

Homework 2 Solutions.

1. Let  $P_i \subseteq \mathbf{R}^{d_i}$  be a nonempty polyhedron defined by  $n_i$  inequalities,  $i = 1, 2$ , and let  $P := P_1 \times P_2 := \{(x_1; x_2) : x_1 \in P_1, x_2 \in P_2\}$ .

a) Show that  $P$  is a polyhedron in  $\mathbf{R}^d$  defined by  $n$  inequalities, with  $d = d_1 + d_2$  and  $n = n_1 + n_2$ , bounded iff both  $P_1$  and  $P_2$  are.

b) Show that, if  $v_i$  is a vertex of  $P_i$ ,  $i = 1, 2$ , then  $(v_1; v_2)$  is a vertex of  $P$ . Show that all vertices of  $P$  arise in this way.

c) Suppose  $v_i, v'_i$  are vertices of  $P_i$ ,  $i = 1, 2$ . Show that  $[(v_1; v_2), (v'_1; v'_2)]$  is an edge of  $P$  if  $v_1 = v'_1$  and  $[v_2, v'_2]$  is an edge of  $P_2$ , or if  $[v_1, v'_1]$  is an edge of  $P_1$  and  $v_2 = v'_2$ . (In fact, all edges of  $P$  arise in this way, but you need not prove it; you can assume it for (d).)

d) Show that  $\delta(P_1 \times P_2) = \delta(P_1) + \delta(P_2)$ .

(This product construction allows you to relate the Hirsch conjecture (of course, now known to be false) for one value of  $(d, n)$  to that for other values. Another such construction, the “wedge,” converts the polyhedron  $Q := \{x \in \mathbf{R}^d : Ax \leq b, a^T x \leq \beta\}$  into the polyhedron  $Q' := \{(x; \xi) \in \mathbf{R}^{d+1} : Ax \leq b, a^T x + \xi \leq \beta, -\xi \leq 0\}$ . You might want to think of parts (a) – (c) above for  $Q$  and  $Q'$ . Using these ideas, one can show that the conjecture is true for all values of  $(d, n)$  iff it holds for all  $d$  and  $n = 2d$ : this is the so-called  $d$ -step conjecture. Similar arguments were used by Santos to modify his “spindle” example in dimension 5 to give a counterexample to the Hirsch conjecture in dimension 43, and to construct counterexamples for all higher dimensions.)

a) Let  $P_i = \{x_i \in \mathbf{R}^{d_i} : A_i x_i \leq b_i\}$ ,  $i = 1, 2$ , where  $A_i$  and  $b_i$  have  $n_i$  rows. Then  $P = \{(x_1; x_2) \in \mathbf{R}^d : A_i x_i \leq b_i, i = 1, 2\}$  and is hence a  $d$ -polytope defined by  $n$  inequalities. If  $\|x_i\| \leq \rho_i$  for all  $x_i \in P_i$ , for  $i = 1, 2$ , then  $\|x\| \leq \rho_1 + \rho_2$  for all  $x \in P$ , so  $P$  is bounded. Conversely, if say  $\|x_1\|$  is unbounded for  $x_1 \in P_1$ , then choose any fixed  $x_2 \in P_2$  and note that  $\|(x_1; x_2)\|$  is then unbounded for  $(x_1; x_2) \in P$ , so  $P$  is unbounded.

b) There is an objective function  $c_i^T x_i$  that is minimized uniquely over  $P_i$  at  $v_i$ ,  $i = 1, 2$ . Then  $c^T x := c_1^T x_1 + c_2^T x_2$  is minimized uniquely over  $P$  at  $(v_1; v_2)$ , which is therefore a vertex. Conversely, if  $c^T x := c_1^T x_1 + c_2^T x_2$  is minimized uniquely over  $P$  at  $(v_1; v_2)$ , then  $c_i^T x_i$  is minimized uniquely over  $P_i$  at  $v_i$ ,  $i = 1, 2$ , so each  $v_i$  is a vertex of  $P_i$ .

c) Suppose  $c_1^T x_1$  is minimized uniquely over  $P_1$  by  $v_1$ , and the set of minimizers of  $c_2^T x_2$  over  $P_2$  is the line segment joining  $v_2$  and  $v'_2$ . Then the set of minimizers of  $c^T x := c_1^T x_1 + c_2^T x_2$  is exactly the line segment joining  $(v_1; v_2)$  and  $(v_1; v'_2)$ , showing that this is an edge. The same argument works in the other case. To show the converse, note that if  $c^T x$  as above defines an edge of  $P$ , and neither  $c_1^T x_1$  nor  $c_2^T x_2$  is uniquely minimized, then the set of minimizers of  $c^T x$  contains at least a line segment times a line segment, a contradiction. Suppose therefore without loss of generality that  $c_1^T x_1$  is minimized uniquely over  $P_1$  at  $v_1$ . Now if  $c_2^T x_2$  is minimized over  $P_2$  at more than an edge of  $P_2$ , we again get a contradiction.

d) Let  $(v_1; v_2)$  and  $(w_1; w_2)$  be two vertices of  $P$ . There is a path from  $v_1$  to  $w_1$  in  $P_1$  of length at most  $\delta(P_1)$ , which gives a path of the same length from  $(v_1; v_2)$  to  $(w_1; v_2)$  in  $P$  by just holding the second component fixed. Similarly, there is a path from  $(w_1; v_2)$  to  $(w_1; w_2)$  of length at most  $\delta(P_2)$  holding the first component fixed. Concatenating these two paths gives one of length at most  $\delta(P_1) + \delta(P_2)$ . To show that the diameter is at least this sum, let  $v_i$  and  $w_i$  be vertices of  $P_i$  a distance  $\delta(P_i)$  apart,  $i = 1, 2$ . Then any path from  $(v_1; v_2)$  to  $(w_1; w_2)$  gives by projection on its two components a path from  $v_1$  to  $w_1$  and one from  $v_2$  to  $w_2$ , and so its total length is at least  $\delta(P_1) + \delta(P_2)$ .

2. In certain combinatorial optimization problems, the polyhedron defined by certain classes of inequalities is not a 0-1 polytope, but a polytope whose every vertex has components taking on only the values 0, 1/2, or 1. Call such a polytope a (0,1/2,1)-polytope.

Show that every (0,1/2,1)-polytope in  $\mathbf{R}^d$  has diameter at most  $2d - 1$ . Prove that there is a (0,1/2,1)-polytope in  $\mathbf{R}^d$  with diameter  $\lfloor 3d/2 \rfloor$  (first consider  $d = 1, 2$  and then see if you can blow these examples up to higher dimensions.)

The proof is by induction, being trivial for  $d = 1$  (there are seven cases, including the empty polytope). Suppose it is true for (0,1/2,1)-polytopes of dimension at most  $d - 1$ , and consider one in  $\mathbf{R}^d$ , say  $P$ , and two vertices of  $P$ , say  $v$  and  $w$ .

a) If  $v_1 = w_1 = \alpha$ , for  $\alpha = 0$  or  $1$ , let  $Q := \{x \in P : x_1 = \alpha\}$ . Then  $v$  and  $w$  are vertices of  $Q$  (you can prove this using an argument as in Q1, or just assume it). By omitting its first coordinate,  $Q$  can be thought of as a polytope in  $\mathbf{R}^{d-1}$ , so by the inductive hypothesis (since all its vertices are also vertices of  $P$  by an argument like that in Q1, so (0,1/2,1)-valued), there is a path from  $v$  to  $w$  in  $Q$  of length at most  $2(d-1) - 1$ . This is also a path from  $v$  to  $w$  in  $P$ .

b) If  $v_1$  is 0 or 1 (assume wlog the first), and  $w_1 = 1/2$ , then  $w$  is not optimal in  $\min\{x_1 : x \in P\}$ , so since local optimality implies global optimality for linear optimization in a polytope, there is a vertex  $z$  adjacent to  $w$  with  $z_1 < w_1$ . Hence  $z_1 = 0$ . By a), there is a path in  $P$  from  $v$  to  $z$  of length at most  $2(d-1) - 1$ , so one from  $v$  to  $w$  of length at most  $2d - 2$ .

c) If  $v_1 = 0$  and  $w_1 = 1$  (or vice versa), then by the same argument as in (b), there is a vertex  $z$  of  $P$  adjacent to  $w$  with  $z_1 = 0$  or  $1/2$ . Then using (a) or (b), there is a path in  $P$  from  $v$  to  $z$  of length at most  $2d - 2$ , so one from  $v$  to  $w$  of length at most  $2d - 1$ .

d) If  $v_1 = w_1 = 1/2$ , then either  $x_1 \geq 1/2$  for all  $x \in P$ , or  $x_1 < 1/2$  for some  $x \in P$ . In the first subcase,  $\{x : x_1 = 1/2\}$  is a supporting hyperplane to  $P$ , so  $Q := \{x \in P : x_1 = 1/2\}$  is a (0,1/2,1)-polytope with all its vertices (including  $v$  and  $w$ ) also vertices of  $P$ . As in (a), there is a path in  $Q$  (hence in  $P$ ) from  $v$  to  $w$  of length at most  $2(d-1) - 1$ . In the second subcase, as in (b) there is a vertex  $u$  adjacent to  $v$  with  $u_1 = 0$ , and a vertex  $z$  adjacent to  $w$  with  $z_1 = 0$ . By case (a), there is a path in  $P$  from  $u$  to  $z$  of length at most  $2(d-1) - 1$ , so one from  $v$  to  $w$  of length at most  $2d - 1$ .

This completes the inductive step and the proof.

The proof of existence of the bad examples is also by induction, starting with  $P_1 = [0, 1]$  in  $\mathbf{R}^1$  and  $P_2 = \{x \in \mathbf{R}^2 : 0 \leq x_j \leq 1, j = 1, 2, 1/2 \leq x_1 + x_2 \leq 3/2\}$  in  $\mathbf{R}^2$ . These have the required diameters 1 and 3. For larger  $d$ , define  $P_d = P_2 \times P_{d-2}$ . This is a (0,1/2,1)-polytope in  $\mathbf{R}^d$ , with diameter  $\delta(P_2) + \delta(P_{d-2})$  by Q1, and this is  $3 + \lfloor 3(d-2)/2 \rfloor = \lfloor 3d/2 \rfloor$  as desired.

3. a) Consider a polyhedron  $P$  and a vertex  $v$  of  $P$  that uniquely minimizes  $c^T x$  over  $P$ . Show that  $\{x \in P : c^T x \leq \gamma\}$  is bounded for every  $\gamma > c^T v$ .

b) Klee and Walkup constructed an (unbounded) polyhedron of dimension 4 with 8 facets and diameter 5  $>$  8 - 4 violating the Hirsch conjecture, and from this (see Q1) a polyhedron  $P$  of dimension  $d = 8$  with  $n = 16$  facets and diameter 10 =  $n - d + 2$ , also violating the conjecture. Hence  $P$  has two vertices a distance 10 apart. Use part (a) to construct a polytope  $Q$  of dimension 8 with 17 facets and two vertices  $v$  and  $w$  of  $Q$  so that:

- (i) some linear objective function  $c^T x$  is minimized uniquely over  $Q$  by  $v$ ; and
- (ii) every path from  $w$  to  $v$  on which  $c^T x$  is monotonically decreasing uses at least 10  $>$  17 - 8 edges.

(This shows that the “monotonic” Hirsch conjecture is false even for 8-dimensional polytopes. In fact, using projective transformations instead of an extra bounding hyperplane, one can show that it fails even for dimension 4.)

a) If  $\{x \in P : c^T x \leq \gamma\}$  is not bounded, it contains a ray  $\{u + \lambda w : \lambda \geq 0\}$  for some nonzero  $w$ . Because of the extra constraint,  $c^T w \leq 0$ . If  $c^T w < 0$ , then  $c^T x$  is unbounded below on  $P$ , a contradiction, while if  $c^T w = 0$ , then  $v + \lambda w$ ,  $\lambda \geq 0$  shows that  $c^T x$  is not uniquely minimized by  $v$ , again a contradiction. (Here we have used the representation theorem for polyhedra, which implies that the direction of any ray in  $Q$  also is the direction of a ray from every point of  $Q$ .)

b) Let  $v$  and  $w$  be two vertices of  $P$  a distance 10 apart. Choose  $c$  so that  $c^T x$  is uniquely minimized over  $P$  by  $v$ , and choose  $\gamma$  greater than  $c^T u$  for all vertices  $u$  of  $P$ . Define  $Q$  as in (a) using this  $c$  and  $\gamma$ . Then  $c^T x$  is uniquely minimized over  $Q$  by  $v$ , so  $v$  is a vertex of  $Q$ , and if  $\tilde{c}^T x$  is uniquely minimized over  $P$  by  $w$ , it is also uniquely minimized over  $Q$  by  $w$ , so  $w$  is a vertex of  $Q$ ; similarly, every  $u$  that is a vertex of  $P$  is also a vertex of  $Q$ . Moreover, every vertex  $u$  of  $Q$  with  $c^T x < \gamma$  is a vertex of  $P$ : take the same objective that is uniquely minimized over  $Q$  at  $u$  and use “local implies global” to show that it is also minimized over  $P$  at  $u$ . Finally, any edge of  $Q$  between two vertices  $u$  and  $u'$  with  $c^T x < \gamma$  is also an edge of  $P$ , by the same reasoning.

Now consider any path of vertices from  $w$  to  $v$  on which  $c^T x$  is monotonically decreasing. Then every vertex on this path has  $c^T x \leq c^T w < \gamma$ . It follows that such vertices cannot be on the new facet defined by  $c^T x = \gamma$ , so they are all vertices of  $P$ . Since every path in  $P$  from  $w$  to  $v$  contains at least 10 edges, so does every monotonic path in  $Q$  from  $w$  to  $v$ .