialize the above example even more. The following spectral function finds many applications in semidefinite programming. Consider the symmetric and strictly convex function and the corresponding spectral function:

$$
\begin{aligned}
& f: x \in \mathbb{R}_{++}^{n} \mapsto-\sum_{i=1}^{n} \log x_{i} \\
& f \circ \lambda: A \in S_{++}^{n} \mapsto-\log \operatorname{det}(A)
\end{aligned}
$$

(Here $S_{++}^{n}$ denotes the set of all positive definite symmetric matrices.) Then Theorem 4.13 says that for $\mu \in \mathbb{R}_{\downarrow}^{n}$ such that

$$
\mu_{1}=\cdots=\mu_{k_{1}}>\mu_{k_{1}+1}=\cdots=\mu_{k_{2}}>\mu_{k_{2}+1} \cdots \mu_{k_{r}} \quad\left(k_{r}=n\right),
$$

we have

$$
\begin{aligned}
\nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)[H, H] & =\sum_{p=1}^{n} \frac{h_{p p}^{2}}{\mu_{p}^{2}}+\sum_{\substack{p \neq q \\
\mu_{p}=\mu_{q}}} \frac{h_{p q}^{2}}{\mu_{p}^{2}}+\sum_{p, q: \mu_{p} \neq \mu_{q}} \frac{h_{p q}^{2}}{\mu_{p} \mu_{q}} \\
& =\sum_{p, q=1,1}^{n, n} \frac{h_{p q}^{2}}{\mu_{p} \mu_{q}} \\
& =\operatorname{tr}\left((\operatorname{Diag} \mu)^{-1} H(\operatorname{Diag} \mu)^{-1} H\right) .
\end{aligned}
$$

The last equality may easily be verified. In general, for an arbitrary symmetric matrix $A$, we get

$$
\nabla^{2}(f \circ \lambda)(A)[H, H]=\operatorname{tr}\left(A^{-1} H A^{-1} H\right) .
$$

This agrees with the standard formula for the second derivative of the function $-\log \operatorname{det}(A)$. (See for example [12, Proposition 5.4.5].) Moreover, the result in Section 5 tells us that

$$
A \succ 0 \quad \text { implies } \operatorname{tr}\left(A^{-1} H A^{-1} H\right)>0 \quad \text { for all } 0 \neq H \in S^{n},
$$

and this result can also be verified directly.
Example 6.3. Consider the following symmetric function and its corresponding spectral function:

$$
\begin{aligned}
& \phi_{k}(x)=k \text { th largest element of }\left\{x_{1}, x_{2} \ldots, x_{n}\right\}, \\
& \lambda_{k}(A)=k \text { th largest eigenvalue of } A .
\end{aligned}
$$

The function $\phi_{k}(x)$ is linear near every point $x$ such that

$$
\bar{x}_{k-1}>\bar{x}_{k}>\bar{x}_{k+1}
$$

since locally we have $\phi_{k}(x)=x_{m}$ for the index $m$ such that $x_{m}$ is the $k$ th largest coordinate of $x$. In particular if $x \in \mathbb{R}_{\downarrow}^{n}$, then $k=m$. So

$$
\nabla \phi_{k}(x)=e^{m}, \quad \nabla^{2} \phi_{k}(x)=0, \quad b_{\phi_{k}}(x)=0 .
$$

Then Theorem 4.13 says that for $\mu \in \mathbb{R}_{\downarrow}^{n}$ such that

$$
\mu_{k-1}>\mu_{k}>\mu_{k+1}
$$

we have

$$
\nabla^{2} \lambda_{k}(\operatorname{Diag} \mu)[H, H]=\nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)[H, H]=2 \sum_{\substack{q=1 \\ q \neq k}}^{n} \frac{1}{\mu_{k}-\mu_{q}} h_{k q}^{2} .
$$

This agrees with the result in [7, p. 92].

## 7. The eigenvalues of $\nabla^{2}(f \circ \lambda)$

A natural question one may ask is: Is there any relationship between the eigenvalues of $\nabla^{2} f(\lambda(Y))$ and those of $\nabla^{2}(f \circ \lambda)(Y)$ ? This section shows that locally such a relationship will be quite weak, although more globally they are closely related. Let $Y$ be a symmetric matrix such that

$$
\begin{aligned}
\lambda_{1}(Y) & =\cdots=\lambda_{k_{1}}(Y)>\cdots>\lambda_{k_{l-1}+1}(Y)=\cdots=\lambda_{m}(Y) \\
& =\cdots=\lambda_{k_{l}}(Y)>\cdots \lambda_{k_{r}}(Y) \quad\left(k_{0}=0, k_{r}=n\right) .
\end{aligned}
$$

Using the representation given in Theorem 4.1 and Corollary 4.15 one can see that the eigenvalues of $\nabla^{2}(f \circ \lambda)(Y)$ are:

- $\left\{\lambda_{i}\left(\nabla^{2} f(\lambda(Y))\right) \mid i=1, \ldots, n\right\}$.
- $b_{k_{l}}$ is an eigenvalue for every $l=1, \ldots, r$ with multiplicity $\left(k_{l}-k_{l-1}\right)\left(k_{l}-k_{l-1}\right.$ $-1) / 2$.
- $\frac{f_{k_{l}}^{\prime}(\lambda(Y))-f_{k_{s}}^{\prime}(\lambda(Y))}{\lambda_{k_{l}}(Y)-\lambda_{k_{s}}(Y)}$ is an eigenvalue with multiplicity $\left(k_{l}-k_{l-1}\right)\left(k_{s}-k_{s-1}\right)$ for every ordered pair $\left(\lambda_{k_{l}}(Y), \lambda_{k_{s}}(Y)\right)$ such that $\lambda_{k_{l}}(Y)>\lambda_{k_{s}}(Y)$.
So we can immediately conclude that

$$
\begin{align*}
& \lambda_{\max }\left(\nabla^{2}(f \circ \lambda)(Y)\right) \geqslant \lambda_{\max }\left(\nabla^{2} f(\lambda(Y))\right), \\
& \lambda_{\min }\left(\nabla^{2} f(\lambda(Y))\right) \geqslant \lambda_{\min }\left(\nabla^{2}(f \circ \lambda)(Y)\right) . \tag{8}
\end{align*}
$$

We are going to show now that the above inequalities may be strict.
Example 7.1. Consider the convex function

$$
f(x, y):=\frac{x^{2}+y^{2}}{4}+\frac{\cos 2 x+\cos 2 y}{8}
$$

and the point

$$
\mu=(2 \pi, \pi) \in \mathbb{R}_{\downarrow}^{2} .
$$

Then

$$
\nabla f(x, y)=\binom{\frac{x}{2}-\frac{\sin 2 x}{4}}{\frac{y}{2}-\frac{\sin 2 y}{4}}, \quad \nabla^{2} f(x, y)=\left(\begin{array}{cc}
\sin ^{2} x & 0 \\
0 & \sin ^{2} y
\end{array}\right) .
$$

Using the representation in Theorem 4.13 we get

$$
\nabla^{2} f(\mu)=0, \quad \nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)[H, H]=h_{12}^{2},
$$

where

$$
H=\left(\begin{array}{ll}
h_{11} & h_{12} \\
h_{12} & h_{22}
\end{array}\right) .
$$

Then clearly

$$
\lambda_{\max }\left(\nabla^{2}(f \circ \lambda)(\operatorname{Diag} \mu)\right)=1>\lambda_{\max }\left(\nabla^{2} f(\mu)\right)=0 .
$$

In order to demonstrate a strict inequality between the smallest eigenvalues one needs to consider the function $-f(x, y)$ at the same point $\mu$.

Even though we may not have equalities in (8) at a particular matrix $Y$, if we consider the eigenvalues of $\nabla^{2} f(\lambda(Y))$ and $\nabla^{2}(f \circ \lambda)(Y)$ as $Y$ varies over an orthogonally invariant, convex set we can see that they vary within the same bounds. More precisely we have the following theorem. To make its proof precise, we need the main result from [9,11] saying that: A symmetric function $f$ is $\mathscr{C}^{2}$ if and only if $f \circ \lambda$ is, and $f$ is convex if and only if $f \circ \lambda$ is.

Theorem 7.2. Let $C$ be a convex and symmetric subset of $\mathbb{R}^{n}$, and let $f: C \rightarrow \mathbb{R}$ be symmetric, $\mathscr{C}^{2}$ function. Then

$$
\begin{equation*}
\min _{y \in C} \lambda_{\min }\left(\nabla^{2} f(y)\right)=\min _{Y \in \lambda^{-1}(C)} \lambda_{\min }\left(\nabla^{2}(f \circ \lambda)(Y)\right) . \tag{9}
\end{equation*}
$$

## Proof.

$$
\begin{aligned}
& \lambda_{\min }\left(\nabla^{2} f(y)\right) \geqslant \alpha \quad \forall y \in C \\
& \quad \Leftrightarrow \quad f-\frac{\alpha}{2}\|\cdot\|^{2} \quad \text { convex } \\
& \quad \Leftrightarrow \quad\left(f-\frac{\alpha}{2}\|\cdot\|^{2}\right) \circ \lambda \quad \text { convex } \\
& \quad \Leftrightarrow \quad f \circ \lambda-\frac{\alpha}{2}\|\cdot\|_{2}^{2} \quad \text { convex } \\
& \quad \Leftrightarrow \quad \lambda_{\min }\left(\nabla^{2}(f \circ \lambda)(Y)\right) \geqslant \alpha \quad \forall Y \in C .
\end{aligned}
$$

Remark 7.3. If we multiply both sides of Eq. (9) by -1 we will get

$$
\max _{y \in C} \lambda \max \left(\nabla^{2} f(y)\right)=\max _{Y \in \lambda^{-1}(C)} \lambda_{\max }\left(\nabla^{2}(f \circ \lambda)(Y)\right) .
$$

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