| Mathematical Programming |
| :--- |
| OR 630 Fall 2005 |
| Instructor: Mike Todd |

Lecture 23
OR 630 Fall 2005

## Deeper Into the Ellipsoid Method

Given the polyhedron $Q:=\left\{x \in \mathbb{R}^{m}: A^{T} x \leq b\right\}$ where we assume:
(1) $Q \subseteq B(0, R)=\left\{x \in \mathbb{R}^{m}:\|x\| \leq R\right\}$ ( $Q$ possibly empty) and
(2) if $Q \neq \emptyset$ then $Q \supseteq B(\hat{x}, r)=\left\{x \in \mathbf{R}^{m}:\|x-\hat{x}\| \leq r\right\}$ for some (unknown) $\hat{x} \in \mathbf{R}^{m}$ and some (known) $0<r<R$,
our goal is to find a feasible point in $Q$ or show that $Q=\emptyset$.


Figure 1: A two-dimensional polyhedron $Q$ satisfying the initial assumptions for the ellipsoid method

To close in on a feasible point, we will construct a shrinking sequence of ellipsoids expressed as $E(z, B):=\left\{x \in \mathbb{R}^{m}:(x-z)^{T} B^{-1}(x-z) \leq 1\right\}$ for some center $z \in \mathbb{R}^{m}$ and some $B \in \mathbf{R}^{m \times m}$ with B symmetric and positive definite (i.e. $\forall v \neq 0: v^{T} B v>0 \Leftrightarrow$ the eigenvalues of $B$ are all positive) in the following manner:

Step 0: Set $z_{0}=0$ and $B_{0}=R^{2} I$. Then $Q \subseteq E\left(z_{0}, B_{0}\right)=: E_{0}$.
$\overline{\text { Step } \mathbf{k}}+1, \mathbf{k} \geq \mathbf{0}$ : Given $Q \subseteq E\left(z_{k}, B_{k}\right)=: E_{k}$, if $z_{k} \in Q$ then we have a feasible point STOP. If $z_{k} \notin Q$ and $k$ is "large enough" (see below) then we can conclude that Q is empty - STOP. Otherwise, generate $E_{k+1}:=E\left(z_{k+1}, B_{k+1}\right)$ by choosing some $a=a_{i} \neq 0$ where $a_{i}^{T} z_{k}>b_{i}$ (i.e. $z_{k}$ violates the $i$ th constraint of Q ), and letting $E_{k+1}$ be the minimum volume ellipsoid such that $E_{k+1} \supseteq E_{k}^{1 / 2}:=\left\{x \in E_{k}: a^{T} x \leq a^{T} z_{k}\right\}$. Clearly we have $Q \subseteq E_{k}^{1 / 2} \subseteq E_{k+1}$,
so we move on to the next iteration.

How large does $k$ have to be for us to determine that $Q$ is empty? If $\operatorname{vol}(\cdot)$ is the $m$-dimensional volume then let $\operatorname{Vol}(\cdot)$ be the scaled $m$-dimensional volume, i.e. $\operatorname{Vol}(\cdot)=$ $\frac{\operatorname{vol}(\cdot)}{\operatorname{vol}(B(0,1))}$. Then $\operatorname{Vol}\left(E_{0}\right)=R^{m} \operatorname{Vol}(B(0,1))=R^{m}$, and similarly, $\operatorname{Vol}(B(\hat{x}, r))=r^{m}$. So if $\operatorname{Vol}\left(E_{k}\right)<r^{m}$ then $E_{k}$ cannot contain $B(\hat{x}, r)$ and thus $Q$ must be empty. We will show later that $\operatorname{Vol}\left(E_{k+1}\right)<\exp \left(\frac{-1}{2(m+1)}\right) \operatorname{Vol} E_{k}$, and therefore we can conclude that $Q$ is empty when

$$
\begin{aligned}
\operatorname{Vol}\left(E_{k}\right)<\exp \left(\frac{-k}{2(m+1)}\right) \operatorname{Vol}\left(E_{0}\right) \leq r^{m} & \Rightarrow \exp \left(\frac{-k}{2(m+1)}\right) R^{m} \leq r^{m} \\
& \Rightarrow k \geq 2(m+1) m \ln \left(\frac{R}{r}\right) .
\end{aligned}
$$

We now prove some intermediate results that will help to establish the algorithm for an iteration. To simplify the notation going forward, when we refer to a specific iteration going from $E_{k}$ to $E_{k+1}$, we will drop any subscript $k$ and use + in place of $k+1\left(E_{+}:=E_{k+1}\right.$, etc).

Lemma 1 If $B$ is symmetric and positive definite then it has a symmetric, positive definite square root $B^{1 / 2}$ with $B^{1 / 2} B^{1 / 2}=B$. Moreover, $\operatorname{Vol}(E(z, B))=\sqrt{\operatorname{det}(B)}$.

Proof: We can leverage what we know about numbers and apply this first to diagonal matrices and then to symmetric matrices. $B$ can be factorized into $B=Q D Q^{T}$ where $Q$ is an orthogonal matrix $\left(Q^{T} Q=I\right)$ and $D$ is a diagonal matrix. Moreover, the columns of $Q$ are the eigenvectors of $B$ and the diagonal entries of $D$ are its eigenvalues, and thus all $d_{j j}$ are positive.

Then setting

$$
D^{1 / 2}=\left(\begin{array}{ccc}
\sqrt{d_{11}} & & \mathbf{0} \\
& \ddots & \\
\mathbf{0} & & \sqrt{d_{m m}}
\end{array}\right)
$$

and $B^{1 / 2}=Q D^{1 / 2} Q^{T}$ gives

$$
B^{1 / 2} B^{1 / 2}=\left(Q D^{1 / 2} Q^{T}\right)\left(Q D^{1 / 2} Q^{T}\right)=Q\left(D^{1 / 2} I D^{1 / 2}\right) Q^{T}=Q D Q^{T}=B
$$

Now note that

$$
x \in E(z, B) \Leftrightarrow(x-z)^{T} B^{-1}(x-z) \leq 1 \Leftrightarrow\left(B^{-1 / 2}(x-z)\right)^{T}\left(B^{-1 / 2}(x-z)\right) \leq 1 \Leftrightarrow x=z+B^{1 / 2} w
$$

for some $w \in B(0,1)$. So defining $X(w):=z+B^{1 / 2} w$ gives

$$
\begin{aligned}
\operatorname{Vol}(E(z, B)) & =\frac{\int_{x \in E(z, B)} 1 d x}{\operatorname{vol}(B(0,1))} \\
& =\frac{\int_{w \in B(0,1)} 1\left|\operatorname{det}\left(B^{1 / 2}\right)\right| d w}{\operatorname{vol}(B(0,1))} \\
& =\left|\operatorname{det}\left(B^{1 / 2}\right)\right| \frac{\operatorname{vol}(B(0,1))}{\operatorname{vol}(B(0,1))} \\
& =\left|\operatorname{det}\left(B^{1 / 2}\right)\right| \\
& =\sqrt{\operatorname{det}(B)}
\end{aligned}
$$

Lemma 1 confirms our earlier comment that $\operatorname{Vol}\left(E_{0}\right)=R^{m}$.
Lemma 2 If $B \in \mathbb{R}^{m \times m}$ is symmetric and positive definite and $a \in \mathbf{R}^{m}$ is non-zero then

$$
\bar{B}:=B-\sigma \frac{B a a^{T} B}{a^{T} B a}
$$

is symmetric and positive definite for $\sigma<1$ with $\operatorname{det}(\bar{B})=(1-\sigma) \operatorname{det}(B)$ and

$$
\bar{B}^{-1}=B^{-1}+\left(\frac{\sigma}{1-\sigma}\right)\left(\frac{a a^{T}}{a^{T} B a}\right) .
$$

Proof: $a^{T} B a>0$, so $\bar{B}$ is well-defined and clearly symmetric. We also have

$$
\begin{aligned}
\bar{B} & =B^{1 / 2}\left(I-\sigma \frac{B^{1 / 2} a a^{T} B^{1 / 2}}{\left(B^{1 / 2} a\right)^{T}\left(B^{1 / 2} a\right)}\right) B^{1 / 2} \\
& =B^{1 / 2}\left(I-\sigma \frac{u u^{T}}{u^{T} u}\right) B^{1 / 2}
\end{aligned}
$$

for $u=B^{1 / 2} a .\left(I-\sigma \frac{u u^{T}}{u^{T} u}\right)$ has an eigenvalue of $(1-\sigma)>0$ associated with the eigenvector $u$ and eigenvalue $1>0$ with multiplicity $(m-1)$ associated with the $(m-1)$-dimensional subspace orthogonal to $u$, so it is positive definite with determinant $(1-\sigma)$. Then $\forall v \neq 0$, $v^{T} \bar{B} v=\left(B^{1 / 2} v\right)^{T}\left(I-\sigma \frac{u u^{T}}{u^{T} u}\right)\left(B^{1 / 2} v\right)>0$, so $\bar{B}$ is positive definite, and

$$
\begin{aligned}
\operatorname{det}(\bar{B}) & =\operatorname{det}\left(B^{1 / 2}\right) \operatorname{det}\left(I-\sigma \frac{u T^{T}}{u^{T} u}\right) \operatorname{det}\left(B^{1 / 2}\right) \\
& =(1-\sigma) \operatorname{det}(B)
\end{aligned}
$$

Finally, $\bar{B}=B+v w^{T}$ for $v=-\sigma \frac{B a}{a^{T} B a}$ and $w=B a$, thus

$$
\begin{aligned}
\bar{B}^{-1} & =B^{-1}-\frac{B^{-1} v w^{T} B^{-1}}{1+w^{T} B^{-1} v} \\
& =B^{-1}+\frac{\sigma^{B^{-1} B a a^{T} B B^{-1}}}{1-\sigma \frac{a^{T} B a}{T^{T} B B^{-1} B a}} \\
& =B^{-1}+\left(\frac{\sigma}{1-\sigma}\right)\left(\frac{a a^{T}}{a^{T} B a}\right) .
\end{aligned}
$$

Lemma 3 For any $a \neq 0$, the minimum of $a^{T} x$ over $x \in E(z, B)$ is $a^{T} z-\sqrt{a^{T} B a}$ and is attained by $x=z-\frac{B a}{\sqrt{a^{T} B a}}$.

Proof: By Cauchy-Schwartz, if we minimize $\left(B^{1 / 2} a\right)^{T} w$ over the unit ball $B(0,1)$ then the optimal solution is $-\sqrt{a^{T} B a}$ and is attained by $w=-\frac{B^{1 / 2} a}{\sqrt{a^{T} B a}}$. If we apply the transformation $X(w)$ as in the proof of Lemma 1 then we have the desired result.


Figure 2: The transformation used in the proof of Lemma 3.

We are now ready to look at the algorithm for performing an iteration.
Theorem 1 Given an ellipsoid $E=E(z, B)$ and $0 \neq a \in \mathbb{R}^{m}$, the minimum volume ellipsoid containing $E^{1 / 2}=\left\{x \in E: a^{T} x \leq a^{T} z\right\}$ is $E_{+}=E\left(z_{+}, B_{+}\right)$for

$$
\begin{aligned}
& z_{+}:=z-\tau \frac{B a}{\sqrt{a^{T} B a}} \text { and } \\
& B_{+}:=\delta\left(B-\sigma \frac{B a a^{T} B}{a^{T} B a}\right)
\end{aligned}
$$

where $\tau=\frac{1}{m+1}, \delta=\frac{m^{2}}{m^{2}-1}$, and $\sigma=\frac{2}{m+1}$. Moreover,

$$
\frac{\operatorname{Vol}\left(E_{+}\right)}{\operatorname{Vol}(E)}<\exp \left(\frac{-1}{2(m+1)}\right) .
$$

But this theorem is just the special case where $\alpha=0$ of:
Theorem 2 Given an ellipsoid $E=E(z, B)$ and $0 \neq a \in \mathbb{R}^{m}$, the minimum volume ellipsoid containing $E_{\alpha}=\left\{x \in E: a^{T} x \leq a^{T} z-\alpha \sqrt{a^{T} B a}\right\}$ for $-\frac{1}{m} \leq \alpha<1$ is $E_{+}=E\left(z_{+}, B_{+}\right)$for

$$
\begin{aligned}
z_{+} & :=z-\tau \frac{B a}{\sqrt{a^{T} B a}} \text { and } \\
B_{+} & :=\delta\left(B-\sigma \frac{B a a^{T} B}{a^{T} B a}\right)
\end{aligned}
$$

where $\tau=\frac{1+m \alpha}{m+1}, \delta=\frac{\left(1-\alpha^{2}\right) m^{2}}{m^{2}-1}$, and $\sigma=\frac{2(1+m \alpha)}{(m+1)(1+\alpha)}$. Also,

$$
\frac{\operatorname{Vol}\left(E_{+}\right)}{\operatorname{Vol}(E)}=\left(\frac{m}{m+1}\right)\left(\frac{m^{2}}{m^{2}-1}\right)^{\frac{m-1}{2}}(1-\alpha)\left(1-\alpha^{2}\right)^{\frac{m-1}{2}} .
$$

For $\alpha=0$, this ratio is less than $\exp \left(\frac{-1}{2(m+1)}\right)$.


Figure 3: An illustration of Theorem 2. Note that the parallel lines are the linear constraints discussed in the proof.

Proof: We will not prove that $E_{+}$is the minimum volume ellipsoid containing $E_{\alpha}$, but we will show that the volume ratio between $E$ and $E_{+}$for $\alpha=0$ holds as in the theorem, and thus our earlier conclusions regarding the necessary number of iterations are valid.

We begin by noting that $x \in E_{\alpha}$ implies that $x$ satisfies the quadratic constraint $(x-z)^{T} B^{-1}(x-z) \leq 1$ and the linear constraint $a^{T} x \leq a^{T} z-\alpha \sqrt{a^{T} B a}$. But from Lemma 3, we know that any $x \in E$ also satisfies the linear constraint $a^{T} x \geq a^{T} z-\sqrt{a^{T} B a}$. Setting $\bar{a}=\frac{a}{\sqrt{a^{T} B a}}$, combining the two linear inequalities, and writing in terms of $(x-z)$ gives us a second quadratic inequality, $\left(\bar{a}^{T}(x-z)+\alpha\right)\left(\bar{a}^{T}(x-z)+1\right) \leq 0$. Now take a weighted combination of the two quadratic constraints, multiplying the first by $(1-\sigma)$ and the second by $\sigma$. We are left with

$$
(x-z)^{T}\left((1-\sigma) B^{-1}+\sigma \bar{a} \overline{a^{T}}\right)(x-z)+\sigma(1+\alpha) \bar{a}^{T}(x-z) \leq(1-\sigma)-\sigma \alpha
$$

We will complete this proof in the next lecture.

1. a) Suppose that $E\left(z_{+}, B_{+}\right)$is the minimum volume ellipsoid containing

$$
\left\{x \in E(z, B): a^{T} x \leq a^{T} z-\alpha\left(a^{T} B a\right)^{\frac{1}{2}}\right\}
$$

where $\alpha>-1 / m$ and $0 \neq a \in \mathbb{R}^{m}$. Show that

$$
a^{T} z-\alpha\left(a^{T} B a\right)^{\frac{1}{2}}=a^{T} z_{+}+\frac{1}{m}\left(a^{T} B_{+} a\right)^{\frac{1}{2}}
$$

i.e., the "depth" of the constraint that was used to make the cut is exactly $-1 / m$ in the new ellipsoid.
b) Suppose we apply the ellipsoid method to try to find a point in

$$
\left\{x \in \mathbb{R}^{2}: x_{1} \leq \frac{1}{2},-x_{1} \leq-\frac{1}{2},-x_{2} \leq-\frac{1}{4}, x_{2} \leq \frac{1}{2}\right\}
$$

starting with $E_{0}:=\left\{x \in \mathbb{R}^{2}:\|x\| \leq 1\right\}$. At each iteration, we choose as the cut to define the new ellipsoid the constraint $a_{i}^{T} x \leq b_{i}$ with maximum depth

$$
\alpha_{i}:=\frac{a_{i}^{T} z-b_{i}}{\left(a_{i}^{T} B a_{i}\right)^{\frac{1}{2}}},
$$

stopping if all $\alpha_{i}$ 's are nonpositive, and using the deep cut method (i.e., the ellipsoid is updated as in (a)).
(i) What are the depths of all the constraints, and what cut is chosen, at the first iteration?
(ii) What are the depths of all the constraints, and what cut is chosen, at the second iteration?
2. Let $A \in \mathbb{R}^{m \times n}$ have rank $m$, and let $P_{A}:=I-A^{T}\left(A A^{T}\right)^{-1} A$.
a) Show that $P_{A}=P_{A}^{T}=P_{A}^{2}$ and hence that $u^{T} P_{A} u=\left\|P_{A} u\right\|^{2}$ for every $u \in \mathbb{R}^{n}$. (So $P_{A}$ is positive semidefinite: $u^{T} P_{A} u \geq 0$ for all $u$.)
b) Show that $P_{A} v=0$ for every $v$ in the range space of $A^{T}$, and $P_{A} v=v$ for every $v$ in the null space of $A$.
3. Consider the standard-form LP problem and its dual, where $A \in \mathbf{R}^{m \times n}$ has rank $m$, and suppose $x \in \mathcal{F}^{0}(P)$ and $(y, s) \in \mathcal{F}^{0}(D)$. Let $\mu=x^{T} s / n$, and suppose that $x_{j} s_{j} \geq \gamma \mu$ for all $j$, for some positive $\gamma$. Suppose $(\Delta x, \Delta y, \Delta s)$ is the solution to

$$
\left.\begin{array}{rl}
A^{T} \Delta y+\Delta s & =0 \\
A \Delta x & =0 \\
S \Delta x & +X \Delta s
\end{array}\right)=\sigma \mu e-X S e, ~ l
$$

for some $0 \leq \sigma \leq 1$. Let $(x(\alpha), y(\alpha), s(\alpha)):=(x, y, s)+\alpha(\Delta x, \Delta y, \Delta s)$ for $0 \leq \alpha \leq 1$.
a) Show that $\Delta x^{T} \Delta s=0$ and that $\mu(\alpha):=x(\alpha)^{T} s(\alpha) / n=(1-\alpha+\alpha \sigma) \mu$.
b) Let $\bar{\alpha}:=\max \{\hat{\alpha} \in[0,1]: X(\alpha) S(\alpha) e \geq \gamma \mu(\alpha) e$ for all $\alpha \in[0, \hat{\alpha}]\}$, and let $\left(x_{+}, y_{+}, s_{+}\right):=$ $(x(\bar{\alpha}), y(\bar{\alpha}), s(\bar{\alpha}))$. Show that either $x_{+}$is optimal in $(P)$ and $\left(y_{+}, s_{+}\right)$in $(D)$, or $x_{+} \in \mathcal{F}^{0}(P)$ and $\left(y_{+}, s_{+}\right) \in \mathcal{F}^{0}(D)$, with only the second possibility if $\sigma>0$.

