

Adaptive Rumor Spreading

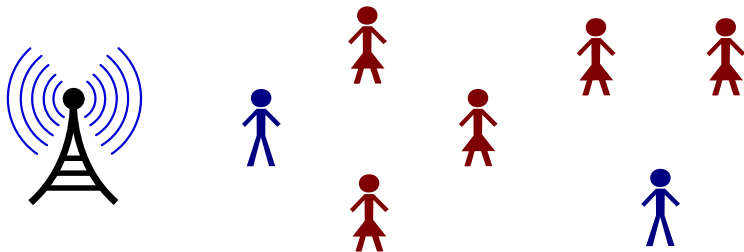
José Correa ¹ Marcos Kiwi ¹
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¹Universidad de Chile

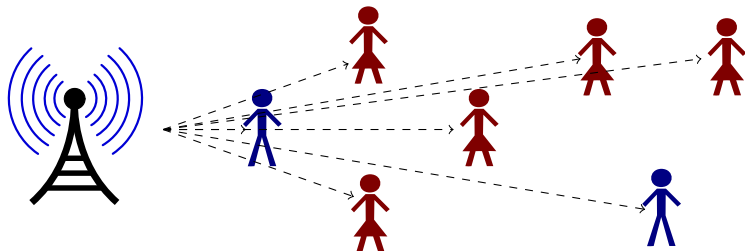
²VU Amsterdam and CWI

July 27, 2015

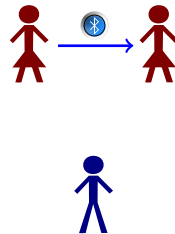
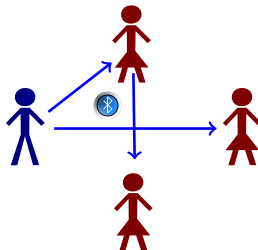
The situation



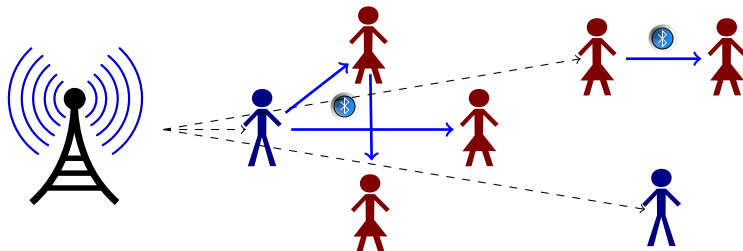
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Introduction

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- ▶ In viral marketing campaigns, the selection of vertices is crucial. [Domingos and Richardson \(2001\)](#)
- ▶ An agent (service provider) wants to efficiently speed up the communication process.

Rumor spreading

- ▶ Models differ in time and communication protocol. [Demers et al. \(1987\)](#) and [Boyd et al. \(2006\)](#)

Rumor spreading

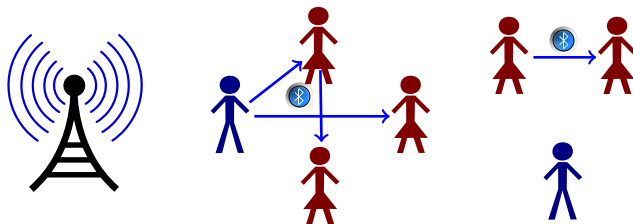
- ▶ Models differ in time and communication protocol. [Demers et al. \(1987\)](#) and [Boyd et al. \(2006\)](#)
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Rumor spreading

- ▶ Models differ in time and communication protocol. [Demers et al. \(1987\)](#) and [Boyd et al. \(2006\)](#)
- ▶ In simple cases, the time to activate all the network is mostly understood.
- ▶ Even in random networks the estimates are logarithmic in the number of nodes. [Doerr et al. \(2012\)](#) and [Chierichetti et al. \(2011\)](#)

Opportunistic networks

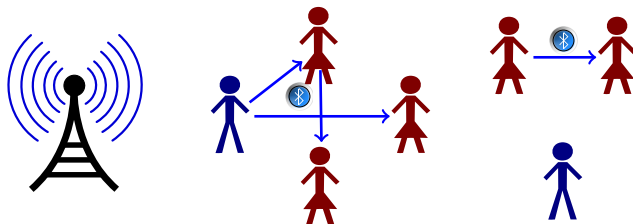
- ▶ We have an overload problem, an option is to exploit opportunistic communications.



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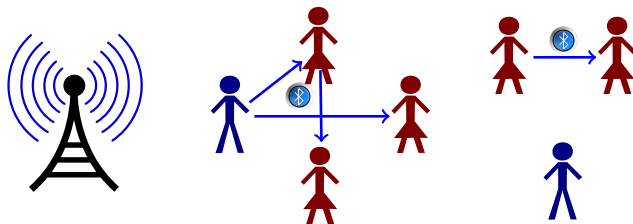
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- ▶ A fixed deadline scenario has been studied heuristically along with real large-scale data.

Whitbeck et al. (2011)



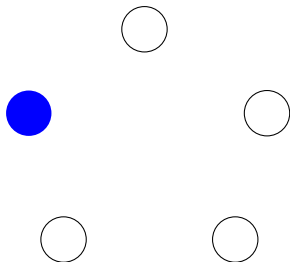
Opportunistic networks

- ▶ We have an overload problem, an option is to exploit opportunistic communications.
- ▶ A fixed deadline scenario has been studied heuristically along with real large-scale data. [Whitbeck et al. \(2011\)](#)
- ▶ Control theory based algorithms greatly outperform static ones. [Sciancalepore et al. \(2014\)](#)



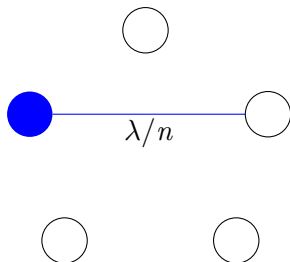
The model

- ▶ Bob communicates and shares information.



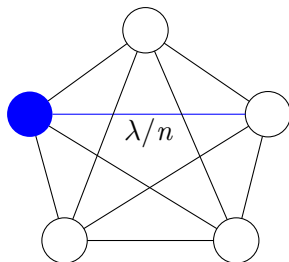
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- ▶ Every pair of nodes can meet and gossip.



The problem

- ▶ There is a unit cost for pushing the rumor.
- ▶ Opportunistic communications have no cost.
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We want a strategy that minimizes the overall number of pushes.

Adaptive and non-adaptive

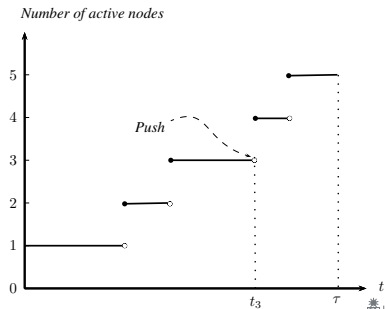
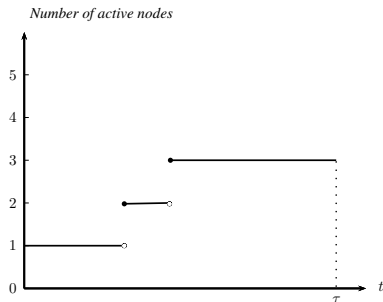
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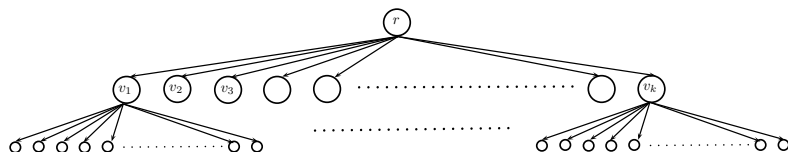
Main result

Define the adaptivity gap as the ratio between the expected costs of non-adaptive and adaptive.

Theorem

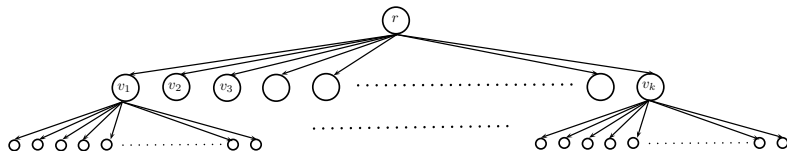
In the complete graph the adaptivity gap is constant.

Adaptive can be arbitrarily better



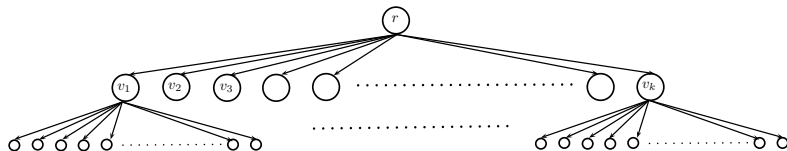
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- ▶ With a small deadline, non-adaptive activates all of the v_i 's.
- ▶ Adaptive activates only the root, then at some time t' pushes to the inactive v_i 's.

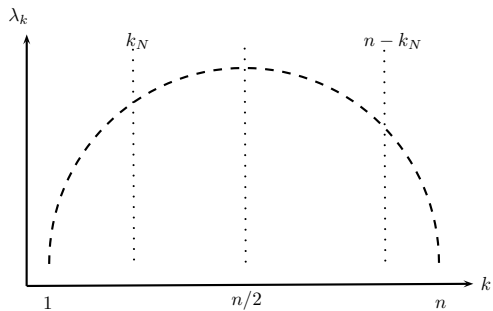


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- ▶ An adaptivity gap of $\frac{\log k}{\log \log k}$ is easy to prove.



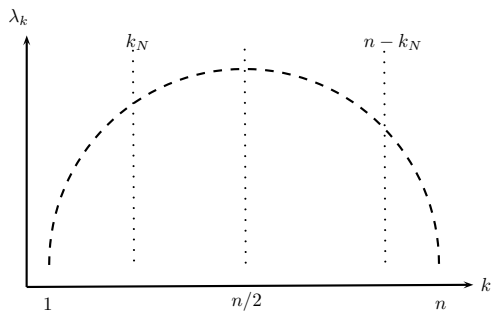
Non-adaptive



$$\lambda = 1.$$
$$\lambda_k := \frac{k(n-k)}{n}.$$

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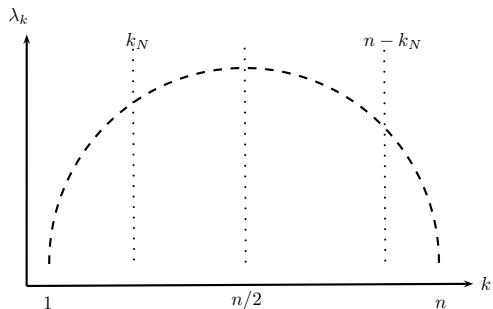
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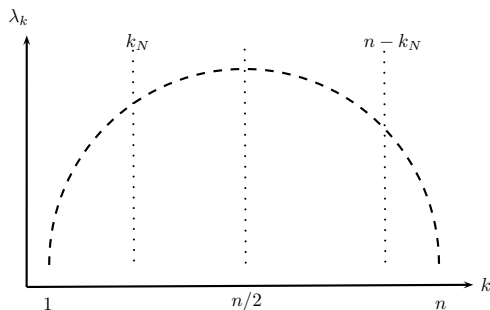
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Non-adaptive

- ▶ Optimal non-adaptive pays almost the same at $t = 0$ and at $t = \tau$.
 - A 2-approximation is easy to see.
- ▶ Non-adaptive does not push more than $n/2$ rumors. Therefore, neither adaptive.



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Big deadline: $\tau \geq (2 + \delta) \log n$

- ▶ Starting from a single active node, the time until everyone is active is $2 \log n + \mathcal{O}(1)$.
- ▶ The time is exponentially concentrated. Jason (1999)
- ▶ Just starting with one node has cost $1 + \varepsilon$, therefore adaptivity does not help.

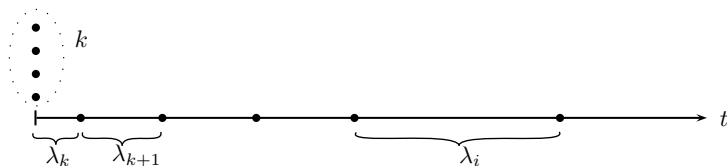
Small deadline: $\tau \leq 2 \log \log n$

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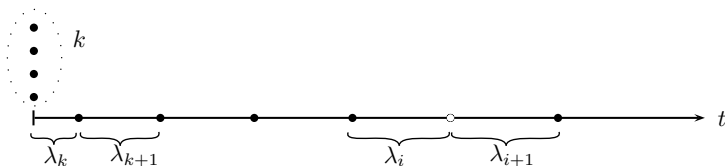
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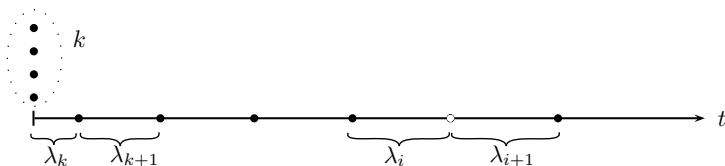
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- ▶ A push can be seen as adding a point.



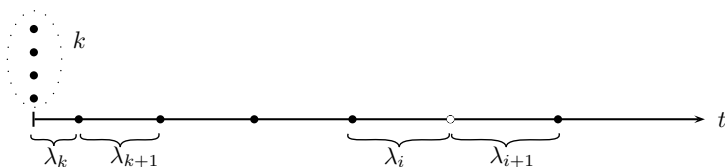
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- ▶ A clairvoyant strategy knows the realization, therefore outperforms adaptive.



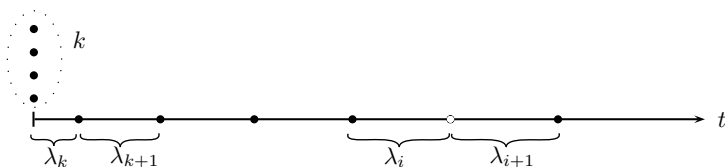
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- ▶ Clairvoyant chooses the best number of initial pushes, given the realization.



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In this case we can prove the gap to be $1 + o(1)$.

Other deadlines

Insight: adaptive interferes when the cost of pushing is less than or equal to that of not pushing, i.e.,

$$1 + \text{cost}(k + 1 \text{ active nodes}) \leq \text{cost}(k \text{ active nodes}). \quad (\star)$$

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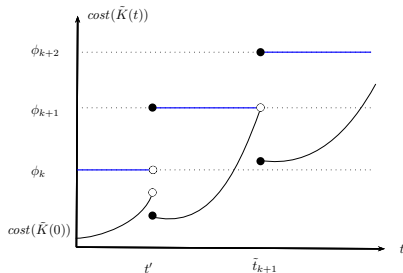
- ▶ A relaxed strategy pushes for free, but with certain conditions.
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- ▶ Relaxed outperforms adaptive.

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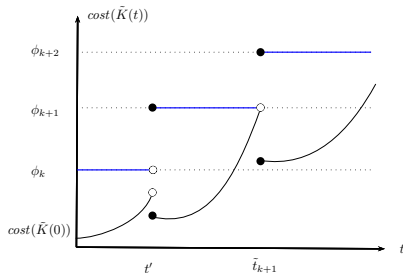
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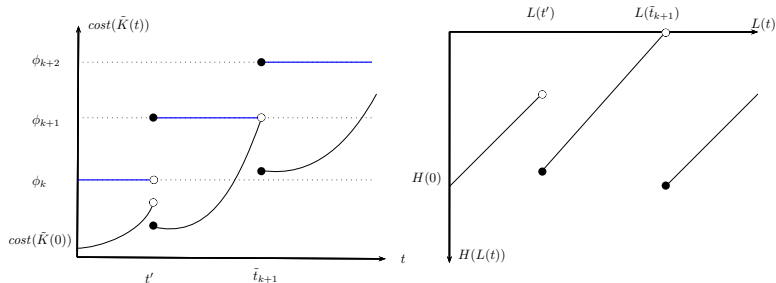
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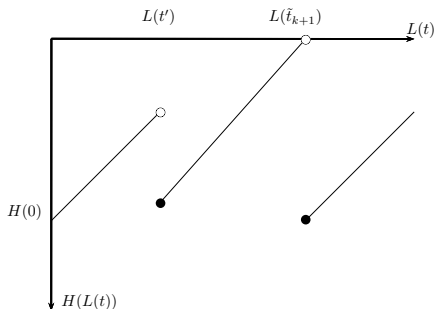
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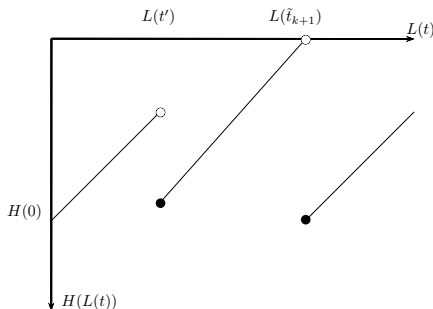
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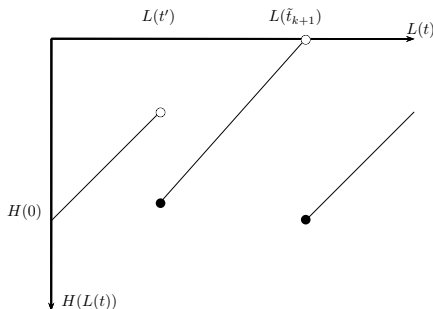
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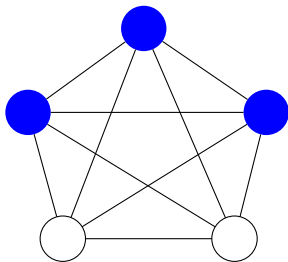
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- ▶ Essentially $H(s)$ is dominated by $s - 2 \text{Pois}(s)$.
- ▶ The number of times $H(s)$ touches zero is constant.



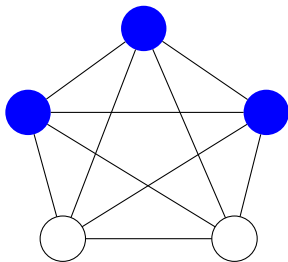
Additional results

- ▶ The target set version has a constant adaptivity gap.

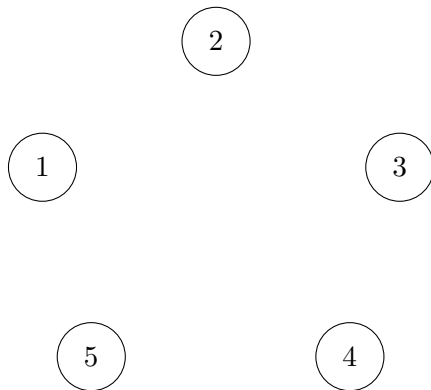


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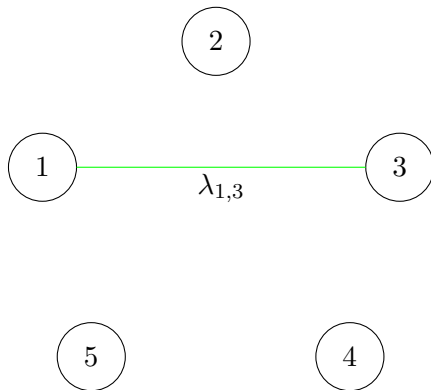
- ▶ The target set version has a constant adaptivity gap.
- ▶ The maximization problem has a $1 + o(1)$ adaptivity gap.



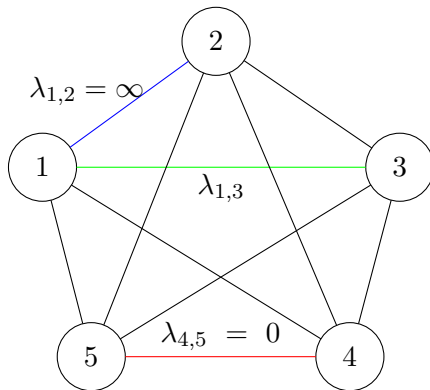
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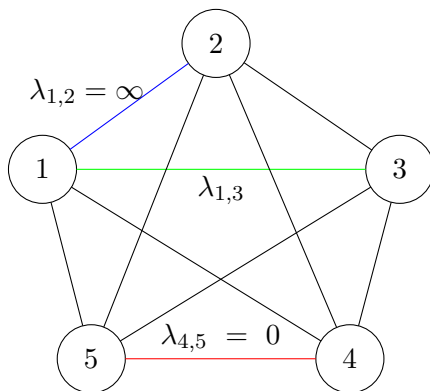


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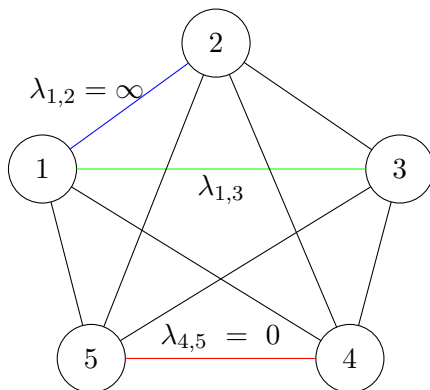
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Even the non-adaptive problem is difficult in this setting!



Conjectures and open problems

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 - High conductance/connectivity.
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- ▶ Additive gap for the complete graph is constant, i.e., $\text{COST}_{NA} - \text{COST}_A = \mathcal{O}(1)$.