Brownian network models of ramp metering

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Conference on Stochastic Processing Networks in Honor of J. Michael Harrison

Outline

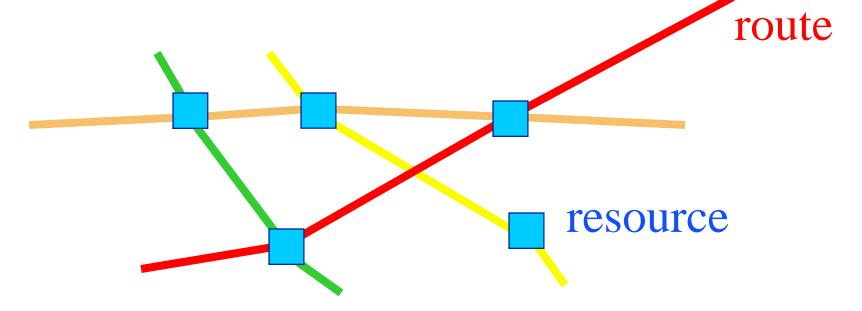
• Rate control in communication networks (relatively well understood)

• Philosophy: optimization vs fairness

• Ramp metering (very preliminary)

Network structure

- set of resources J
- *R* set of routes
- $A_{jr} = 1$ if resource *j* is on route *r* $A_{jr} = 0$ otherwise



Rate allocation

 n_r - number of flows on route r x_r - rate of each flow on route r

> Given the vector $n = (n_r, r \in R)$ how are the rates $x = (x_r, r \in R)$ chosen ?

Optimization formulation

Suppose x = x(n) is chosen to

maximize
$$\sum_{r} w_{r} n_{r} \frac{x_{r}^{1-\alpha}}{1-\alpha}$$

subject to
$$\sum_{r} A_{jr} n_{r} x_{r} \leq C_{j} \quad j \in J$$
$$x_{r} \geq 0 \quad r \in R$$

(weighted α -fair allocations, Mo and Walrand 2000)

$$0 < \alpha < \infty$$
 (replace $\frac{x_r^{1-\alpha}}{1-\alpha}$ by $\log(x_r)$ if $\alpha = 1$)

$$\begin{aligned} & Solution \\ & x_r = \left(\frac{w_r}{\sum_j A_{jr} p_j(n)}\right)^{1/\alpha} \quad r \in R \\ \end{aligned}$$
where
$$\begin{aligned} & \sum_r A_{jr} n_r x_r \leq C_j \quad j \in J; \quad x_r \geq 0 \quad r \in R \\ & p_j(n) \geq 0 \quad j \in J \\ & p_j(n) \left(C_j - \sum_r A_{jr} n_r x_r\right) \geq 0 \quad j \in J \end{aligned}$$
KKT conditions

 $p_j(n)$ - *shadow price* (Lagrange multiplier) for the resource *j* capacity constraint

Examples of α -fair allocations

maximize
$$\sum_{r} w_{r} n_{r} \frac{x_{r}^{1-\alpha}}{1-\alpha}$$

subject to
$$\sum_{r} A_{jr} n_{r} x_{r} \leq C_{j} \quad j \in J$$
$$x_{r} \geq 0 \quad r \in R$$

$$x_r = \left(\frac{W_r}{\sum_j A_{jr} p_j(n)}\right)^{1/\alpha} r \in R$$

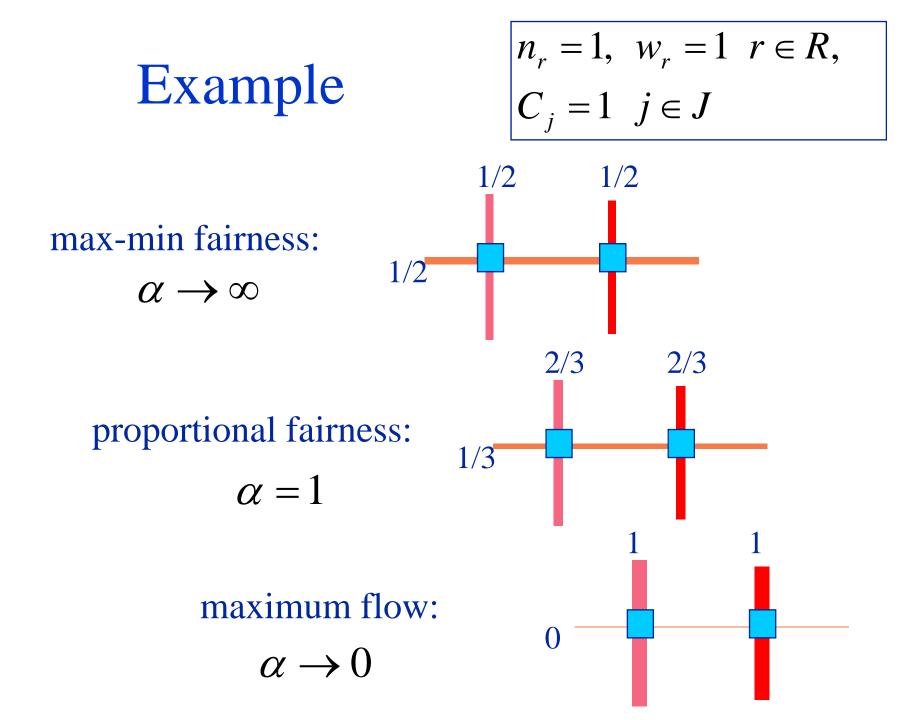
$$\alpha \to 0 \quad (w = 1)$$

$$\alpha \to 1 \quad (w = 1)$$

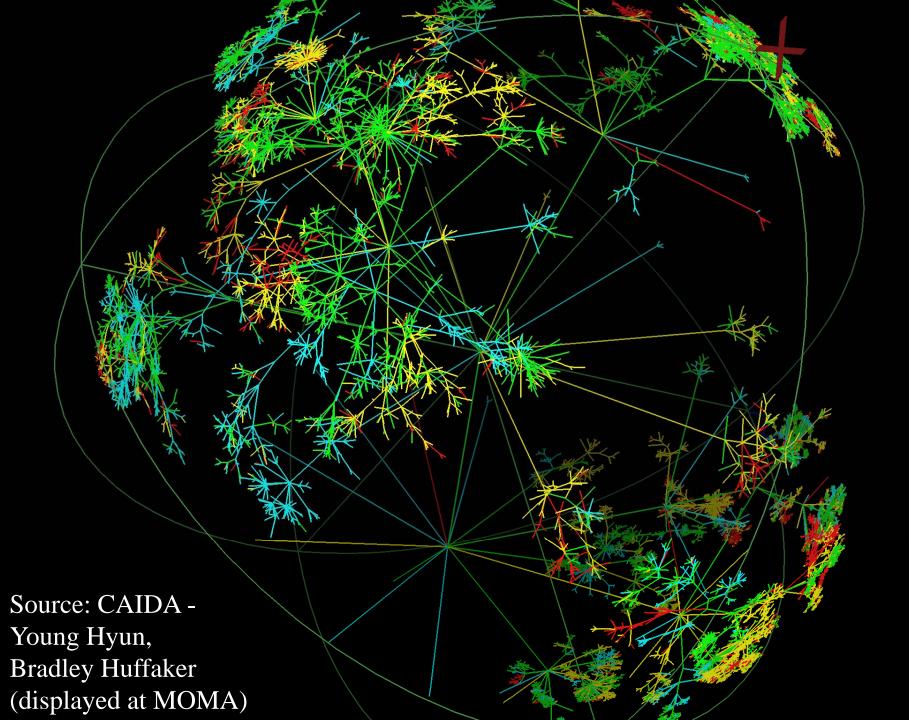
$$\alpha = 2 \quad (w_r = 1/T_r^2)$$

$$\alpha \to \infty \quad (w = 1)$$

- maximum flow
- proportionally fair
- TCP fair
- max-min fair



Source: CAIDA, Young Hyun



Flow level model

Define a Markov process $n(t) = (n_r(t), r \in R)$ with transition rates

 $n_r \rightarrow n_r + 1$ at rate v_r $r \in R$ $n_r \rightarrow n_r - 1$ at rate $n_r x_r(n) \mu_r$ $r \in R$

- Poisson arrivals, exponentially distributed file sizes

Roberts and Massoulié 1998

Stability

Let
$$\rho_r = \frac{\nu_r}{\mu_r} \quad r \in R$$

If
$$\sum_{r} A_{jr} \rho_{r} < C_{j} \quad j \in J$$

then the Markov chain $n(t) = (n_r(t), r \in R)$ is positive recurrent

De Veciana, Lee & Konstantopoulos 1999; Bonald & Massoulié 2001

Heavy traffic: balanced fluid model

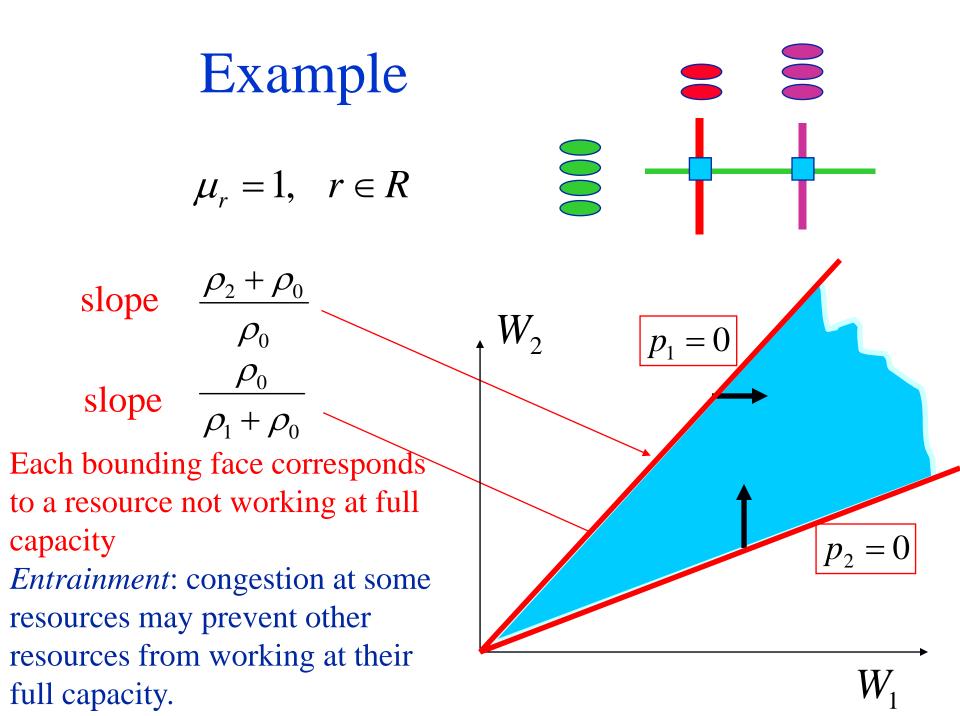
The following are equivalent:

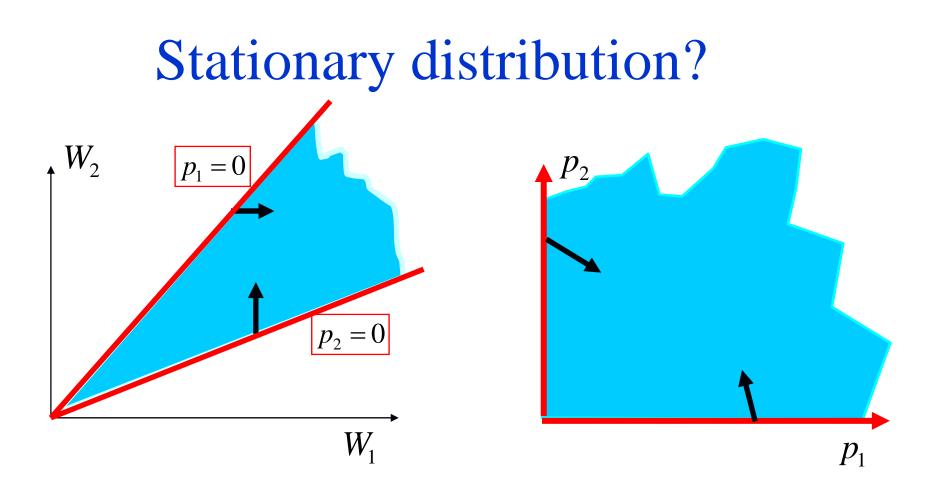
$$\alpha = 1$$

- *n* is an invariant state
- there exists a non-negative vector *p* with

$$n_r = \frac{\nu_r}{\mu_r} \sum_j A_{jr} p_j \quad r \in R$$

Thus the set of invariant states forms a J dimensional subspace, parameterized by p.

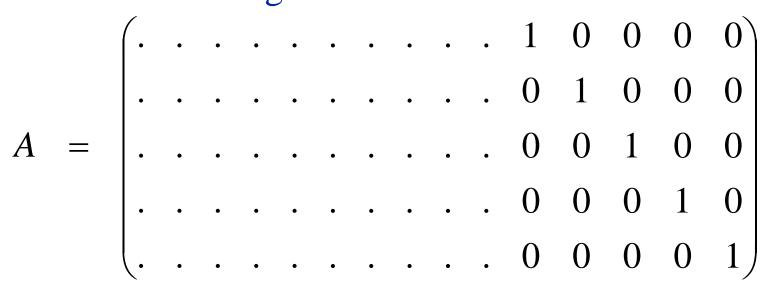




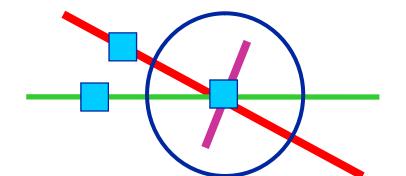
Williams (1987) determined sufficient conditions, in terms of the reflection angles and covariance matrix, for a SRBM in a polyhedral domain to have a product form invariant distribution – a skew symmetry condition

Local traffic condition

Assume the matrix A contains the columns of the unit matrix amongst its columns:



i.e. each resource has some local traffic -



Product form under proportional fairness

Kang, K, Lee and Williams 2009

$$\alpha = 1, w_r = 1, r \in R$$

Under the stationary distribution for the reflected Brownian motion, the (scaled) components of pare independent and exponentially distributed. The corresponding approximation for n is

$$n_r \approx \rho_r \sum_j A_{jr} p_j \quad r \in R$$

where

$$p_j \sim \operatorname{Exp}(C_j - \sum_r A_{jr}\rho_r) \quad j \in J$$

Dual random variables are independent and exponential

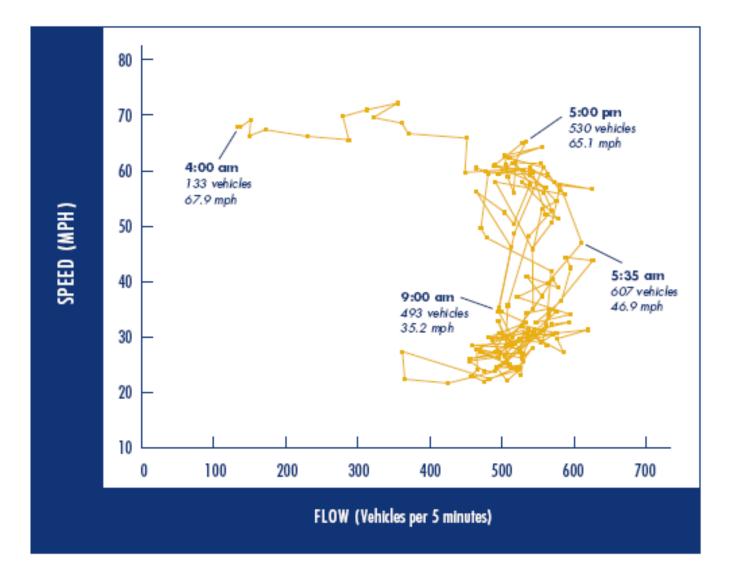
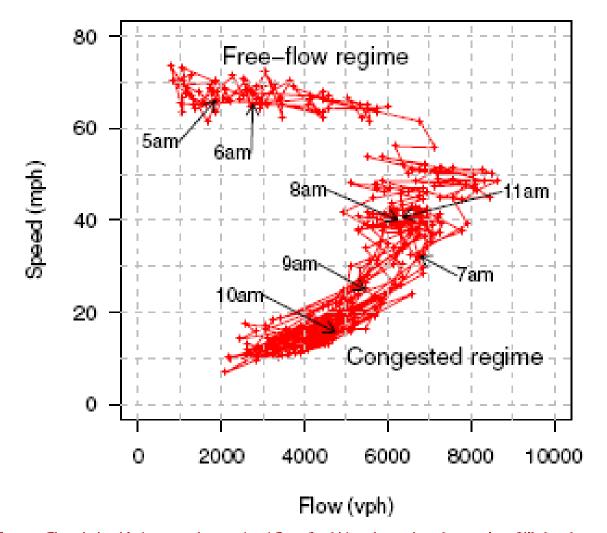


FIGURE 1

Speed vs. flow on I-10 westbound in 5 minute intervals from 4:00 am to 6:00 pm

What we've learned about highway congestion *P. Varaiya*, Access 27, Fall 2005, 2-9.

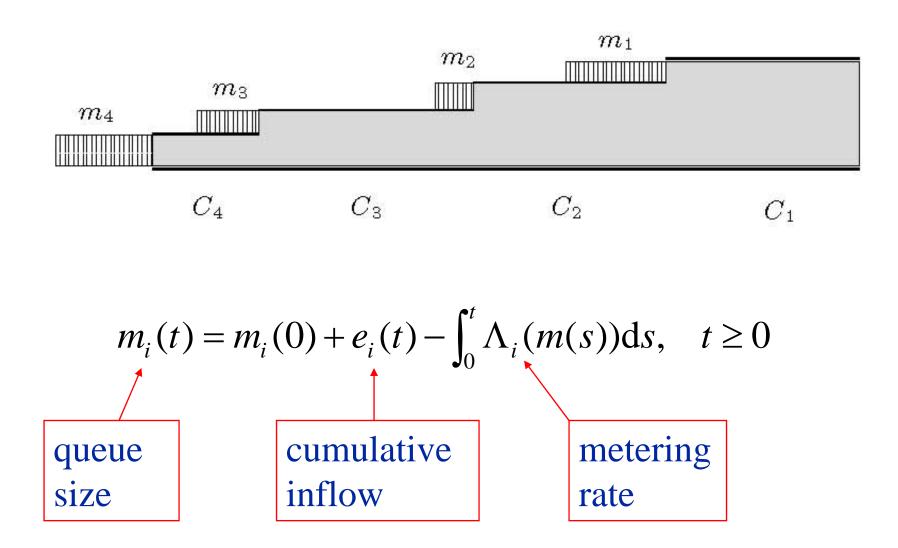


Data, modelling and inference in road traffic networks *R.J. Gibbens and Y. Saatci* Phil. Trans. R. Soc. A366

(2008), 1907-1919.

Figure 2. The relationship between the speed and flow of vehicles observed on the moming of Wednesday, 14 July 2004 using the M25 midway between junctions 11 and 12 in the clockwise direction. In the free-flow regime, flow rapidly increases with only a modest decline in speeds. Above a critical occupancy of vehicles there is a marked drop in speed with little, if any, improvement in flow which is then followed by a severe collapse into a congested regime where both flow and speed are highly variable and attain very low levels. Finally, the situation recovers with a return to higher flows and an improvement in speeds

A linear network



Metering policy

Suppose the metering rates can be chosen to be any vector $\Lambda = \Lambda(m)$ satisfying

$$\sum_{i} A_{ji} \Lambda_{i} \leq C_{j}, \quad j \in J$$
$$\Lambda_{i} \geq 0, \quad i \in I$$
$$\Lambda_{i} = 0, \quad m_{i} = 0$$

and such that

$$m_i(t) = m_i(0) + e_i(t) - \int_0^t \Lambda_i(m(s)) ds \ge 0, \quad t \ge 0$$

Optimal policy?

For each of $i = I, I-1, \dots, I$ in turn choose

$$\int_0^t \Lambda_i(m(s)) \mathrm{d}s \ge 0$$

to be maximal, subject to the constraints. This policy minimizes

$$\sum_{i} m_{i}(t)$$

for all times *t*

Proportionally fair metering Suppose $\Lambda(m) = (\Lambda_i(m), i \in I)$ is chosen to maximize $\sum m_i \log \Lambda_i$ subject to $\sum_{i} A_{ji} \Lambda_{i} \leq C_{j}, \quad j \in J$ $\Lambda_i \ge 0, \quad i \in I$ $\Lambda_i = 0, \quad m_i = 0$

Proportionally fair metering

$$\Lambda_i(m) = \frac{m_i}{\sum_j p_j A_{ji}}, \quad i \in I$$

where

$$\begin{split} &\Lambda_i \geq 0, \quad i \in I \\ &\sum_i A_{ji} \Lambda_i \leq C_j, \quad j \in J \\ &p_j \geq 0, \quad j \in J \\ &p_j \bigg(C_j - \sum_i A_{ji} \Lambda_i \bigg) \geq 0, \quad j \in J \end{split}$$

KKT conditions

 p_j - shadow price (Lagrange multiplier) for the resource j capacity constraint

Suppose that $(e_i(t), t \ge 0)$ is a Brownian motion, starting from the origin, with drift ρ_i and variance $\rho_i \sigma^2$. Let

$$X_{j}(t) = \sum_{i} A_{ji} e_{i}(t) - C_{j} t$$

Then $X(t) = (X_j(t), j \in J)$ is a *J*-dimensional Brownian motion starting from the origin

with drift $-\theta = A\rho - C$

and variance $\Gamma = \sigma^2 A[\rho] A'$

Let $\mathbf{W} = A[\rho]A'\mathbf{R}_+^J$

and
$$\mathbf{W}^{j} = \{ A[\rho] A': q \in \mathbf{R}_{+}^{J}, q_{j} = 0 \}.$$

Define W(t) by the following relationships :

- (i) W(t) = X(t) + U(t) for all $t \ge 0$
- (*ii*) W has continuous paths, $W(t) \in \mathbf{W}$
- (*iii*) for each $j \in J$, U_i is a one dimensional process such that
- (a) U_i is continuous and non decreasing, with $U_i(0) = 0$,

(b)
$$U_{j}(t) = \int_{0}^{t} I\{W(s) \in \mathbf{W}^{j}\} dU_{j}(s) \text{ for all } t \ge 0.$$

If $\theta_j > 0$, $j \in J$, then there is a unique stationary distribution *W* under which the components of

$$Q = (A[\rho]A')^{-1}W$$

are independent, and Q_j is exponentially distributed with parameter

$$\frac{\sigma^2}{2}\theta_j, \quad j \in J$$

and queue sizes are given by

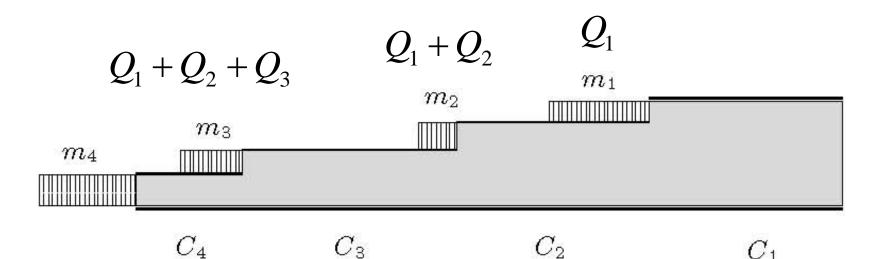
$$M = [\rho] A' Q$$

Delays

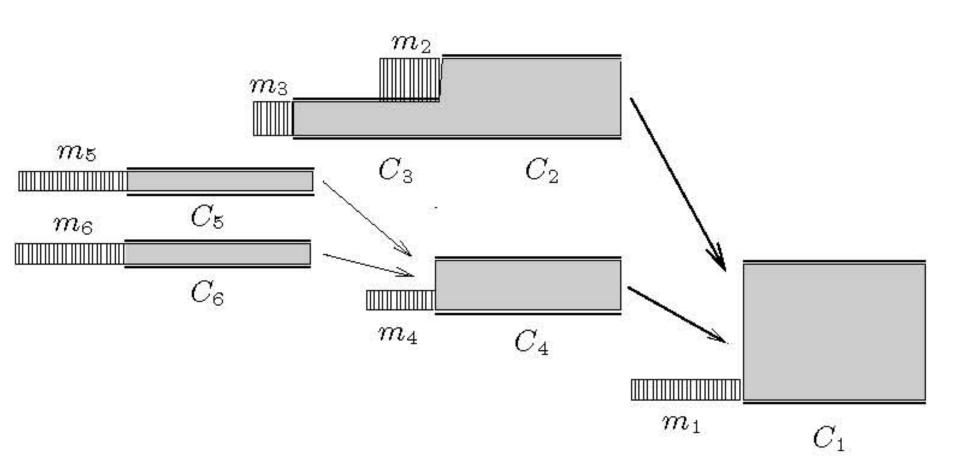
Let
$$D_i(m) = \frac{m_i}{\Lambda_i(m)}$$

- the time it would take to process the work in queue i at the current metered rate. Then

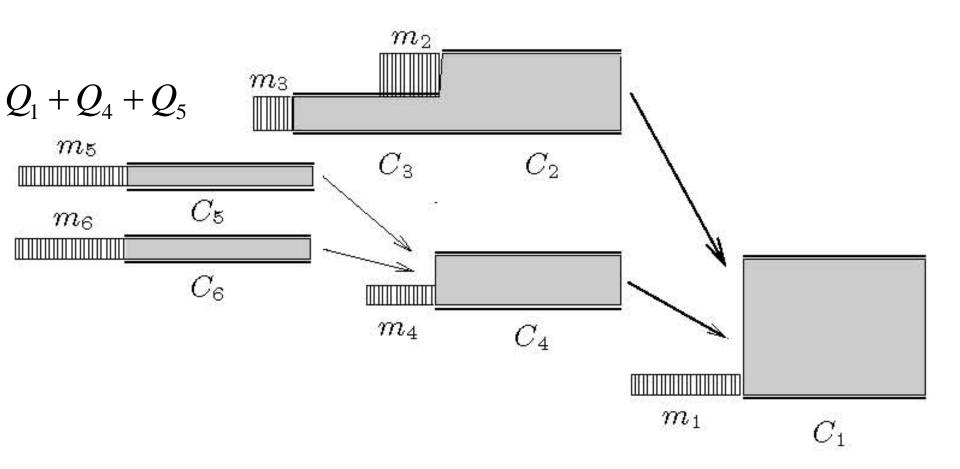
$$D_i(M) = \sum_j Q_j A_{ji}$$

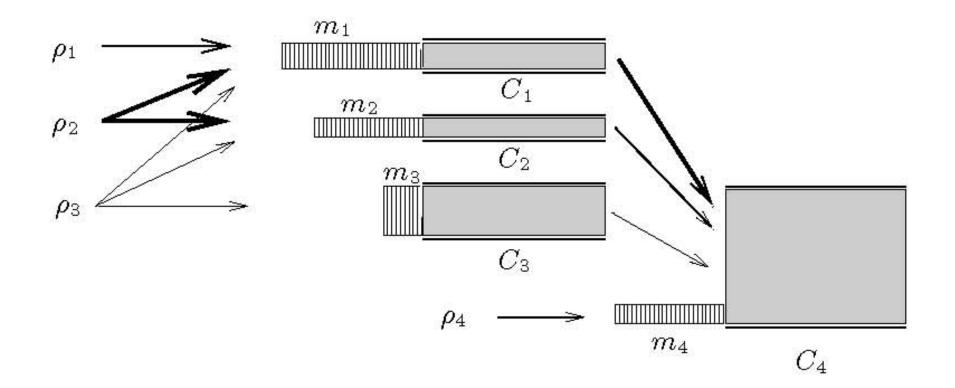


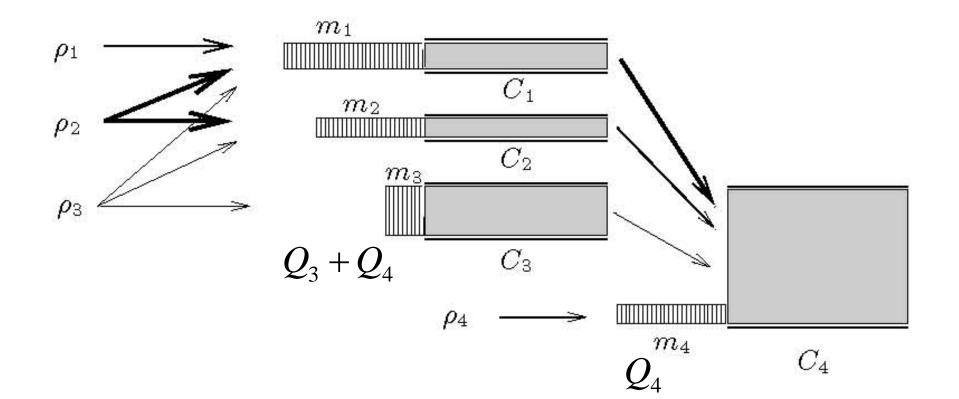
A tree network

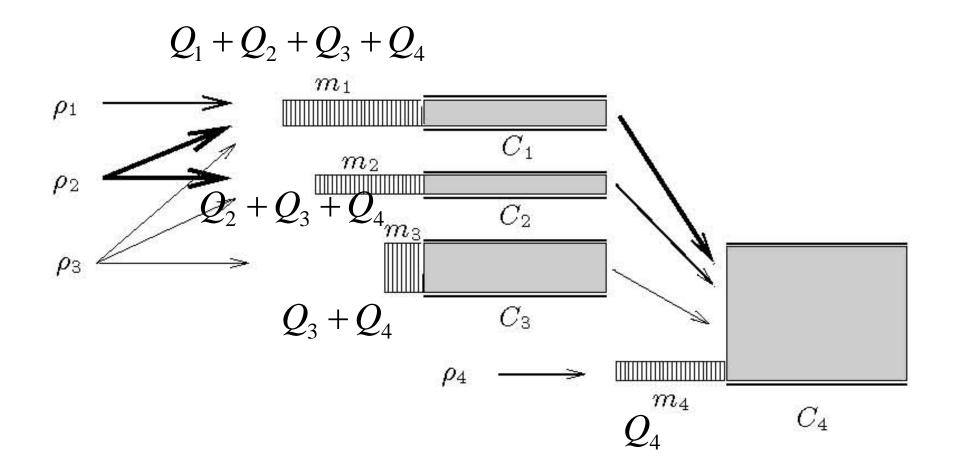


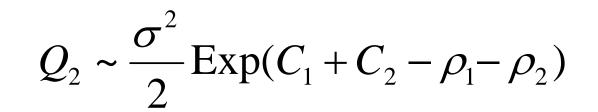
A tree network



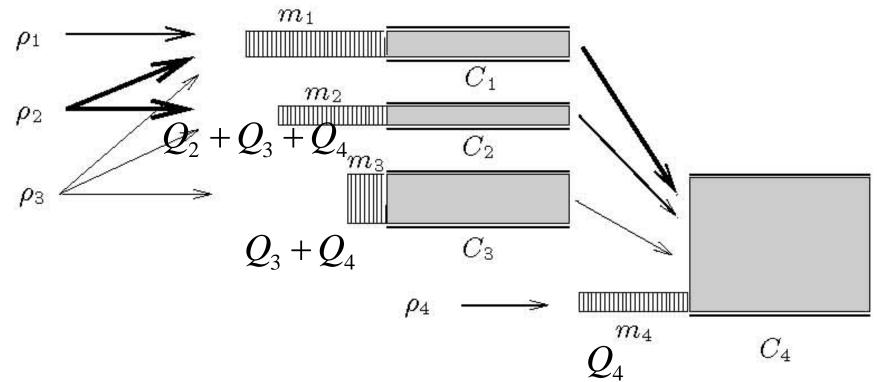








$$Q_1 + Q_2 + Q_3 + Q_4$$



- As Mike has cogently argued, for many applications it may be *easier* to describe the workload arrival process in terms of the mean and variance of a Brownian motion.
- If relevant time periods long enough, negative increments less likely.
- The Brownian model exposes structure in a way that more detailed models (e.g. MDP models) do not.