ORIE 6300 Mathematical Programming I

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Recitation 5

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Topic: Transportation Problem

Problem Definition and Formulation¹

Suppose there is a set, S, of suppliers, each with supply s_i and a set, D, of customers each with demand d_j that must be met. Further, suppose that each unit shipped from supply node i to demand node j incurs a cost c_{ij} . Find a minimum-cost shipping scheme that satisfies all the demand and supply restrictions.

Clearly, this problem is only feasible if $\sum_i s_i \ge \sum_j d_j$. Without loss of generality, suppose $\sum_i s_i = \sum_j d_j$ since otherwise we can set a dummy demand node k with $d_k = \sum_i s_i - \sum_j d_j$. Then we can formulate this as an linear program by:

$$\min \begin{array}{ll} \sum_{i \in S, j \in D} c_{ij} x_{ij} \\ \text{s.t.} & \sum_{j \in D} x_{ij} = s_i \quad \forall i \in S \\ & \sum_{i \in S} x_{ij} = d_j \quad \forall j \in D \\ & x_{ij} \geq 0. \end{array}$$

In some cases, we might wish to restrict the value of x_{ij} to be integral.

First, note that the rows of the constraint matrix are linearly dependent because:

$$\sum_{i \in S} s_i = \sum_{i \in S} \sum_{j \in D} x_{ij} = \sum_{j \in D} \sum_{i \in S} x_{ij} = \sum_{j \in D} d_j$$

i.e., adding all the rows in the first constraint set gives the same result as adding all the rows of the second constraint set. Hence, without loss of generality, we can remove one constraint arbitrarily.

Let |S| = m, |D| = n. Consider a graphical representation of this problem where G is bipartite graph with vertex sets corresponding to S and D and an edge set $E = S \times D$, i.e., $\{i, j\} \in E$ for every $i \in S$, $j \in D$. Note that each decision variable corresponds to an edge in the graph. Hence, a basic solution to the LP corresponds to some subgraph.

Claim 1 The graph corresponding to a basic solution to the LP doesn't contain cycles.

Proof: Let C be a cycle in the corresponding subgraph induced by the basic solution. Then $C = i_1 \rightarrow j_1 \rightarrow \ldots \rightarrow j_k \rightarrow i_1$ where $i_l \in S$, $j_l \in D$. Consider the vector x which equals 1 if x_i corresponds a cycle edge from S to D, -1 if x_i corresponds to a cycle edge from D to S, and 0 otherwise.

Note that in any cycle in our graph, every vertex k in the cycle has exactly one edge x_{ik} going from S to D and one edge x_{kj} going from D to S (or vice versa). Hence, it must be that Ax = 0, where A is our constraint matrix.

¹Based on previous notes of Maurice Cheung

So, consider any basis, B and suppose C is a cycle using only our basis variables. Let A_B be the corresponding basis matrix and x_B be the matching components of x. Since $x_i = 0$ for $i \notin B$, $0 = Ax = [A_B|A_N][x_B|x_N] = A_Bx_B + A_N 0 = A_Bx_B$. Hence, x_B is a non-zero element in the null space of A_B , so B is not a basis.

Noting that our graph has n + m vertices, and each basis has n + m - 1 edges (since there are that many constraints), and each basis cannot contain a cycle, it follows that each basic solution corresponds to a spanning tree of our graph.

A Simplex-like Algorithm

First, note that linear dependence of the primal constraints is equivalent to linear dependence of the dual variables. Since there is no non-negativity in the dual problem, we can choose one dual variable and set it arbitrarily (for example, set it to 0 for convenience).

Let's see how a simplex-like algorithm can be used to solve the Transportation Problem. Using the characterization of basic feasible solution, notice that if we add an edge corresponding to a non-basic variable to the subgraph spanned by the edges corresponding to the basic variables, this creates a unique cycle. The algorithm is as follows:

Initialization: A basic feasible solution, x, to the primal LP

Step 1: Choose a dual variable and set it arbitrarily.

Step 2: Solve for the other dual variables to maintain the complementary slackness condition, i.e., if x_{ij} is basic, then $u_i + v_j = c_{ij}$.

Step 3: For every non-basic edge $\{i, j\}$, compute the reduced costs $\bar{c}_{ij} = c_{ij} - u_i - v_j$. If all reduced costs are non-negative, STOP: Dual solution is feasible. Else, choose x_{ij} such that $\bar{c}_{ij} < 0$. This will be the entering basic variable (this create a cycle in the graph).

Step 4: Alternatingly increase (from $i \to j$ and decrease (from $j \to k$) flow around edges in the cycle to preserve 0 net flow. Let $\delta = \min_{(i,j)} \{x_{ij} : x_{ij} \text{ basic variable }, (i, j) \text{ a decreasing edge} \}$. Increase all "forward" edges by δ , decrease all "backwards" edges by δ . Remove from the basis an edge which achieves the minimum. Goto Step 1.