## ORIE 6300 Mathematical Programming I

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## Recitation 4

Lecturer: Chaoxu Tong Topic: Pointed Polyhedra

In class, we saw that every bounded polyhedra is a polytope in the set of convex combination of its vertices.<sup>1</sup> Now we will extend the theory to pointed polyhedra (i.e., those that contain no lines).

**Definition 1** A polyhedron Q is pointed if there is no  $y \in Q$  and  $d \neq 0$  such that for any  $\lambda \in \mathbb{R}$ ,

$$y + \lambda d \in Q$$

**Definition 2** Let C be a nonempty convex set: then the <u>recession cone</u> of C, rec(C), is

$${d \in R^m : \forall x \in C, \forall \alpha \ge 0, x + \alpha d \in C}.$$

**Proposition 1** If C is a nonempty set then rec(C) is a nonempty convex cone.

**Proof:** Let  $d_1, d_2 \in rec(C), \lambda_1, \lambda_2 \geq 0$ . We want to show that  $\lambda_1 d_1 + \lambda_2 d_2 \in rec(C)$ . For any  $x \in C$  and any  $\alpha > 0$ 

$$x + \alpha(\lambda_1 d_1 + \lambda_2 d_2) = [x + (\alpha \lambda_1) d_1] + (\alpha \lambda_2) d_2.$$

The quantity in brackets lies in C since  $\alpha \lambda_1 \geq 0$  and  $d_1 \in rec(C)$ , and then the desired vector lies in C because  $\alpha \lambda_1 \geq 0$  and  $d_2 \in rec(C)$ . Also,  $0 \in rec(C)$  by definition.

**Proposition 2** For  $Q := \{ y \in \mathbb{R}^m : A^T y \leq c \}$  then (if Q is nonempty)

$$rec(Q) = \{ d \in \mathbb{R}^m : A^T d \le 0 \}.$$

**Proof:** 

⊃:

if  $A^T d \leq 0$  then for any  $y \in Q, \alpha \geq 0$ .

$$A^{T}(y + \alpha d) = A^{T}y + \alpha A^{T}d$$

$$\leq c + 0$$

$$= c.$$

hence  $(y + \alpha d) \in Q$ .

 $\subset$ :

Suppose  $d \in rec(Q)$ , and choose any  $y \in Q$ . Then  $\forall \alpha \geq 0$ 

$$A^T(y+\alpha d) = A^Ty + \alpha A^Td$$
 
$$\leq c$$
 This implies 
$$A^Ty \leq c$$
 and 
$$A^Td \leq 0$$

otherwise, the above would fail for large  $\alpha$ 

<sup>&</sup>lt;sup>1</sup>Based on previous notes of Maurice Cheung

**Theorem 3** (Representation of Pointed Polyhedra). Let Q (defined as in Proposition 2) be a nonempty pointed polyhedron, and let P be the set of all convex combinations of its vertices and K be its recession cone. Then

$$Q=P+K:=\{p+d:p\in P, d\in K\}.$$

## **Proof:**

⊇:

Any  $p \in P$  is inside Q and, thus, satisfies all linear constraints of Q, so any  $p + d \in P + K$  has

$$A^{T}(p+d) = A^{T}p + A^{T}d \le c + 0 = c.$$

 $\subseteq$ :

The proof is by induction on  $\{m - ra(y)\}$ .

True for  $\{m - ra(y) = 0\} \Leftrightarrow y$  is itself a vertex of Q and  $d = 0 \in rec(C)$ .

Suppose true if  $\{m - ra(y) < k\}$  for some k > 0 and consider  $y \in Q$  with ra(y) = m - k < m. Choose  $0 \neq d \in \mathbb{R}^m$  with  $A_{=}^T d = 0$  ( $A_{=}^T$  are all equality constraints for y) and consider  $y + \alpha d$ ,  $\alpha \in \mathbb{R}$ . Since Q is pointed there are three cases to consider.

(1)  $\alpha$  is bounded above and below, say by  $\underline{\alpha} < 0 \& \overline{\alpha} > 0$ . As in the previous theorem

$$y = \frac{\overline{\alpha}}{\overline{\alpha} - \underline{\alpha}} (y + \underline{\alpha}d) + \frac{-\underline{\alpha}}{\overline{\alpha} - \underline{\alpha}} (y + \overline{\alpha}d),$$

and  $(y + \overline{\alpha}d)$  has  $m - ra(y + \overline{\alpha}d) < k$ , so

$$\begin{array}{rclcrcl} (y+\overline{\alpha}d) & = & \overline{p} & + & \overline{d} & , & \overline{p} \in P & , & \overline{d} \in K, \\ \text{and similarly} & & & & \\ (y+\underline{\alpha}d) & = & p & + & \underline{d} & , & p \in P & , & \underline{d} \in K, \end{array}$$

so

$$y = \frac{\overline{\alpha}}{\overline{\alpha} - \underline{\alpha}} (\underline{p} + \underline{d}) + \frac{-\underline{\alpha}}{\overline{\alpha} - \underline{\alpha}} (\overline{p} + \overline{d})$$
$$= [\frac{\overline{\alpha}}{\overline{\alpha} - \alpha} \underline{p} + \frac{-\underline{\alpha}}{\overline{\alpha} - \alpha} \overline{p}] + \{ \dots \underline{d} + \dots \overline{d} \}.$$

The vector in brackets is a point of P and that in braces a point in K.

(2)  $\alpha$  is bounded below but not above. Then  $d \in K$  and  $y = [y + \underline{\alpha}d] + (-\underline{\alpha})d$ , with  $\underline{\alpha}$  defined as before. The vector in brackets lies in P + K as in the first part by the inductive hypothesis. Therefore

$$y = (\underline{p} + \underline{d}) + (-\underline{\alpha})d$$
  
=  $p + (\underline{d} + (-\underline{\alpha})d)$ 

lies in P + K.

(3)  $\alpha$  is bounded above but not below. Then we can simply switch d to -d and  $\overline{\alpha}$  to  $-\underline{\alpha}$ , and we get back to case(2).

This completes the proof.

**Theorem 4** (Fundamental theorem of LP). Consider the LP problem  $\max\{b^Ty:y\in Q\}$  with Q being a pointed polyhedron. Then

- 1. if there is a feasible solution, there is a vertex solution (basic feasible solution);
- 2. if there is a feasible solution and  $b^Ty$  is unbounded above on Q, then there is a ray or halfline:  $\{y + \alpha d : \alpha \geq 0\} \in Q$  on which  $b^Ty$  is unbounded above; and
- 3. if  $b^Ty$  is bounded above on Q, then the max is attained and attained at a vertex Q.

## **Proof:**

- (1): If  $Q \neq \emptyset$ ,  $P \neq \emptyset$ , so there exists a vertex.
- $(2)\&\ (3)$ :

Assume  $P \neq \emptyset \& P$  is a set of convex combinations of  $v_1, v_2, v_3, ..., v_k$ .

$$\begin{split} \sup\{b^Ty: y \in Q\} &= \sup\{b^Ty: y \in P + K\} \\ &= \sup\{b^Tp + b^Td: p \in P, d \in K\} \\ &= \sup\{b^Tp: p \in P\} + \sup\{b^Td: d \in K\}. \end{split}$$

If there is some  $\overline{d} \in K$  with  $b^T \overline{d} > 0$  then by considering  $\alpha \overline{d}$ ,  $\alpha \to +\infty$ , see that  $\sup\{b^T d : d \in K\} = +\infty$ . Then  $b^T y$  is unbounded above on Q and clearly unbounded above on  $\{y + \alpha \overline{d}, \alpha \geq 0\}$  for any  $y \in Q$ .

If there is no such  $\overline{d} \in K$ , then  $\sup\{b^Td: d \in K\} = 0$ , attained by d = 0. Then

$$\sup\{b^{T}y : y \in Q\} = \sup\{b^{T}p : p \in P\}$$

$$= \sup\{\sum_{i=1}^{k} \lambda_{i}(b^{T}v_{i}) : \sum_{i=1}^{k} \lambda_{i} = 1, \text{ all } \lambda_{i} \geq 0\}$$

$$= \max_{1 \leq i \leq k} b^{T}v_{i}$$

In this case  $\sup\{b^Ty:y\in Q\}$  is attained by  $y=v_i$  where i attains the maximum.